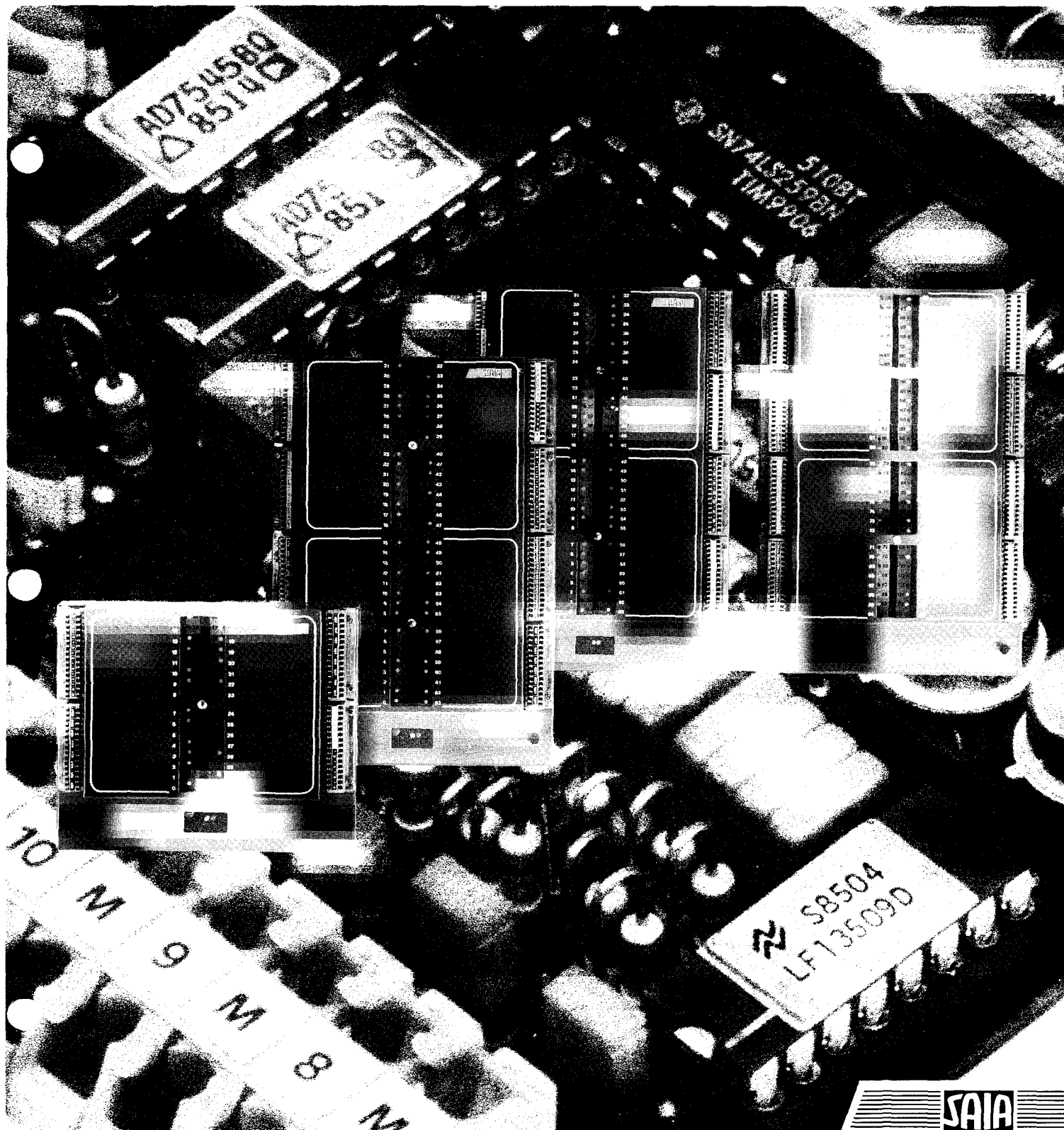


# SAIA® PLC

Programmable controllers

## Manual of the series PCA 1 Hardware



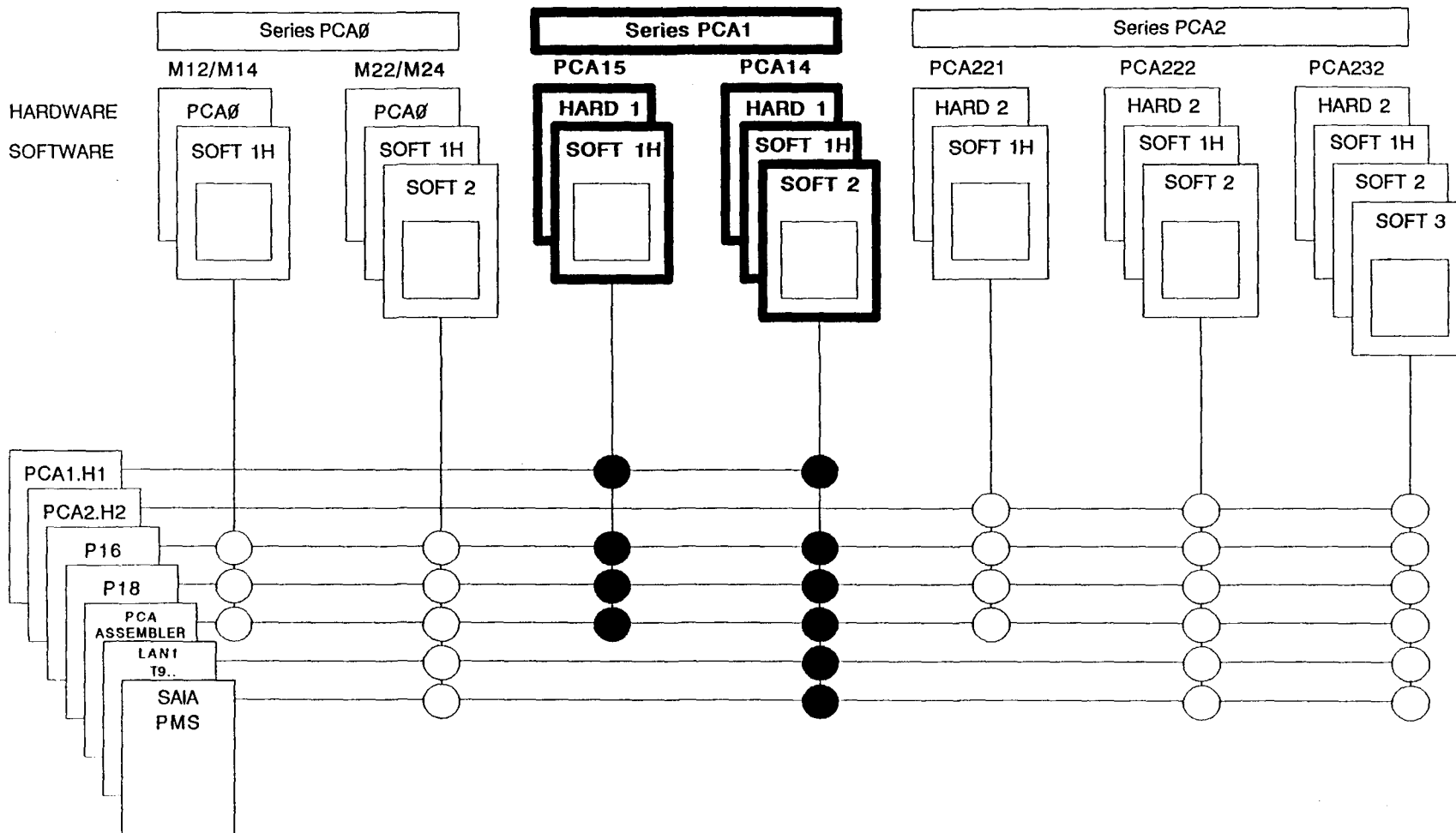
## **HARDWARE - PCA1**


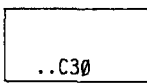
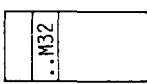

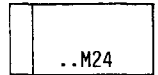




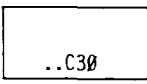
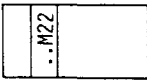

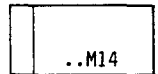




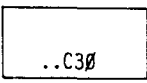
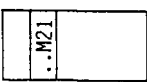
### **GENERAL**

#### **PART A BASIC MODULES**

#### **PART B INPUT/OUTPUT MODULES as well as ADDITIONAL and DISPLAY MODULES**

#### **PART C OPERATING MODES**



	Series PCA0	Series PCA1 	Series PCA2
<b>Soft level 3</b>  Soft level 2 + 32 word instructions for - arithmetic ± 9 digits - data transfer - word register			PCA232  User memory 8K program steps + 8K text characters + 8K byte data  256 or 512 I/O
<b>Soft level 2</b>  Soft level 1H + Serial interface + Date-time + Data register + Parameter instructions (soft interrupt, FIFO, PID)	Standard versions and OEM  PCA0.M22                      PCA0.M24   max. 32 I/O                      max. 64 I/O  User memory max. 4K program steps max. 4K text characters/data	PCA14  PCA141    PCA147    PCA147 + ..C45     32(56)    64(112)    128(224) I/O  User memory max. 8K program steps max. 8K text characters/data	PCA222   256 or 512 I/O  User memory max. 8K program steps max. 8K text characters/data
<b>Soft level 1H</b>  Instruction set with 32 basic instructions for - timers and counters - parallel programs and subroutines - indexing, etc.  20 additional instructions for - arithmetic - data transfer - check-sum	Standard versions  PCA0.M12                      PCA0.M14   24/32 I/O                      48/64 I/O  User memory max. 4K program steps	PCA15  PCA151    PCA156    PCA157 + ..C45     32(56)    64(112)    128(224) I/O  User memory max. 4K program steps	PCA221   256 or 512 I/O  User memory max. 8K program steps

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Selling price: sFr 60.-

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**PART A      BASIC MODULES**

**Chapter A 1    System structure**

**Chapter A 2    Technical data of system series PCA15**

**Chapter A 3    Technical data of system series PCA14**

**Chapter A 4    Extension housing ..C45**

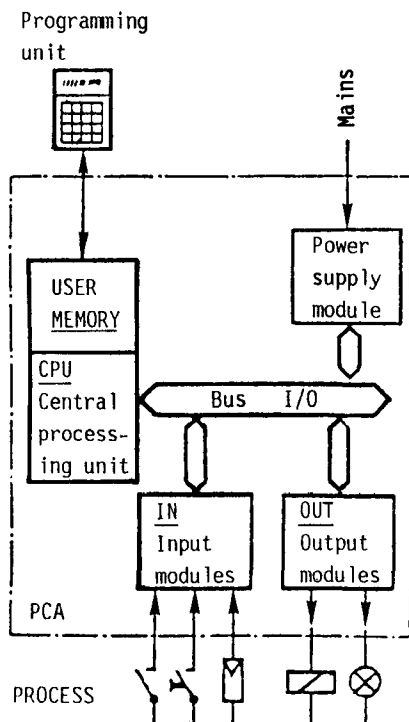
**Chapter A 5    Voltage supply, watchdog, reset, dimensions**



## PART A Hardware

### A 1 System structure

#### A 1.1 Block circuit diagram of the SAIA®PLC



4 or 8 plug-in locations for I/O modules which may be arranged as desired

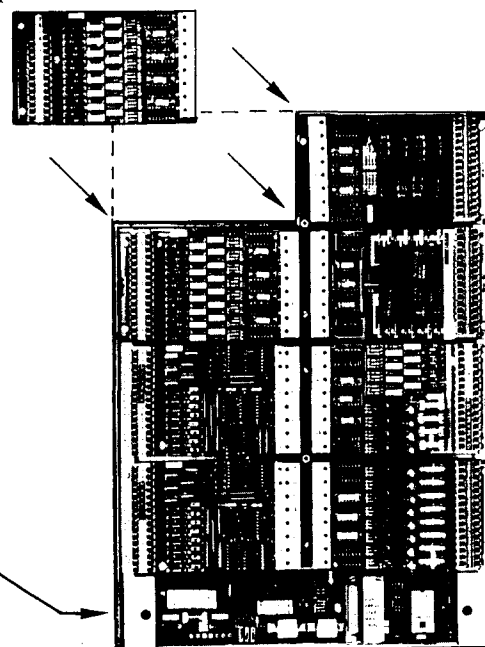
The SAIA®PLC is subdivided into the following hardware modules:

- Central processing unit CPU
- User MEMORY
- SUPPLY module
- Serial communication interface
- Input modules (digital or analog)
- Output modules (digital or analog)

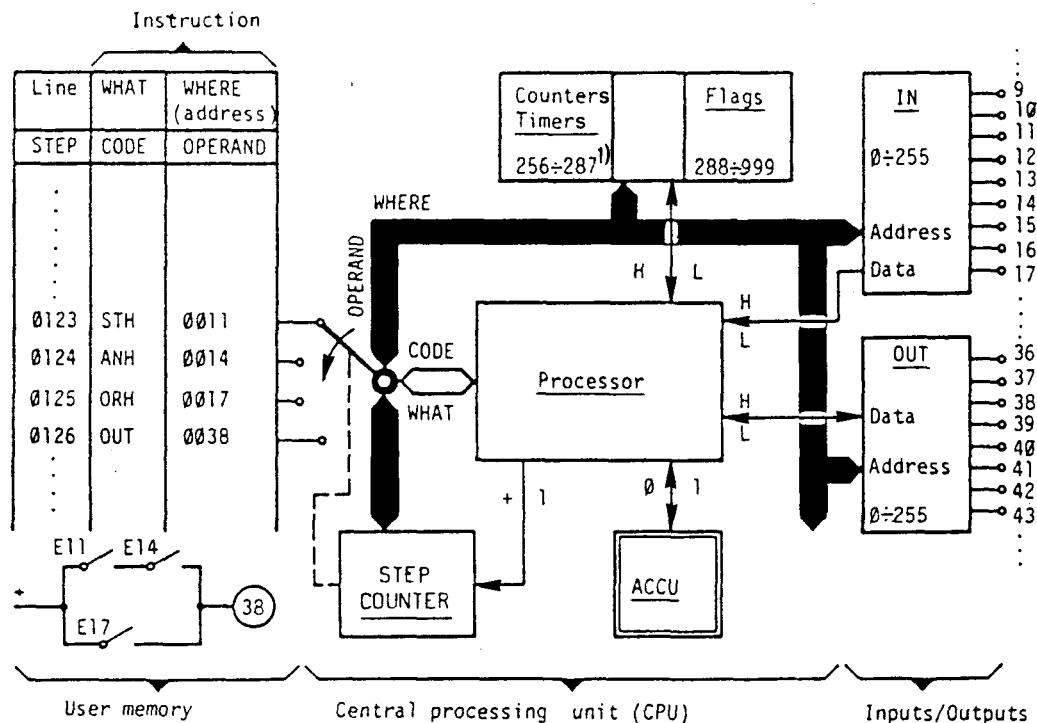
All listed modules can be plugged onto the common bus.

Program input takes place via the programming unit.

Basic module (without I/O) comprising processor section (CPU), supply section and rack. Some basic modules allow the connection to an extension housing.



## A 1.2 Functional description of the SAIA®PLC



The instructions for linking the input signals and formation of the actual output states are entered by the user in the user memory, arranged in "words". Each word having a length of 16 bits comprises a complete instruction, subdivided into CODE and OPERAND. The CODE states "what" is to be executed, whilst the OPERAND states "where" the element in question is located.

The instructions are read and interpreted consecutively by the CPU. After an instruction has been processed, the step counter reading is incremented by 1 and the next instruction in the user memory is read. Additionally, the logical states of the elements (H or L) are interrogated by the CPU via the data bus. Each linkage result is stored in the accumulator (ACCU). With an output instruction, the result of the operation for example is transferred to an output.

The CPU contains all units required for auxiliary functions, such as e.g. timer and counter registers, flag memories, index registers, etc. The return addresses for subroutines are stored in additional memories.

1) The registers 288 to 479 may be used as counters with the PCA14 from version V6.034 onwards.

## A 2 Technical data of system series PCA15

CPU	μP 8085.2, system program V6.3.. <sup>1)</sup>
Cycle time	70μs per program line (average of logic instructions)
Instruction set	Software level 1H 32 basic instructions + 20 additional instructions for transfer functions, arithmetics (+, -, x, ÷) and check sum
Parallel programs and subroutines	Up to 16 parallel programs, any number of subroutines nested down through 3 levels
Index register	1 per parallel program (max. 16)
User memory	1K, 2K or 4K program lines on EPROM, RAM or buffered RAM chip
Inputs and outputs	32, 64 or 128 input/output addresses corresponding to the housing size  Up to 56, 112 or 224 inputs/outputs corresponding to the housing size, with compact module PCA1.B90 or B80
Flag memory	712 flags, 235 of which are non-volatile 477 are volatile or non-volatile <sup>2)</sup>
Timer and counter or arithmetic registers	32 timer or counter registers + 32 counter registers, volatile <sup>2)</sup>
Counting or computing capacity	65'535 ( $2^{16}-1$ ) per counter register, extendible as desired by means of cascading
Time range	0.1...6553s (0.01...655s) <sup>2)</sup>

<sup>1)</sup> When switching on the PLC, the CPU system version is displayed on the programming unit ..P10 or ..P05 for one second.

<sup>2)</sup> Please refer to PCA15, page 8A for modification possibilities

## A 2.1 Versions of system series PCA15

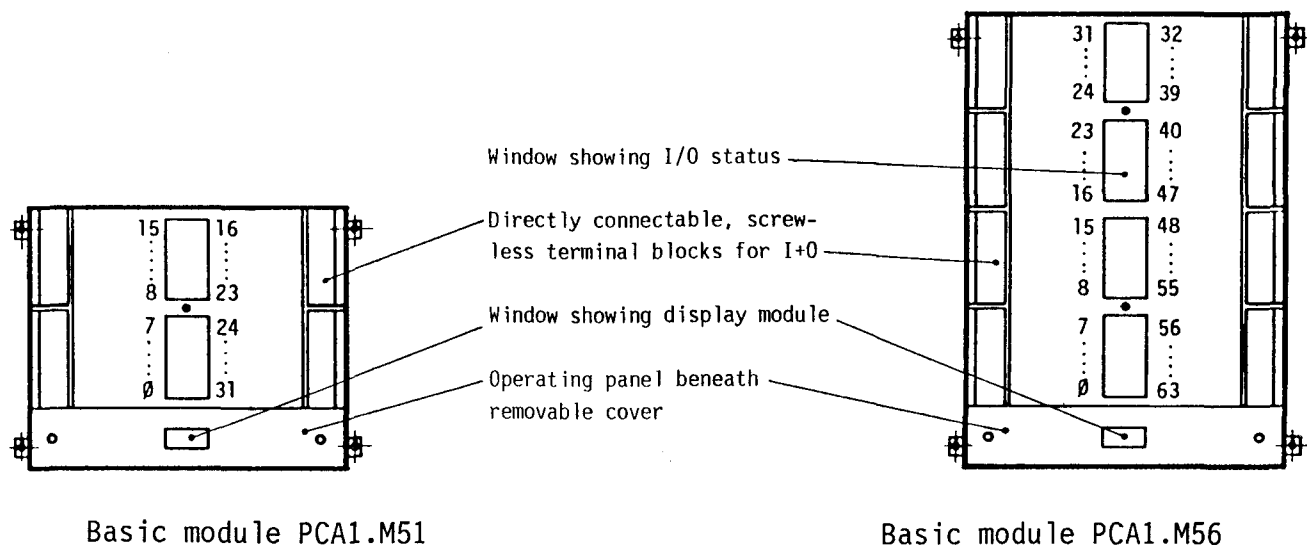
3 versions are available, corresponding to the required number of input and output addresses.

### Type of system PCA151

32 I+O addresses  
56 I+O with compact module PCA1.B9Ø

### Type of system PCA156

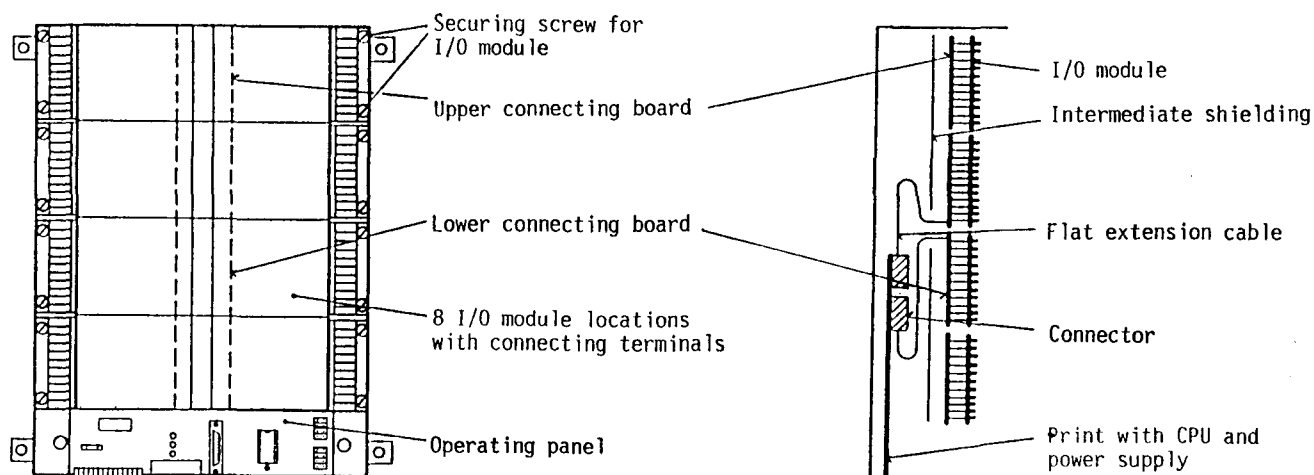
64 I+O addresses  
112 I+O with compact module PCA1.B9Ø



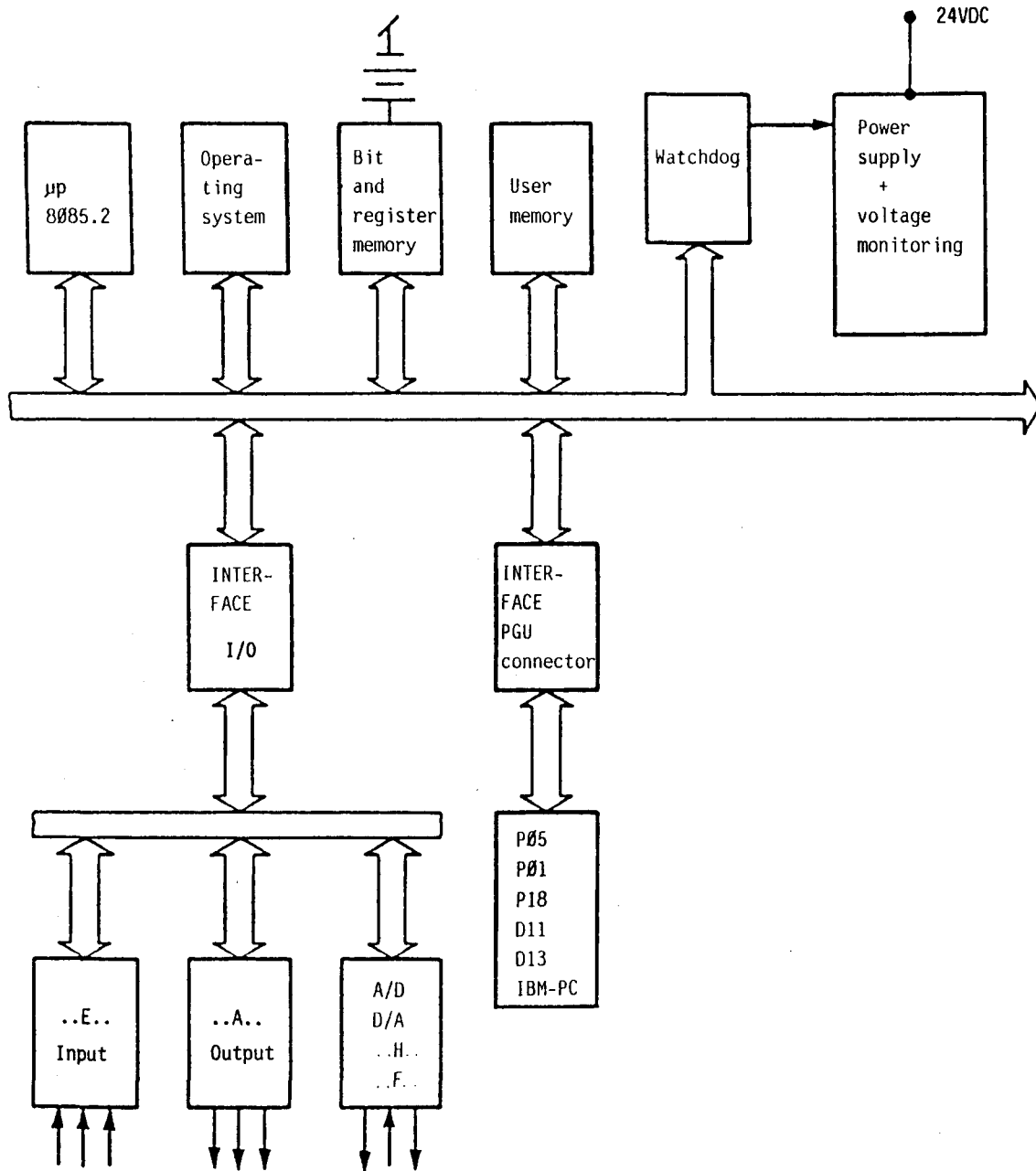
### PCA1.M51 and PCA1.M56 Basic modules

In addition to the processor (CPU), the basic modules of the system series PCA15 also include the internal power supply and the housing.

### Presentation (PCA1.M56)



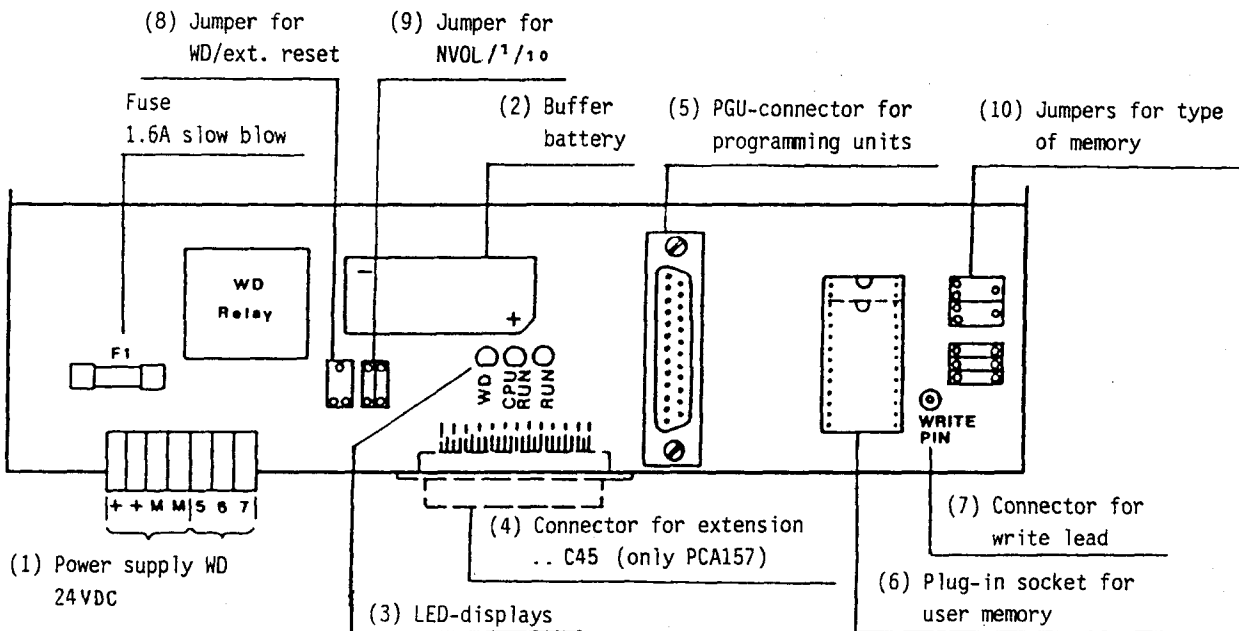
## A 2.2 Block circuit diagram PCA15



## A 2.3 Basic modules

### A 2.3.1 Operating panel of the basic modules PCA1.M51/M56/M57

All operating elements for the PCA15 are clearly arranged on the operating panel which can be covered.



- ① The terminal board is plugged onto the circuit board. Wires with cross-sections up to 1.5 mm<sup>2</sup> are accepted by the screw terminals.
- ② The buffered battery supplies the non-volatile flags, counters/timers and, if used, the 6116 or 6264 RAM chip user memory. Data are retained approx. 2 months with the PLC switched off. The pluggable NiCd cell lasts approx. 5 years (order no. for spare batteries: no. 4'507'1360'0).
- ③ The LED "CPU RUN" (yellow) blinks every 2s during normal operation. When the time base is set to 0.01s, the blinking rate is 0.2s. If the LED stays on or off, there is either no power available, the PLC is in RESET mode, the CPU has a malfunction or a trap has been produced in the software sequence.

The LED "RUN" (green) is illuminated when the CPU is in the operating mode RUN and the user program is executed normally.

The watchdog monitoring indicator (green) is illuminated when the watchdog relay is excited.

- ④ The 25-pole connector for the extension cable (only on the PCA157) allows connection to housing ..C45 which means that the number of I+O addresses is increased from 64 to 128 I+O or 112 to 224 I+O respectively.
- ⑤ The 25-pole PGU connector is used to connect the programming unit ..P05 or any other programming unit by using the programming interface PCA0.P01. Also the display modules PCA1.D11 and ..D13 can be connected here.

- ⑥ The 28-pole plug-in socket accomodates the user memory. When inserting, please make sure that the index groove is at the top. If memory chips with a 24-pole socket are used (e.g. 6116, 2716, 2732A), please insert in such a way that they are flush with the lower edge of the socket.

The following memory chips can be used:

- unbuffered RAM chips, on plug-in socket  
 No. 4'502'4512'0 (type 6116) for 1K program lines (24-pole)  
 No. 4'502'4718'0 (type 6264 or 8464) for 4K program lines (28-pole)

Comment: The RAM 6116 and 6264 or 8464 allow writing, erasing and modification of a program. On voltage failure, the memory contents are stored via the buffered battery for approx. 2 months. The program, however, is not transportable, because the data stored is lost, if the RAM chip is removed.

- buffered RAM chips, on plug-in socket  
 PCA1.R92 for 2K program lines (24-pole, with write lead) <sup>1)</sup>  
 PCA1.R95 for 4K program lines (28-pole) } see page 81B  
 PCA1.R96 for 4K program lines (28-pole)

In contrast to the unbuffered RAM chip, the program in this memory is transportable, since it is protected by an integrated circuit and a lithium battery which lasts approx. 8 years (..R96 approx. 6 years). These chips are therefore particularly suitable for starting the controller.

- EPROM chips, on plug-in socket  
 No. 4'502'4373'0 (type 2716) for 1K program lines (24-pole)  
 No. 4'502'4644'0 (type 2732A) for 2K program lines (24-pole)  
 No. 4'502'4719'0 (type 2764) for 4K program lines (28-pole)

According to the prior art, reliable operation of user programs over a period of several years is only ensured, if EPROM memories are used. The manufacturers chosen by us guarantee program safety for at least 10 years.

It is recommended to protect the window of the EPROM by means of a sticker to prevent the memory from being accidentally subjected to UV-radiation.

- ⑦ Connector for the write lead for the types PCA1.R91/R92/R94 (..R91 and ..R94 are no more available).

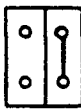
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<sup>1)</sup> Attention: Neither the write lead nor the connector WR must be touched or get into contact with the frame, since otherwise changes in contents may occur.

### Function of the preselection jumpers



watchdog  
ext. reset



NVOL  
1/10

- ⑧ Watchdog/external reset (factory setting: jumper in position watchdog)  
According to the block circuit diagram in chapter "Power supply", terminal 7 of the terminal board can be preselected either for the break contact of the WD-relay or as a fast reset input (see chapter "Fast external RESET circuit").

- ⑨ NVOL (factory setting: not inserted)  
If the jumper is inserted, all flags, timer and counter registers are non-volatile (retentive).

1/10 (factory setting: jumper inserted)

If the jumper is inserted, the time-base is 1/10s. If the jumper is not inserted, the time-base is to 1/100s.

- ⑩ Preselection for the user memory  
Corresponding to the type of memory and storage capacity the jumpers must be inserted differently (see the following table).

Attention: Do not use any other combinations, as these can cause damage to the CPU.

		RAM		buffered RAM				EPROM		
R95 EPROM	3)	6116	6264 8464	R91 <sup>1)</sup>	R92	R94 <sup>1)</sup>	R95 R96	2716	2732 A	2764
RAM										
2764										
8464 R95										
3)										
6116										
2716										
8464 2732/64										

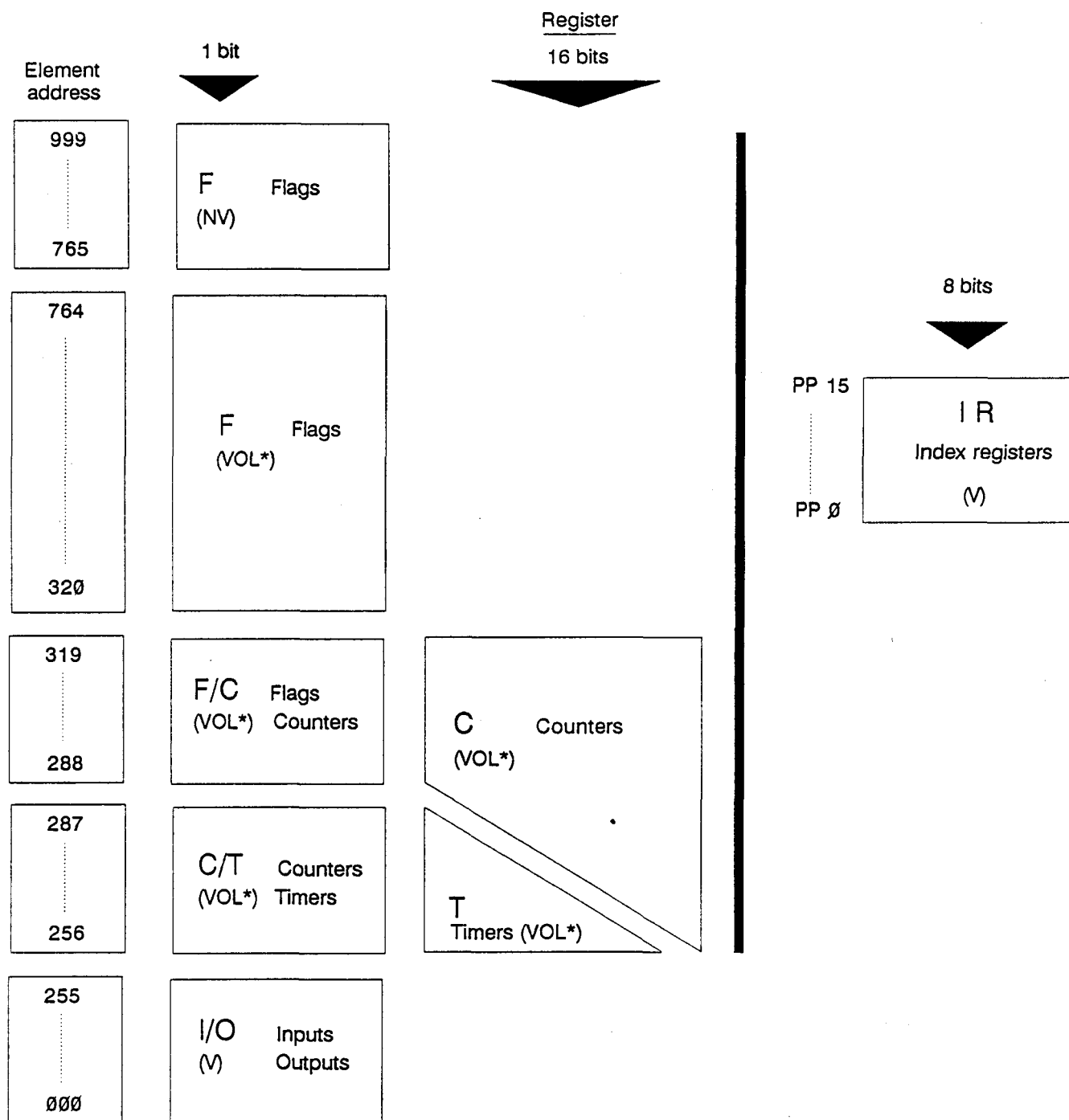
<sup>1)</sup> memory chips which are no more available

<sup>2)</sup> position "write disable"

<sup>3)</sup> factory setting for ..R95/..R96

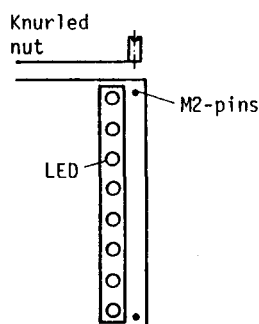
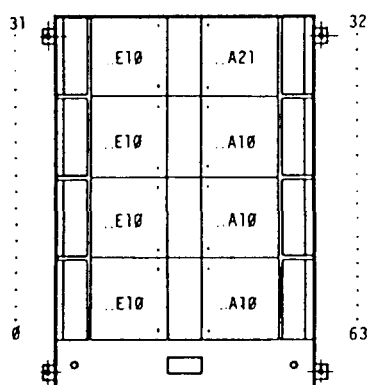


## 2.4 Register organization

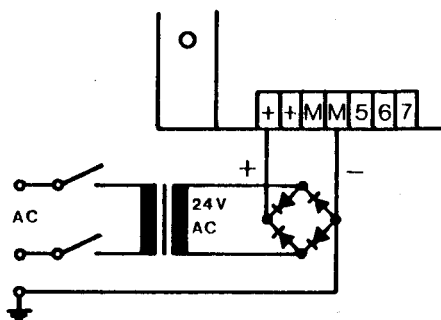


## A 2.5 Brief instruction for operating a PCA15

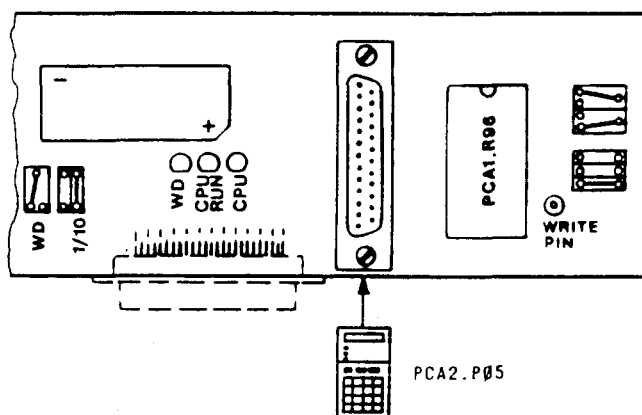
### a) Installation of I/O modules



### b) Power supply



### c) Connecting the user memory ..R96 and the programming unit ..P05



In order to try out the programming examples, it is recommended that addresses 0...31 of a PCA156 should be equipped with ..E10 I-modules, while O-modules should use the addresses 32...63.

1. Undo fastening screw to remove the cover and lift.
2. Center I/O modules above the two M2-pins and carefully press them into the blade connectors.
3. Tighten M2-knurled nuts and cheese head screws with tooth washers on the terminal side.
4. Provide the LEDs with the corresponding address labels.
5. Take a transformer (for "playing" 30VA are sufficient) with a secondary voltage of 24VAC and connect the terminals + and M of the PLC via the bridge rectifier.
6. A switch has the advantage that all resettable elements and the STEP-counter can easily be reset to their defined starting positions by switching off the PLC.
7. All jumpers must be positioned as evident from the figure (factory setting), so that the PCA1.R96 buffered RAM chip can be used.
8. Insert the buffered RAM chip ..R96 as shown with the index groove at the top.
9. Connect the ..P05 programming unit at the 25-pole PGU-connector.

d) Example program "Blinker"

10. Switch on the power supply of the PLC. The yellow "CPU RUN" of the 3 LEDs on the operating panel blinks, 1s on, 1s off, while the green LED does not light up.
11. Actuate the mode selecting key **P** (PROG) at the programming unit for approx. 1/2s, until the LED "PROG" lights up.
12. Type in the following "Blinker" program:

	STEP	CODE	OPERAND	Programm in mnemocode
A, E	(0000) <sup>1)</sup>	(00)	(0000)	
E	(0001)	02	256	STL 256
E	(0002)	14	256	STR 256
E	(0003)	00	5	COO 0.5s
E	(0004)	13	32	COO 32
E	(0005)	20	1	JMP 1
E	(0006)	(00)	(0000)	

<sup>1)</sup> The values in brackets need not be keyed in, but will be displayed.

13. Actuate the mode selecting key **R** (RUN) for approx. 1/2s.
- > Red LED "RUN" on ..P05 is illuminated
  - > Green LED "RUN" on PCA15 is illuminated
  - > Program will be run, i.e. output 32 will blink 0.5s on and 0.5s off (frequency 1Hz).
14. If the time base is to be changed to 1/100s proceed as follows: switch off the PLC, remove jumper from 1/10 and insert at 1/100. Switch the PLC on again. Push the mode selecting key **R** (RUN) for approx. 1/2s.
- > Output 32 blinks ten times faster, i.e. at 10Hz. The selection of the time base 1/100s is also evident from the higher blinking frequency of the yellow LED "CPU RUN".

e) Example program "Blinker" with watchdog activated

If it is desired that the watchdog function be activated for the preceding example program, the instruction COO 255 must be added to this circulating program. To ensure that this instruction is executed in every cycle independently of the blinker program, SEA must precede it. This alteration is programmed as follows:

15. Actuate the mode selecting key **P** (PROG) for approx. 1/2s.
16. Type in:

				Mnemocode
A	5	(20)	(1)	
E	(0005)	19	0	SEA 0
E	(0006)	13	255	COO 255
E	(0007)	20	1	JMP 1
E	(0008)	(00)	(0000)	

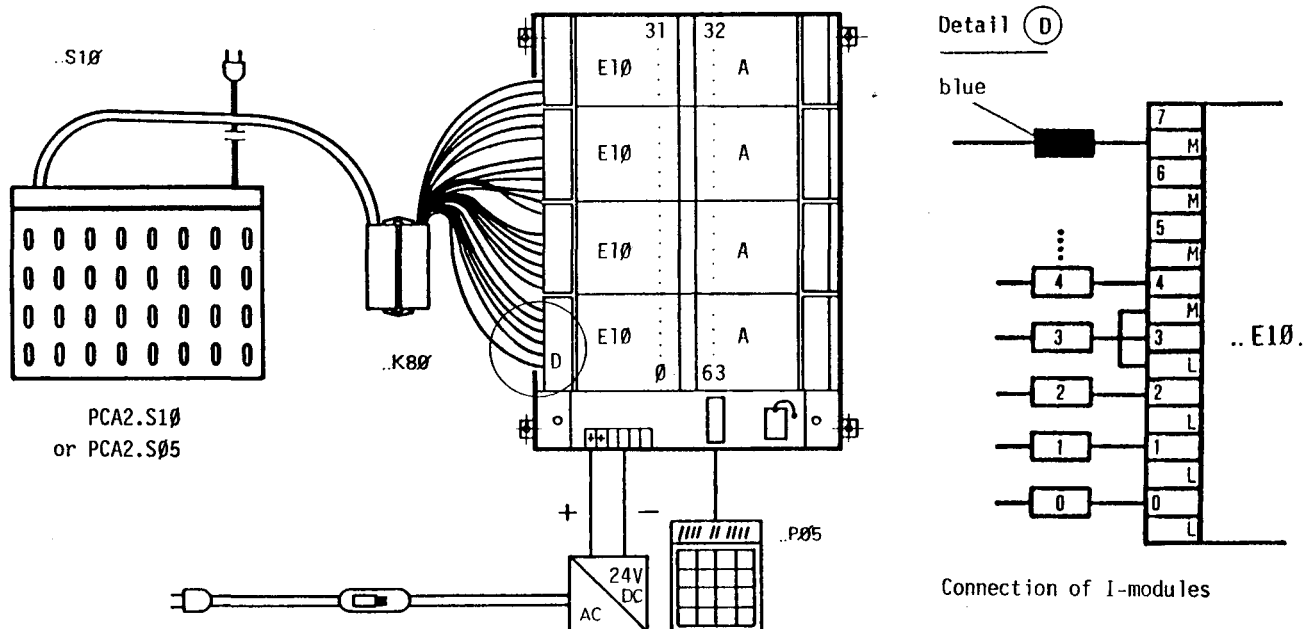
17. Actuate the mode selecting key **R** (RUN) for approx. 1/2s.

--> The program will be run and the green WD lamp will light because the watchdog circuit receives a frequency of approx. 1000Hz. If an operating mode is selected other than "RUN" the WD relay will release and the green WD lamp will go out. In order to provide effective protection for the controller, terminals 5 and 6 should be wired as described in chapter A 5.4 "The watchdog monitoring circuit".

f) Connection of the input simulation unit

A complete programming work station is obtained by using the PCA2.S10 input simulation unit with a PCA1.K80 connecting cable; many program examples can be tested with it.

18.



If a program starts, for example, at address 110, proceed as follows:

19. Actuate the mode selecting key **S** (STEP) for approx. 1/2s and type in

**A** 110 **+**

20. Actuate the mode selecting key **R** (RUN) for approx. 1/2s

--> Program starts to run from address 110.

Proceed similarly for all other examples.

### A 3 Technical data of system series PCA14

CPU	$\mu$ P 8085.2, system program V6.0.. 1)
Cycle time	70 $\mu$ s (per program line, average)
Instruction set	32 basic instructions, 20 additional instructions for arithmetics, text output, communication and parameter functions
Parameter functions	<ul style="list-style-type: none"> <li>- PID-loops</li> <li>- Shift registers</li> <li>- Check sum</li> <li>- Interrupt management</li> </ul>
Number of parallel programs	16 (PP 15 for interrupt control)
Number of index registers	16 (1 per parallel program)
Number of subroutines	as desired, 3 levels per parallel program
User memory	1K, 2K, 4K or 8K program lines on EPROM, RAM or buffered RAM memory
Text or data memory	2K, 4K or 8K character or data bytes on EPROM, RAM or buffered RAM memory, memory extension up to 40K characters with modules PCA1.R20/R25
Number of input and output addresses (depending on the housing size)	32, 64, 128
Max. no. of inputs + outputs (B90)	56, 112, 224
Flags	712 (477 volatile 2), 235 non-volatile)
No. of timers	32 (ADD 256...287)
No. of counters or arithmetic reg.	224 (ADD 256...479) as of V6.034
Counting capacity or arithmetic registers	65 535 ( $2^{16}-1$ ) with cascading as desired
Time range	0.1 (0,01)s...6553 (655)s
Date-time (software) 3)	Week, day of the week, year, month, day, hour, minute, second
Accuracy of date-time 3)	<3s/day
Serial data interface	20mA current loop, active or passive depending on cabling, for input/output of text or communication acc. to DIN 66019 Baud rate 110...9600 bauds 4)

1) When switching on the PLC, the system version is displayed on the programming unit P10 or P05 for one second. For this reason, the operating mode selector switch has to be in operating mode RUN.

2) Please refer to the text for modification possibilities.

3) Hardware date-time see chapter PCA1.E40.

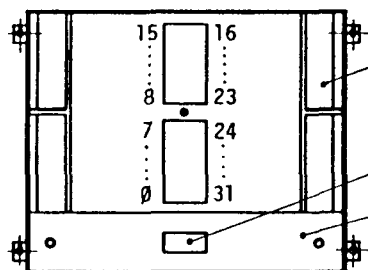
4) Owing to the high baud rates an appropriate program structure is required.

### A 3.1 Versions of system series PCA14

3 versions are available, corresponding to the required number of input and output addresses (PCA1.M47 and extension housing ..C45, see chapter A 4).

#### Type of system PCA141

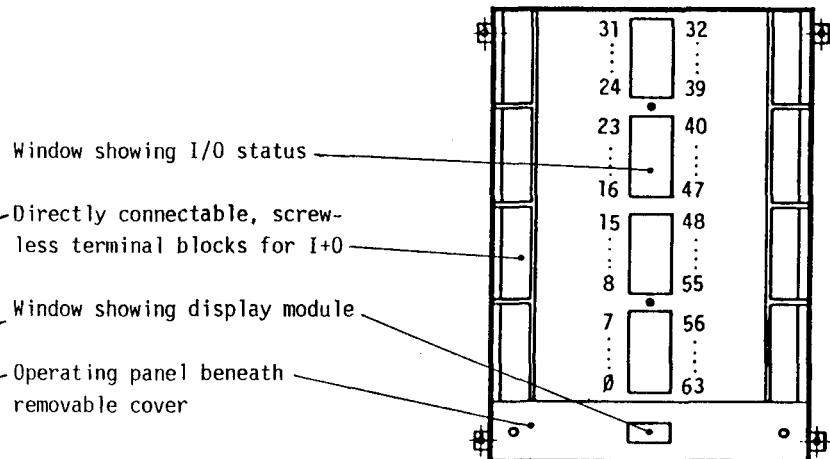
for 32 I+O addresses  
 ≅ 56 I+O with module B90



Basic module PCA1.M41

#### Type of system PCA147

for 64 I+O addresses  
 ≅ 112 I+O with module B90

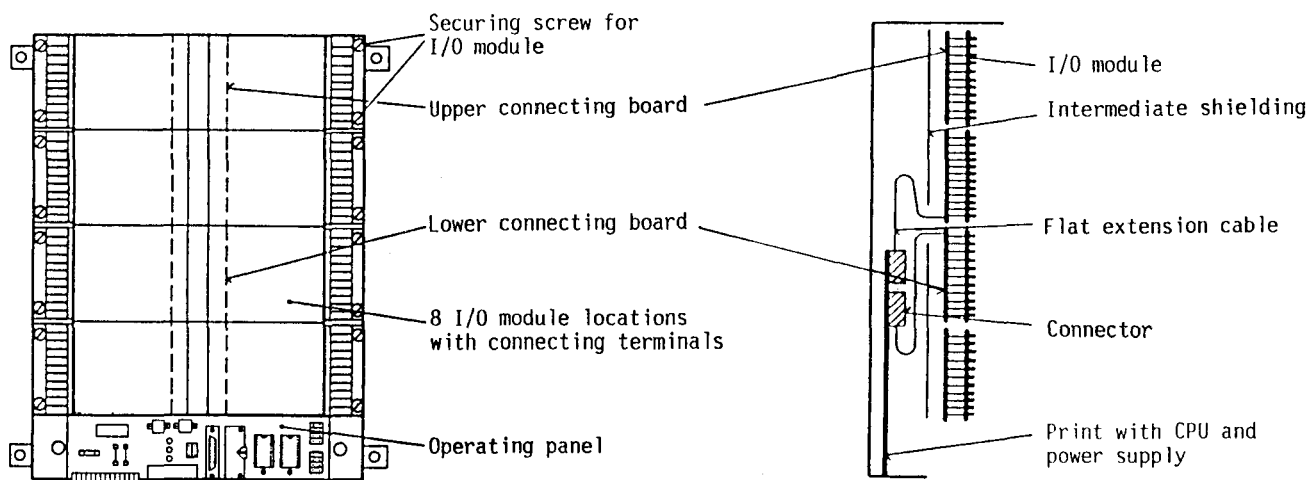


Basic module PCA1.M47

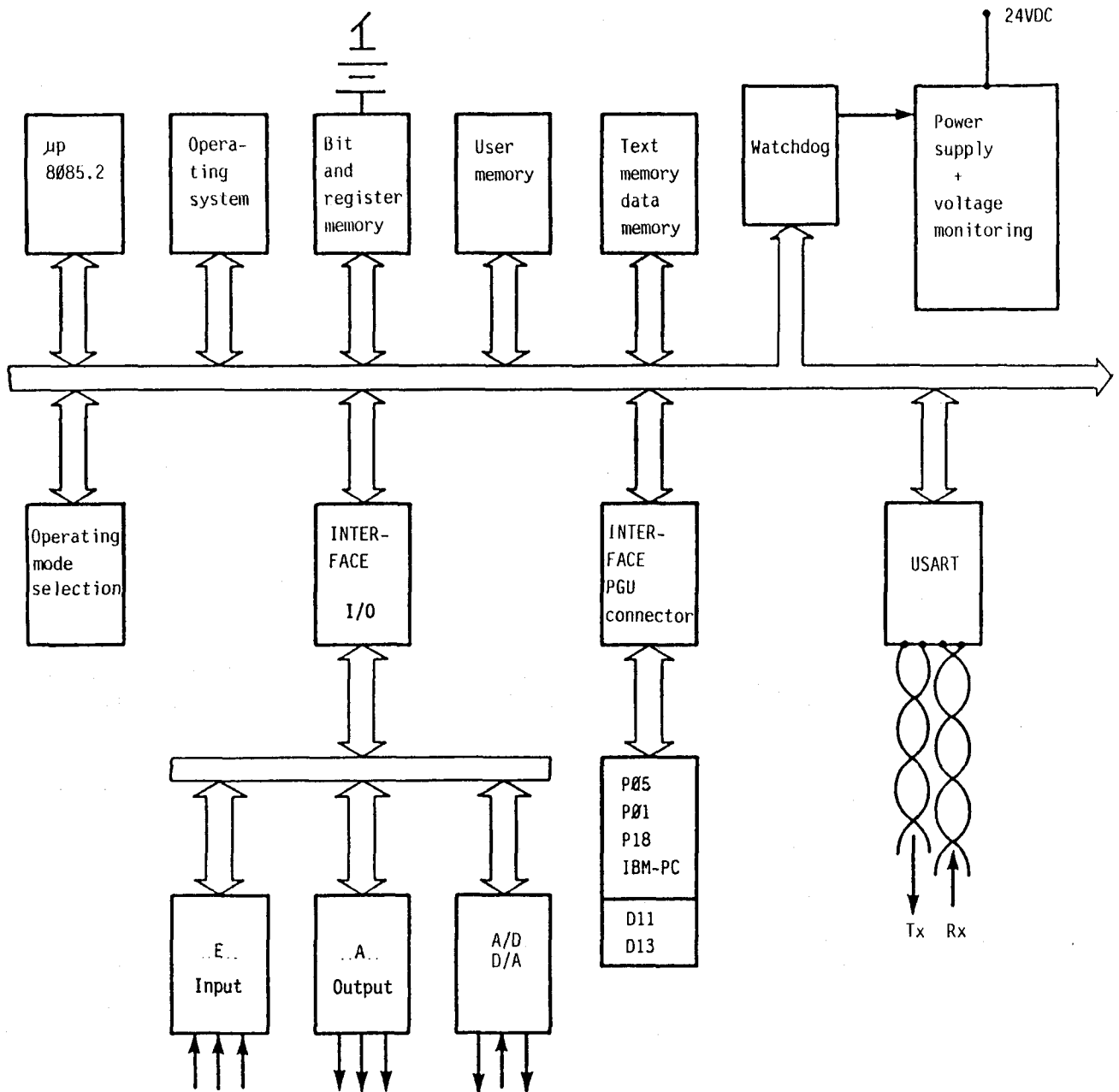
#### Types PCA1.M41 and M47 basic modules

In addition to the processor (CPU), the basic module of the system series PCA14 also includes the internal power supply and the housing.

#### Presentation (type of system PCA1.M47)



### A 3.2 Block circuit diagram PCA14

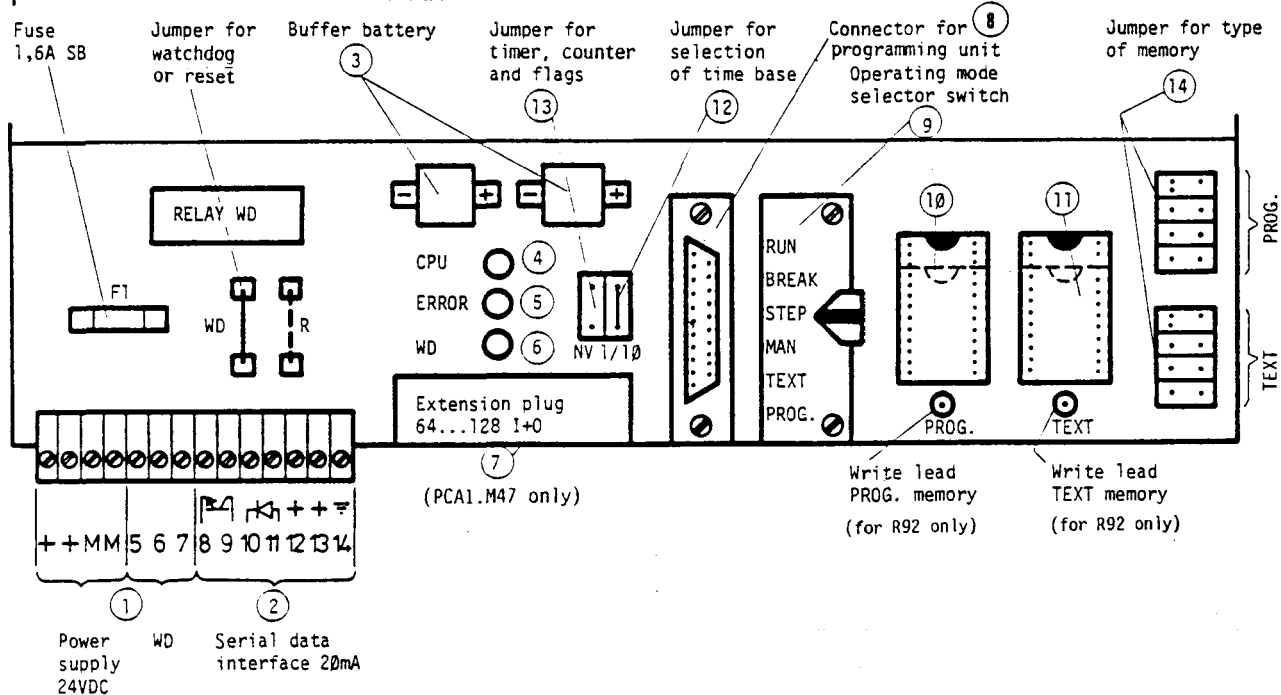


PCA141/46/47

### A 3.3 Basic modules

#### A 3.3.1 Operating panel of the basic modules PCA1.M41/M47

All operating elements for the PCA14 are clearly arranged on the operating panel which can be covered.



- ① The terminal strip is plugged onto the circuit board. Wires with diameters up to 1.5 mm<sup>2</sup> are accepted by the screw terminals.
- ② The serial data interface is connected on the circuit board. Depending on wiring, it can be defined whether the PCA14 is active or passive at the 20mA-current loop.
- ③ The buffer battery supplies the retentive flags, counters/timers and, if used, the 6116 or 6264 RAM chip user memory. The data is protected for approx. 2 months when the PLC is switched off. The NiCd cells last approx. 5 years. Spare battery no. 4'507'1195'0. A new version with a plug-in battery is available as of 1989 (no. 4'507'1360'0).
- ④ The CPU monitoring lamp (yellow) blinks every 2s during normal operation. When the time-base is set to 0.01s, the blinking rate is 0.2s. If the light stays on or off, there is either no power available, the PLC is in RESET mode, the CPU has a malfunction or a trap has been produced in the software sequence.
- ⑤ The ERROR lamp (red) indicates errors at the serial data interface. For details refer to chapter "The serial data interface" (see manual software level 2).
- ⑥ The watchdog monitoring lamp (red) is illuminated when the watchdog relay is excited. Please refer to chapter "The watchdog monitoring circuit" for details.
- ⑦ The 25-pole connector of the extension cable (only on the PCA147) allows an increase in I/O from 64 or 112 to 128 or 224 inputs/outputs owing to the connecting cable attached to the extension housing ..C45.



- ⑧ The 25-pole connector (PGU) is used to connect the programming unit. A latch is not provided, because the mode selected on the operating mode selector switch remains operative (unlike the PCA2) when the programming unit is removed.
- ⑨ The operating mode selector switch is used for starting up, troubleshooting and editing of texts. Position "LCM" (transfer from e.g. RAM to EPROM) is not available, because this function is not possible with the PCA1; the PCA2.P16 copying unit is required.
- ⑩
- ⑪ The two 28-pole sockets accommodate the user or text memory "PROG" or "TEXT" respectively (see chapter "Organization of program and text memory"). When inserting them, make sure that the groove points to the top. If 25-pole sockets are used (e.g. 6116, 2716, 2732A), please insert in such a way that they are flush with the lower edge of the socket. The following memory types can be used.

. RAM chip on socket

- 4 502 4512 0 (type 6116) for 1K program lines (24-pole)  
 4 502 4718 0 (type 6264 or 8464) for 4K program lines (28-pole)

Comment: The 6116 and 6264 or 8464 RAMs allow writing, erasing and modification of a program. On power failure, the memory contents are stored by the buffer battery for approx. 2 months. The program, however, is not transportable, because the data stored is lost, if the RAM chip is removed.

. Buffered RAM memory module

- |               |  |                   |
|---------------|--|-------------------|
| Type PCA1.R92 | for 2K program lines (24-pole) <sup>1)</sup> | } see chapter B 2 |
| Type PCA1.R95 | for 4K program lines (28-pole)               |                   |
| Type PCA1.R96 | for 4K program lines (28-pole)               |                   |

User programs can be introduced on the left socket (PROG) as well as on the right socket (TEXT). Text can only be introduced on the right socket. For programming or introduction of texts please insert the write lead for the left socket on the left and that for the right socket on the right. In order to avoid program mutations interrupt both connections during continuous operation in the RUN mode.

Contrary to the 6116 or 6264 RAM chip, the program in this memory is transportable, since it is protected by an integrated circuit and a lithium battery which lasts approx. 8 years. This module is therefore particularly suitable for starting up the controller.

For copying of programs please refer to chapter "PCA2.P16 EPROM-copying unit".

- 1) Attention: Neither the wire lead nor the connector WR must be touched or get into contact with the ground, since otherwise changes in contents may occur.

. EPROM chips on socket

- No. 4 502 4373 0 (type 2716) for 1K program lines (24-pole)
- No. 4 502 4644 0 (type 2732A) for 2K program lines (24-pole)
- No. 4 502 4719 0 (type 2764) for 4K program lines (28-pole)

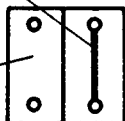
According to prior art, reliable operation of user programs over a period of several years is only ensured, if EPROM memories are used. The manufacturers chosen by us guarantee program safety for at least 10 years.

It is recommended to protect the window of the EPROM by means of a sticker in order to prevent the memory from being accidentally subjected to UV-radiation.

An extension of the text and data memory up to 40K bytes is possible by using the modules PCA2.R20 and R25.

12  
13 The selector jumpers allow various selections:  
14

- The selection of the time base for the timers



NV 1/10

1/10s: jumper inserted (factory setting)

1/100s: jumper not inserted

- The selection of the retentive flags 13

If the jumper is inserted, all flags, timers and counter registers are retentive. If the jumper is not inserted (factory setting), only the flags 765...999 are retentive.

- The selection of the user or text memory 14

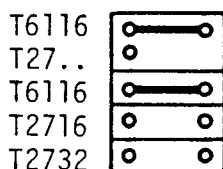
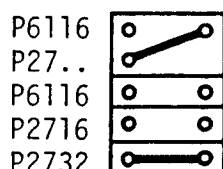
When using the various RAM or EPROM for user program or text, the jumpers have to be inserted as is shown in the following table.

		RAM		Buffered RAM or EPROM		
		6116	6264/8464	R91 2716	R92 2732A	R95/96 2764
P6116 P27.. P6116 P2716 P2732	 PROG-memory	6116	6116	6116	6116	6116
		27..	27..	27..	27..	27..
		6116	6116	6116	6116	6116
		2716	2716	2716	2716	2716
T6116 T27.. T6116 T2716 T2732	 TEXT-memory	6116	6116	6116	6116	6116
		27..	27..	27..	27..	27..
		6116	6116	6116	6116	6116
		2716	2716	2716	2716	2716

Jumper inserted  
 Jumper not inserted

**Attention:** Do not use any other plug combinations, as these can cause damage to the CPU!

**Example:** When using an EPROM 2732 for the user program (P) and a RAM 6116 for the text (T), insert the jumpers as follows:



**Note:**

The preselection jumpers of the PCA14 for RAM R91 or EPROM 2716 respectively are inserted (factory setting).

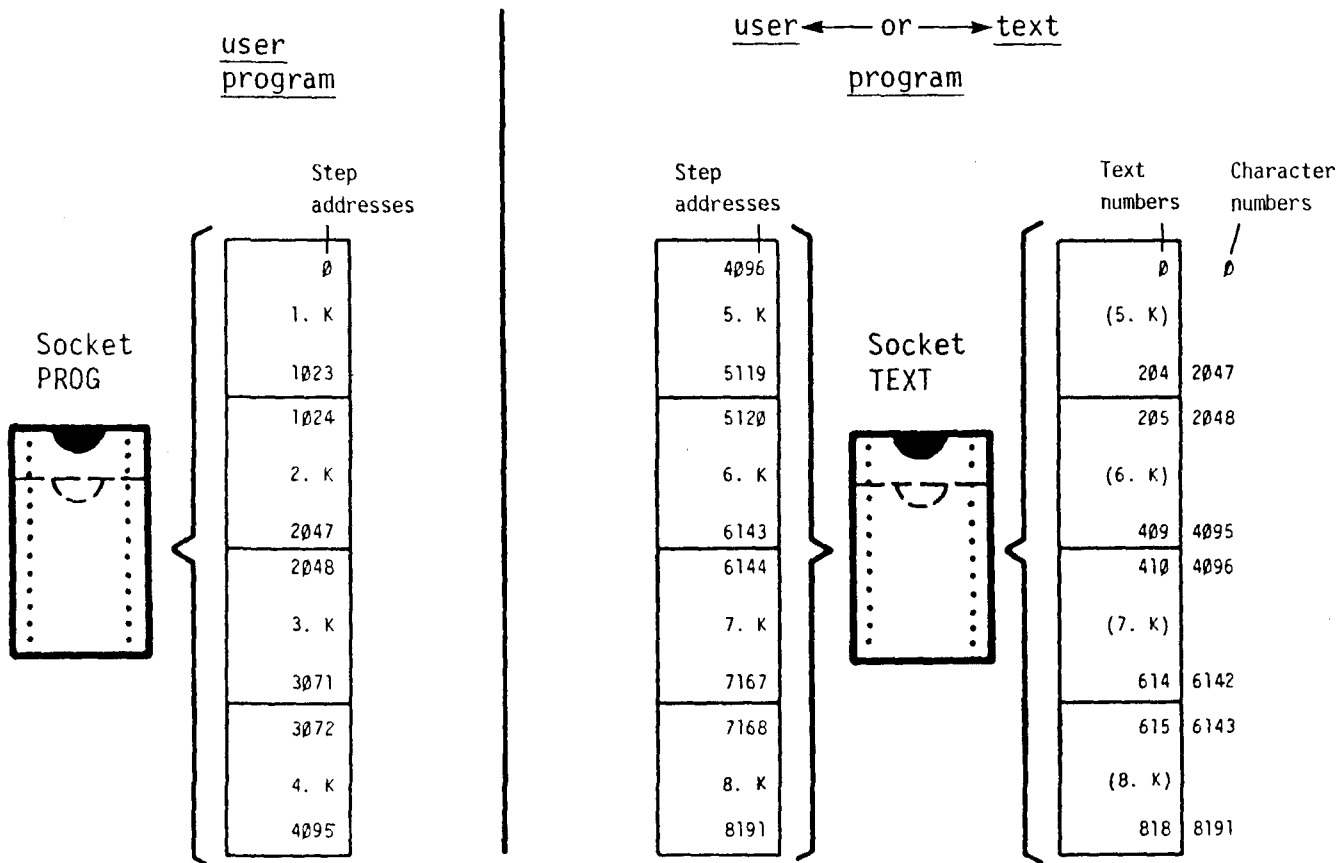
### A 3.4 Organization of program and text memory

All RAM, EPROM or buffered RAM-memory modules mentioned in paragraph "28-pole socket for user memory" can be used both for user programs and texts.

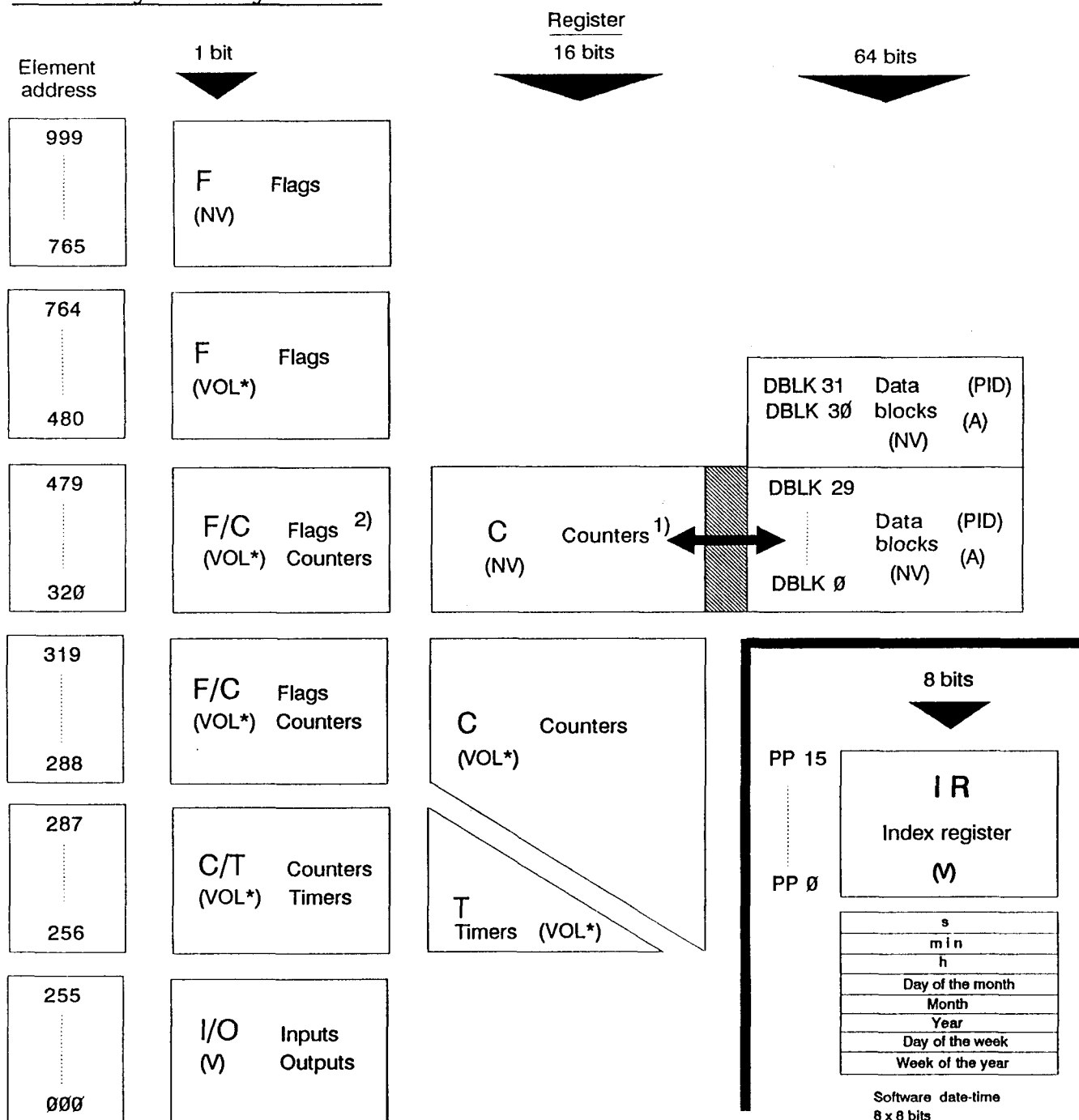
User programs can have a length of up to 8K program lines (at 16 bits). With user programs having a length of more than 4K, the first 4K are stored in the PROG memory on the left (1K...4K) and up to 4K more can be stored in the TEXT memory on the right (5K...8K).

If, e.g., only 2K-memories are available and a user program of > 2K has to be prepared, the 1. and the 2.K can be stored on the left socket PROG (addresses 0...2047) and the 3. and the 4.K on the right socket TEXT (addresses 4096...6143).

Texts having a length of up to 8K characters (at 8 bits) can only be stored in the TEXT memory on the right.



### A 3.5 Register organization



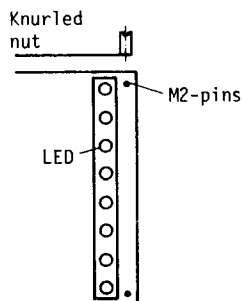
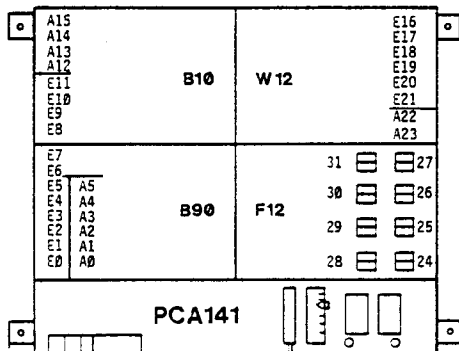
- (V) volatile  
 (NV) non-volatile  
 (VOL\*) volatile, can be made non-volatile with jumper NVOL  
 (A) jumper A open: all 32 DBLK are non-volatile

- 1) Counter registers C320...C479 and PID-data blocks 0...29 use the same memory area. It is therefore recommended to start with DBLK 31 for PID-control tasks.
- 2) The counter registers C320...C479 are available from system program version V6.034 onwards.

Notes:

### A 3.6 Instructions for operating a PCA14 in brief

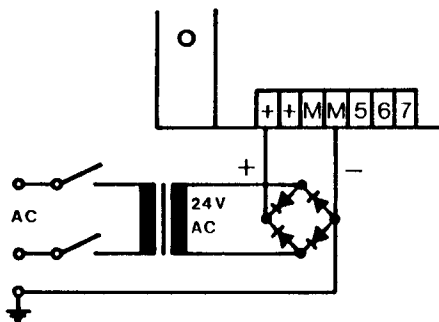
#### a) Installation of I/O modules



In order to test the programming examples, the I/O-equipment must be selected as evident from the accompanying figure. For a short test it suffices to install the I/O-module B90 using the address range 0...7.

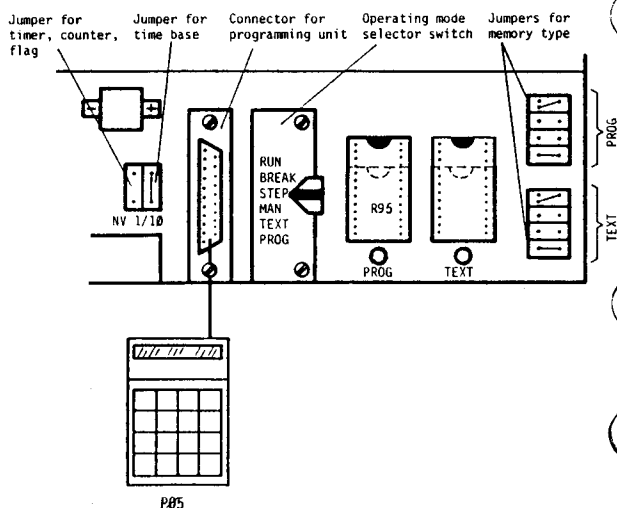
1. Undo fastening screw of the cover and lift.
2. Center I/O-modules above the two M2-pins and carefully press them into the blade connectors.
3. Tighten knurled nuts M2 and ZK-screws with tooth washers on the terminal side.
4. Provide the LEDs with the corresponding address labels.

#### b) Power supply



5. Take a transformer (for "playing" 30VA is enough) with a secondary voltage of 24VAC and connect the terminals + and M of the PLC via a bridge rectifier.
6. A switch has the advantage that all resettable elements and the STEP-counter can easily be reset to their defined starting positions by switching off the PLC.

#### c) Connection of the user memory or text memory R95 or R96 and the programming unit P05



7. For employment of the buffered RAM memory module R95/96 the preselection jumpers on the outer right must be inserted correspondingly (see fig.). For the following simple example (without text output) it is sufficient to use the program memory and to insert the jumpers in position "PROG" accordingly.
8. The buffered RAM-module R95/96 must be inserted in the marked position - notch at the top.
9. The programming unit P05 is connected to the 25-pole connector.

d) Programming example "Blinker"

10. Set operating mode selector switch to "PROG".
11. Switch on power supply of the PLC. The CPU lamp (yellow) flashes 1s on, 1s off. The watchdog lamp (red) is not illuminated.
12. Enter the following blinker program:

	STEP	CODE	OPERAND	Program in mnemocode
A, E	(0000)*	(00)	(0000)	
E	(0001)	01	1	→ STH E1
E	(0002)	04	256	ANL T 256
E	(0003)	14	256	STR T 256
E	(0004)	00	5	0.5 s
E	(0005)	13	400	COO M400
E	(0006)	01	400	STH M400
E	(0007)	10	5	OUT A5
E	(0008)	20	1	JMP 1
E	(0009)	(00)	(0000)	

\*) The values in brackets do not have to be entered, but they are displayed.

13. Set the operating mode selector switch to "RUN". Switch PLC off and on again.

→ The program is executed. In order that output A5 flashes, a voltage of +24V must be applied to input E1. The easiest way to do this is to lead a wire from the power supply terminal + to input terminal E1. As long as this connection exists, A5 flashes at a frequency of 1Hz (if present, the jumper on the B90-module must be "-" (minus)).

14. If the time base is to be changed to 1/100s, proceed as follows: Switch off PLC, remove jumper "1/10". Switch on PLC again.

→ Output A5 flashes 10 times faster, i.e. at 10Hz. The selection of the time base of 1/100s is also recognizable by the higher flashing frequency of the CPU-lamp (yellow).

e) Blinker example with watchdog activated

If in the preceding example the watchdog is to be activated, the instruction COO 255 must be added to this circulating program. In order that this instruction be executed during each cycle independently of the indicator program, it must be preceded by SEA.

This is programmed as follows:

15. Set operating mode selector switch to "PROG".
16. Enter:

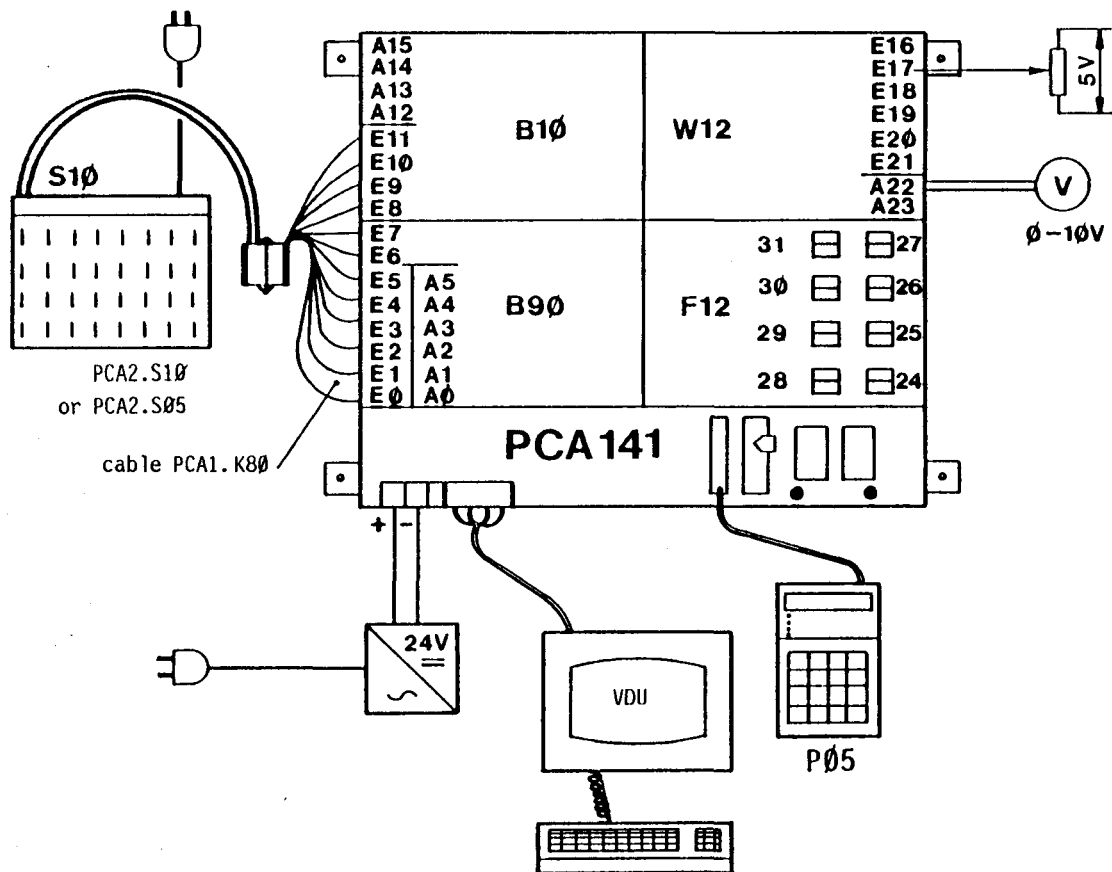
				Mnemocode
A	8	(20)	(1)	
E	(0008)	19	0	→ SEA 0
E	(0009)	13	255	COO 255
E	(0010)	20	1	JMP 1
E	(0011)	(00)	(0000)	



17. Set operating mode selector to "RUN" again.  
 → The program is executed, the red WD-lamp is illuminated, as the WD-circuit receives a frequency of approx. 700Hz. If the operating mode selector switch is set to any other position than "RUN", the WD-relay is released, the red WD-lamp goes out. In order to provide effective WD-protection for the controller, the connectors 5 and 6 and the power supply line must be wired accordingly.

f) Connection of the input simulation unit PCA2.S10

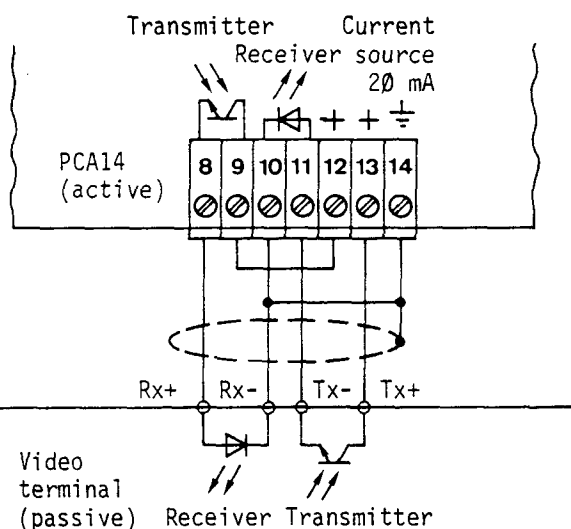
18. The input simulation unit, further modules, a variable DC-voltage of 0...5V as well as a voltmeter 0...10VDC (10kΩ) and a video terminal with a 20mA-data input (or with an adapter 20mA/(RS232c) form a complete program developing and simulation unit for the following programming examples.



The above configuration corresponds to the simulation case V-PCX8.

g) Installation of the 20mA-serial data interface with a video terminal for text input and output

g1) Establishing the cable connection PCA14 <---> video terminal



It must be provided that the video terminal is fitted with a 20mA-current loop interface for full-duplex operation (or a suitable adapter 20mA/RS 232c).

19. The cable connection (max. length of 100m) can be established according to the accompanying figure. The terminal must be "passive", i.e. the 20mA are supplied by the PCA14.

g2) Installation of the text memory module

20. The RAM-memory module R95/96 is inserted to the right of the user memory for the storage of texts. The jumpers are preselected according to chapter point (7.) of this chapter.

g3) Selection of the communication parameters

They are defined according to chapter "Activation of the interface via the software ...".

21. Assumed values for setting the video terminal:

Most of the following values can be preselected via the DIL-switches. If a switch or a key for "Full Duplex" is available, it should be locked in position (for details refer to the manual of the video terminal).

Communication parameters for PAS 100 (assumed)

. Baud rate	4800	6
. Data bits	7	0
. Parity	yes	128
. Even	yes	256
. Stop-bit	1	512
Total		902

This value must be added in line 2 of the 10-line assignment instruction PAS 100.

g4) Activation of the PCA14 data interface  
as editor and for checking the text output

22. The PAS 100-instruction for activating the editor and test output of the text just edited is given at the end of the user memory e.g. at address 4001.

4001	PAS	29	100	
4002		00	902	Transmission parameters (4800 bauds etc.)
4003		01	12	01 for text editor, A12 for Text Busy
4004		00	254	The higher address of 2 elements permanently remain "L", e.g. elements 254 and 253
4005		00	254	
4006		00	0	
.		.	.	NUL
.		.	.	
4010		00	0	
4011	PAS	29	23	Text output from text no. 30 on
4012		00	30	
4013	JMP	20	0	
4014		00	4011	(01 1963)

g5) Enter a text into the text memory

23. Set operating mode selector switch to "STEP".
24. By pressing  4001  on the P05 input unit jump to the beginning of the assignment.
25. By pressing  execute assignment up to 4011.
26. Type in 030 "CR" on the VDU terminal.

030 "CR"

030:.A.B. . . . ^@^@^@^@  
030:

The displayed text is random in case of an uncleared text memory. A point pre-  
ceding a character means that this character is part of the visible section of the ASCII-table (32...127). Control instructions from the "control case" are preceded by an arrow or a ^.

Display on the screen

- CTRL/T ————— 27. To activate the text input mode, press keys **CTRL** and **T** (CTRL/T) simultaneously.
28. Then enter 5 spaces using the special character **\$**, the followed by the SAIA°PLC logo.
- 030: **\$. .0.0.5.S.A.I.A.-**  
 030:  
 031: **.P.L.C^M^J.C.R.O.W.N** — 29. Note that as soon as 10 characters have been entered, the screen automatically proceeds to the following text number.  
 031:  
 032: **.E.D. .W.I.T.H. .P.C**  
 032:  
 033: **.A.1.4^M^J^@^@^@^@** — 30. To enter "CR" without changing the text mode, **^** must be pressed first. The CPU answers with ^M (CTRL/M = "CR").  
 033:
31. To enter "LF" = Line Feed, **CTRL/J** is pressed which corresponds to "LP" ^J appears.
32. NUL is entered to end text input. This is possible via **CTRL/@** (may differ from one peripheral unit to another).
33. To exit from the editor mode enter **"CR"**.

g6) Output of this text

34. With **+** **+** on the P05 unit the program loop 4011 to 4014 is executed once, as a result of which the text is output.

SAIA°PLC  
 CROWNED WITH PCA14

After this sample text has been input/output successfully, the programming examples in the "Software" manual can be entered and tested.

g4) Activation of the PCA14 data interface  
as editor and for checking the text output

22. The PAS 100-instruction for activating the editor and test output of the text just edited is given at the end of the user memory e.g. at address 4001.

4001	PAS	29	100	Transmission parameters (4800 bauds etc.) 01 for text editor, A12 for Text Busy The higher address of 2 elements permanently remain "L", e.g. elements 254 and 253
4002		00	902	
4003		01	12	
4004		00	254	
4005		00	254	
4006		00	0	NUL
.		.	.	
.		.	.	
.		.	.	
4010		00	0	
4011	PAS	29	23	Text output from text no. 30 on (01 1963)
4012		00	30	
4013	JMP	20	0	
4014		00	4011	

g5) Enter a text into the text memory

23. Set operating mode selector switch to "STEP".
24. By pressing A 4001 + on the P05 input unit jump to the beginning of the assignment.
25. By pressing + execute assignment up to 4011.
26. Type in 030 "CR" on the VDU terminal.

030 "CR"

030:.A.B. . . . ^@^@^@^@  
030:

The displayed text is random in case of an uncleared text memory. A point pre-  
ceding a character means that this char-  
acter is part of the visible section of  
the ASCII-table (32...127). Control in-  
structions from the "control case" are  
preceded by an arrow or a ^.

Display on the screen

- CTRL/T ————— 27. To activate the text input mode, press keys **CTRL** and **T** (CTRL/T) simultaneously.
28. Then enter 5 spaces using the special character **\$**, the followed by the SAIA°PLC logo.
- 030: \$. .0.0.5.S.A.I.A.—  
030:  
031: .P.L.C^M^J.C.R.O.W.N — 29. Note that as soon as 10 characters have been entered, the screen automatically proceeds to the following text number.  
031:  
032: .E.D. .W.I.T.H. .P.C  
032:  
033: .A.1.4^M^J^@^@^@^@ — 30. To enter "CR" without changing the text mode, **^** must be pressed first. The CPU answers with ^M (CTRL/M = "CR").  
033:
31. To enter "LF" = Line Feed, **CTRL/J** is pressed which corresponds to "LP" ^J appears.
32. NUL is entered to end text input. This is possible via **CTRL/@** (may differ from one peripheral unit to another).
33. To exit from the editor mode enter **"CR"**.

g6) Output of this text

34. With **+** **+** on the P05 unit the program loop 4011 to 4014 is executed once, as a result of which the text is output.

SAIA°PLC  
CROWNED WITH PCA14

After this sample text has been input/output successfully, the programming examples in the "Software" manual can be entered and tested.

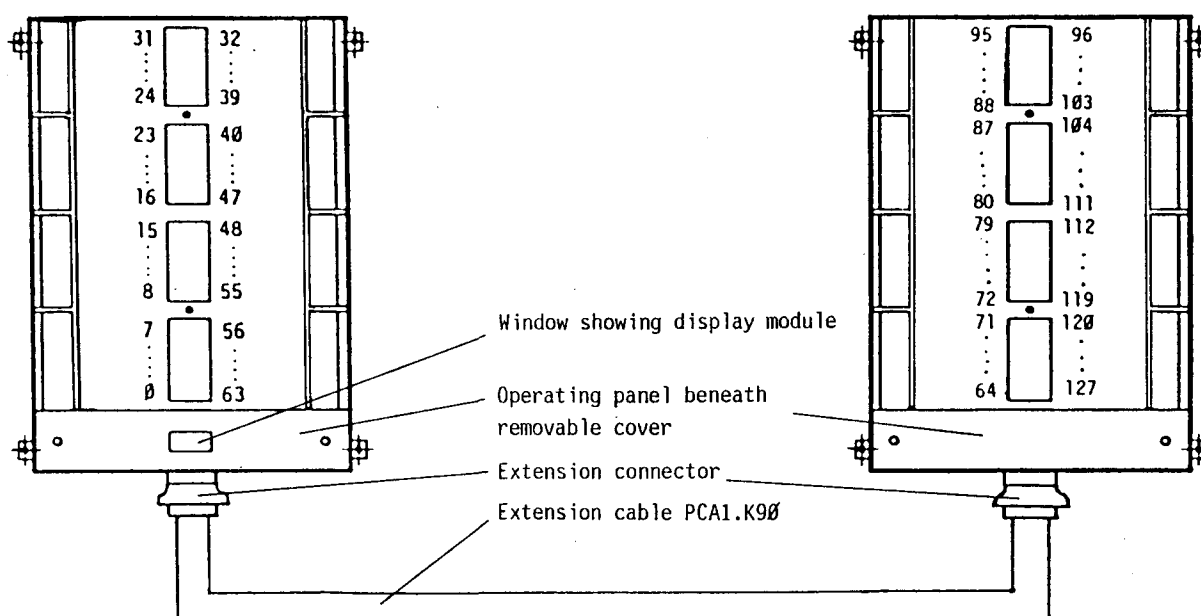
## A 4 Extension housing ..C45

### A 4.1 Basic module PCA1.M57/M47 with extension housing PCA1.C45

In addition to the entire circuitry of the PCA1.M47/M57, the basic module PCA1.M56 also contains the switching circuits and the connector for connection to the extension housing.

The extension housing PCA1.C45 is connected via the connecting cable PCA1.K90. It also has a power supply unit of its own.

### A 4.2 Type of system PCA157/147 with extension housing PCA1.C45 128 I+O addresses, 224 I+O with compact module PCA1.B90



Basic module PCA1.M57 or PCA1.M47

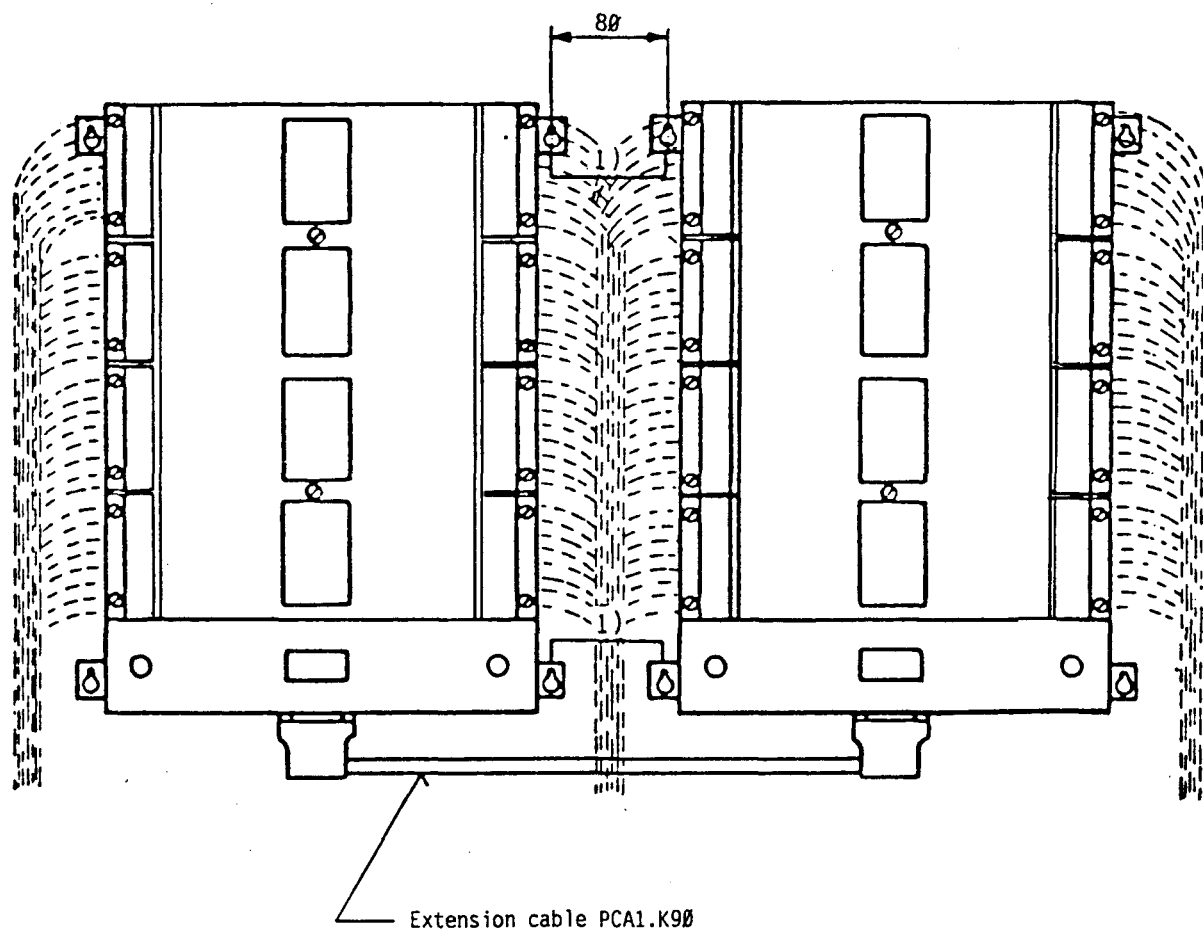
Extension housing PCA1.C45

The three versions are completely compatible as regards hardware and software and can be equipped with all the old and new I/O modules of the series PCA1.

#### A 4.3 Arrangement of the PCA157/147 with extension housing ..C45

Basic module  
PCA1.M47/M57

Extension housing  
PCA1.C45

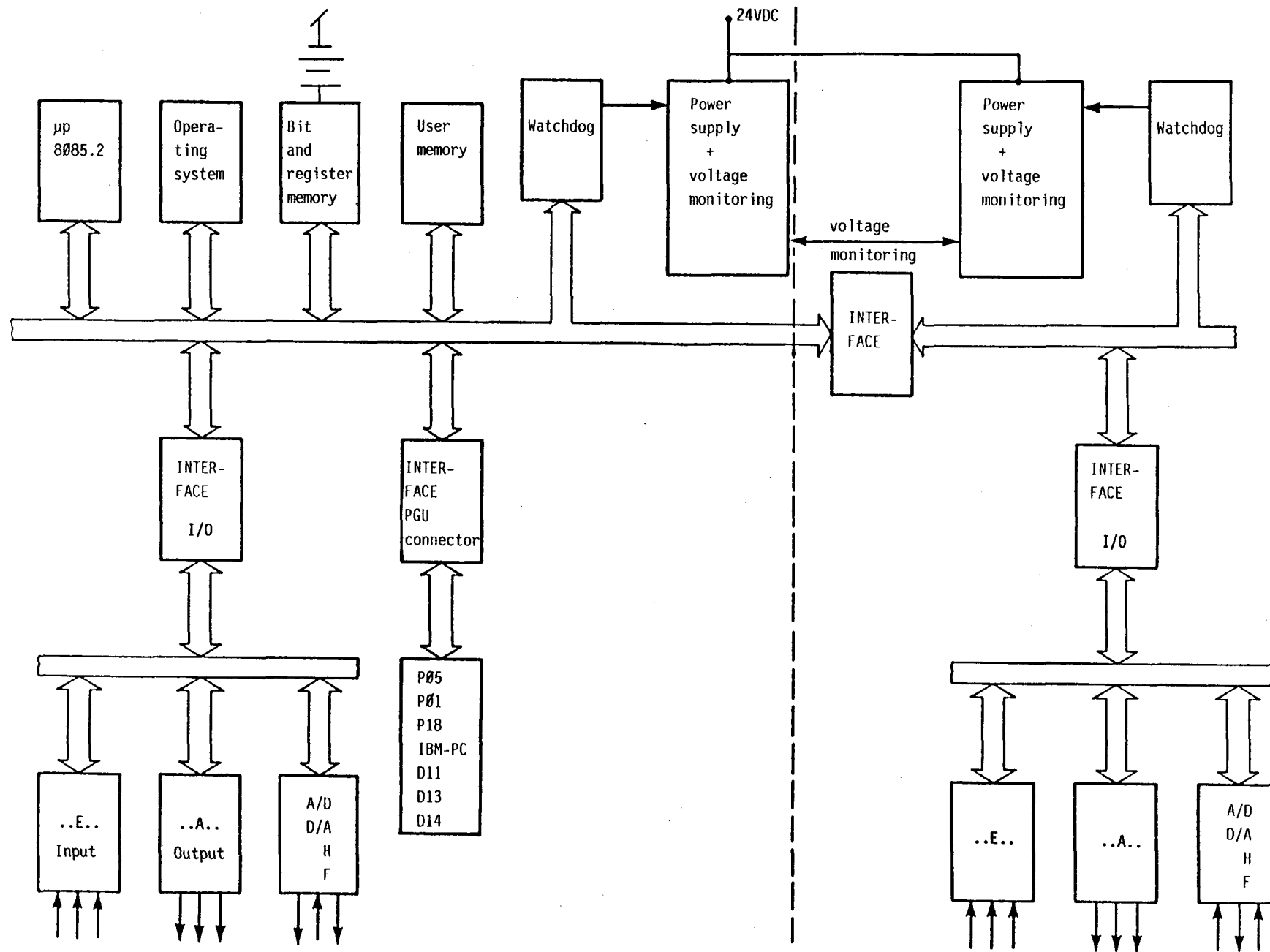


1) There has to be a good metallic bond between both housings.

The extension cable PCA1.K90 is screened so that the I/O wiring and other lines can be laid above this cable.



A 4.4 Block circuit diagram



PCA157/147

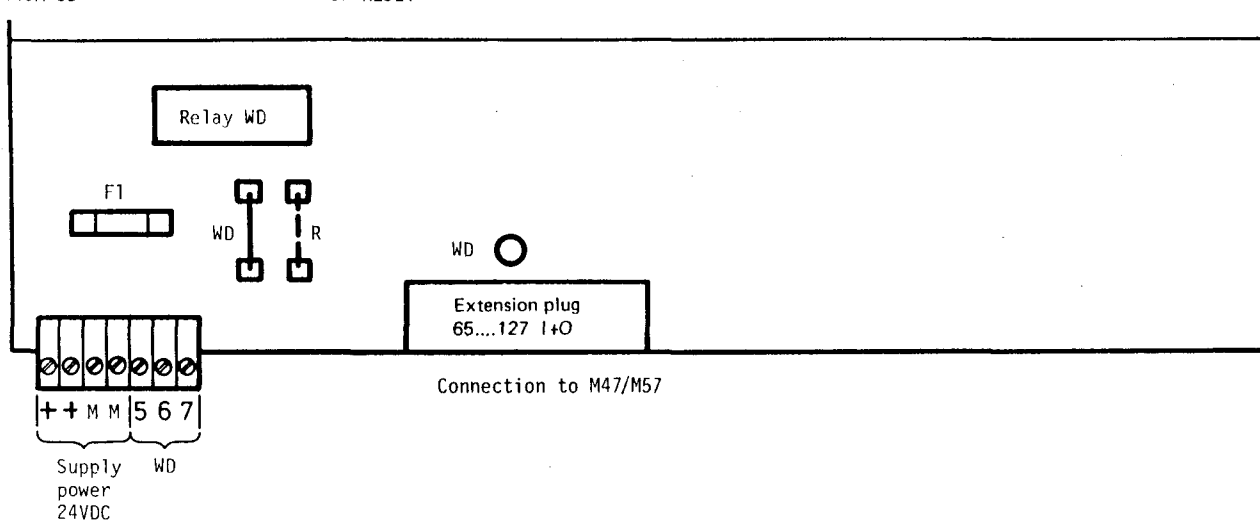
Extension housing PCA1.C45

#### A 4.5 Operating panel of extension housing ..C45

As with PCA157/147, all operating elements for extension housing ..C45 are logically arranged on the operating panel which can be covered.

Fuse  
1.6A SB

Jumper for watchdog  
or RESET



The operating elements described here have the same functions as those of the PCA1 (see chapter "Operating panel").

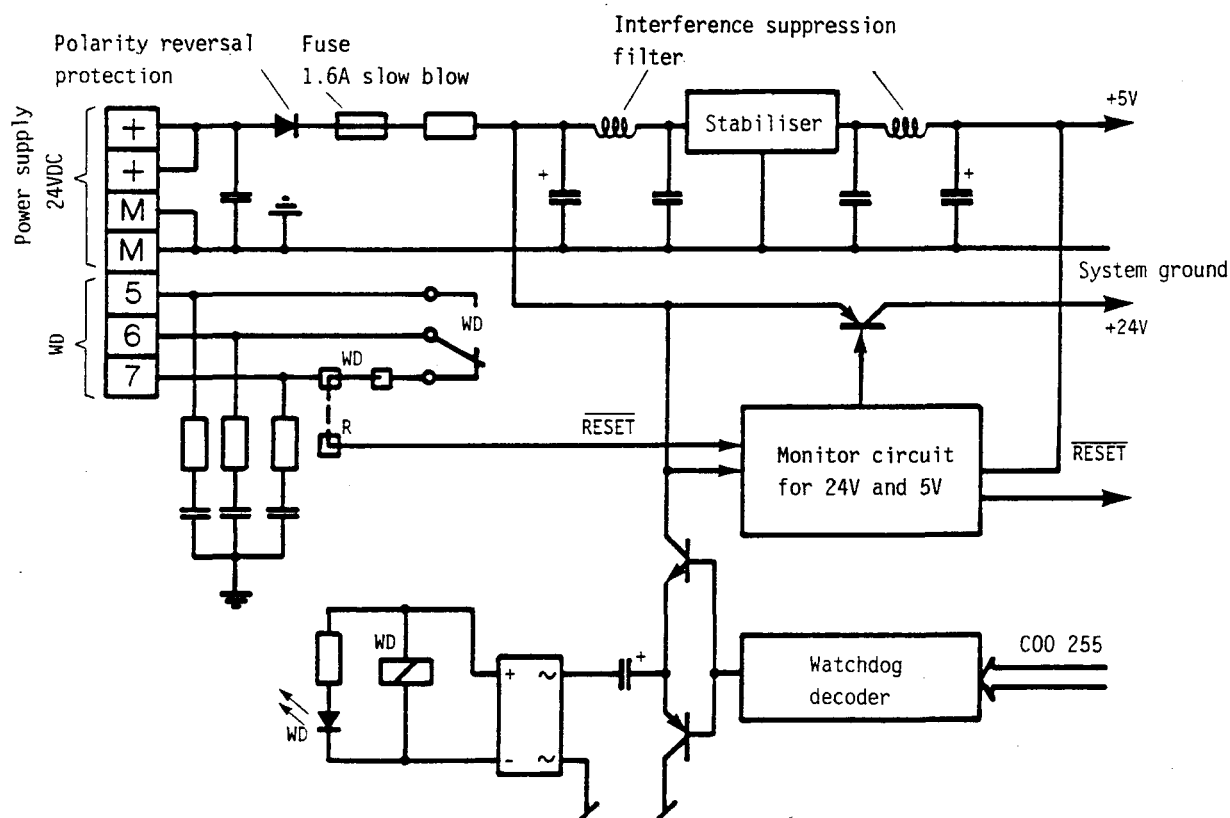
## A 5 Power supply, watchdog, reset, dimensions

### A 5.1 Power supply of PCA1

Supply voltage $V_{in}$	24VDC, smoothed or pulsating
Voltage tolerance	normally $\pm 20\%$ (see following page for details)
Supply current	max. 1A for basic modules and ..C45
Output voltages to electronics	24VDC, smoothed, for internal output driver 5VDC, stabilised $\pm 3\%$ , for remaining electronics
Output current 5V	1.1A
Ambient temperature $T_a$	$0 \dots 50^\circ\text{C}$ (see following page for details)

As indicated on the following page, the PCA15 can be operated with pulsating (P) or smoothed (G) direct current. It may also be connected to the same power supply available for the sensors and actuators. Several components protect the PLC against interference voltages, polarity reversal and low voltages. The 5VDC for supply of the electronic components is generated by a stabiliser.

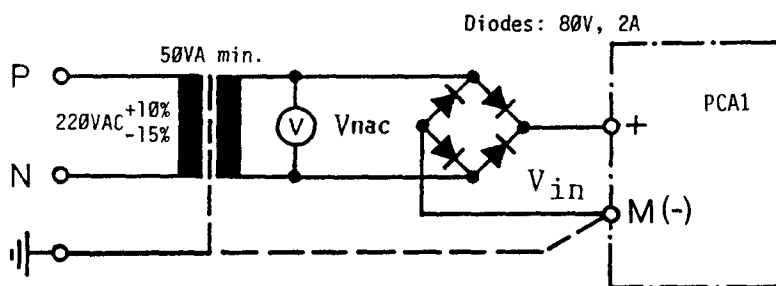
### Block circuit diagram for PCA1 and extension housing ..C45



## A 5.2 Various external power supply circuits

In order to provide the PCA1 and the extension housing ..C45 with the reasonably priced power supplies, a stabiliser has been included in the power section of the PCA1 and the extension housing ..C45, in addition to interference and polarity reversal protection. In case of PCA1.A2.. output modules, this smoothed 24VDC is used for the internal excitation of the relays. One differentiates between two types of power supply, "P" and "G".

### P Power supply with pulsating DC from a transformer with a bridge rectifier



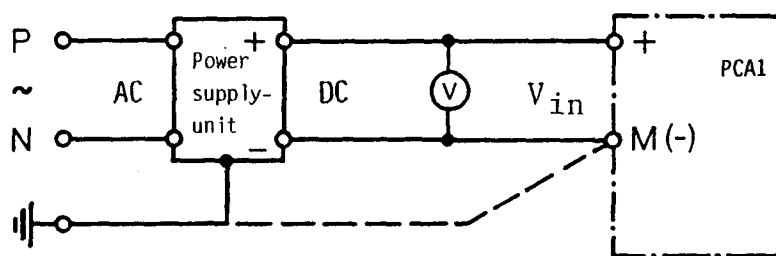
The following information is based on the assumption that the mains supply and therefore the secondary voltage will vary  $\pm 10\%$ /-15%; the AC voltages are based on 220VAC primary.

P1 Without relay output modules  
Secondary alternating voltage  $V_{nac}$ : 22...24.5VAC ( $T_a = 0...50^\circ\text{C}$ )  
(complete range incl. primary voltage fluctuations of  $\pm 10\%$ /-15%: 18.7...27VAC).

P2 With max. 4 relay output modules PCA1.A2..  
Secondary alternating voltage  $V_{nac}$ : 24VAC ( $T_a = 0...50^\circ\text{C}$ )  
(complete range incl. primary voltage fluctuations of  $\pm 10\%$ /-15%: 20.4...26.4VAC)

P optimal For all combinations  $V_{nac}$ : 24VAC

### G Power supply with smoothed DC from power supply unit



It is assumed that the external power supply will not only smoothen but will also stabilise the DC voltage.

G1 Without relay output modules  
Direct voltage range  $V_{in}$ : 20...32VDC ( $T_a = 0...50^\circ\text{C}$ )

G2 With max. 4 relay output modules PCA1.A2..  
Direct voltage range  $V_{in}$ : 24...30VDC ( $T_a = 0...50^\circ\text{C}$ )  
Direct voltage range  $V_{in}$ : 22...32VDC ( $T_a = 0...35^\circ\text{C}$ )

G optimal For all combinations  $V_{in}$ : 26VDC

### A 5.3 Voltage monitoring

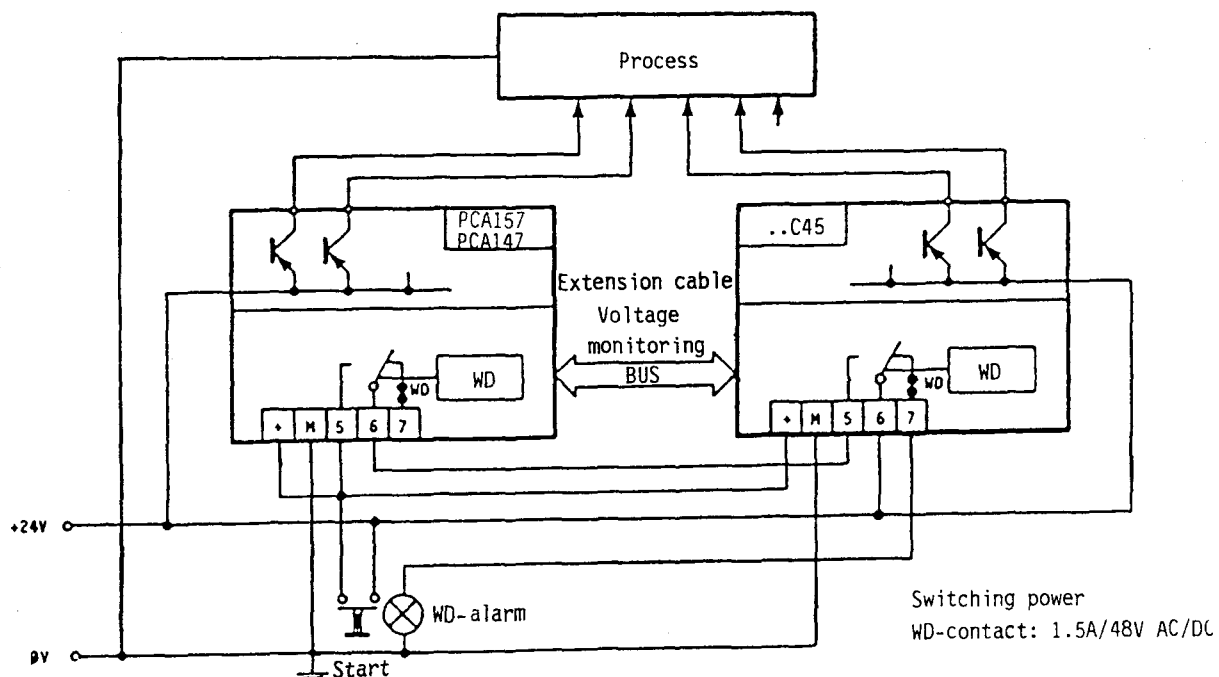
Both the supply voltage  $V_{in}$  and the 5V of the PCA1 and the extension housing the CPU is set in RESET mode, i.e. all volatile flags as well as all outputs are reset. When the input voltage is switched on (or switched on again), the CPU is cleared for operation after 100ms. This delay allows safe resetting of all outputs and provides a clearly defined starting position for program execution.

### A 5.4 Watchdog monitoring circuit

Both the PCA15/14 and the housing ..C45 incorporate this circuit. The two watchdog circuits of the PCA157/147 and the extension housing ..C45 are connected with an extension cable. Via the watchdog circuit, correct user program execution can be monitored reliably and, if a malfunction occurs, effective safety measures can be taken.

The watchdog relay remains excited (contact 5 and 6 closed) as long as address 255 receives a square-wave signal of  $\geq 5\text{Hz}$ . This signal is generated easily with the C00 255 instruction in a circulating monitoring program. Terminals 5 and 6 remain connected (refer to the block circuit diagram for "Power supply") as long as the CPU functions properly in the RUN mode. If a malfunction occurs in the CPU or if any operating mode but RUN is selected, contact 5 and 6 opens and the WD warning lamp is illuminated.

The following safety circuit is recommended (factory setting of watchdog jumper(s)), where the WD-contact 5 interrupts the power supply of the PLC (as well as of the extension housing ..C45) in case of drop of a WD-relay. The CPU provides resetting of the outputs. The breaking capacity of WD-contacts 5, 6 and 7 is 1.5A, 48VAC or DC. The WD-contact is therefore not to be used for direct switching of the total output current.



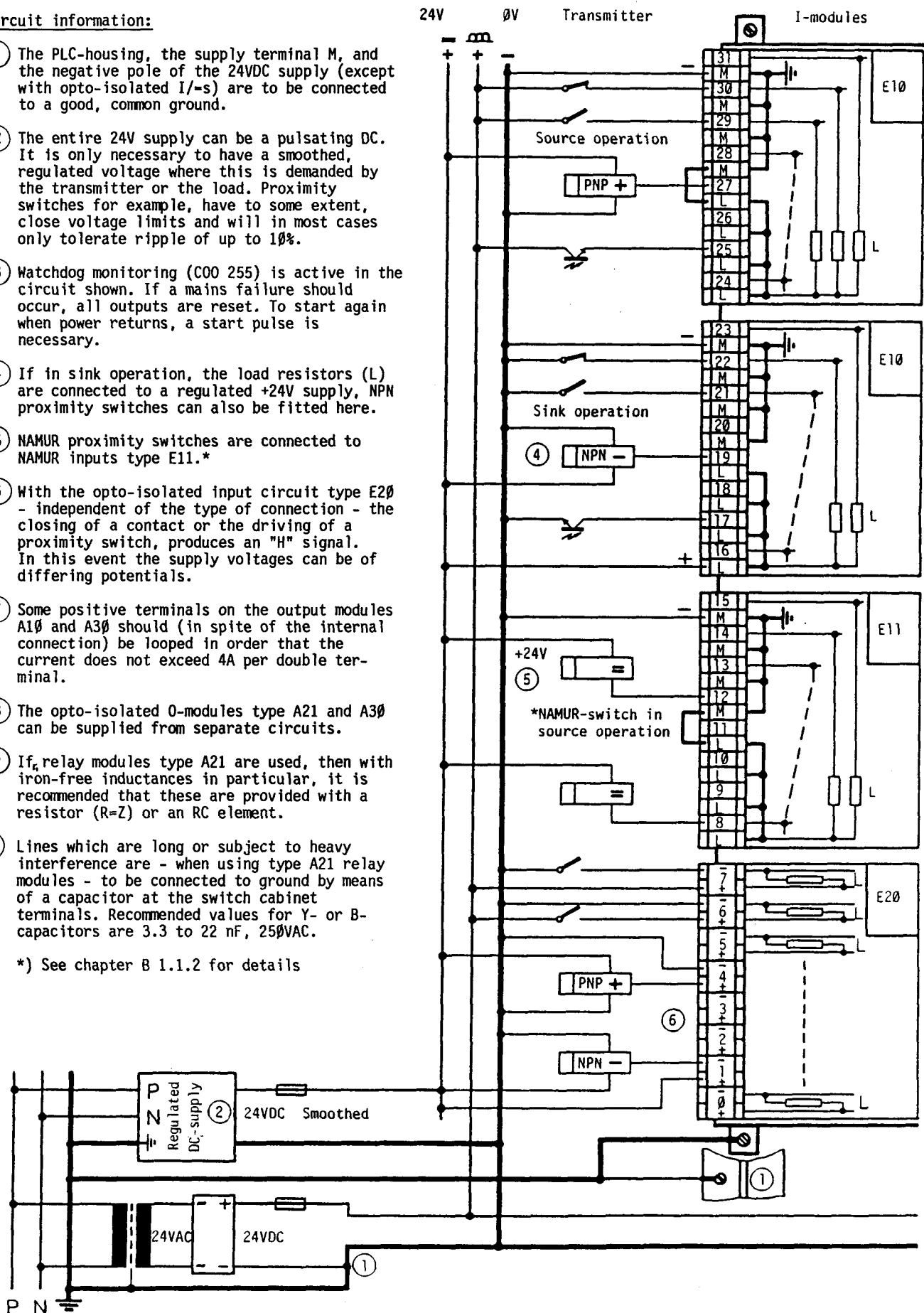


Notes:

**Circuit information:**

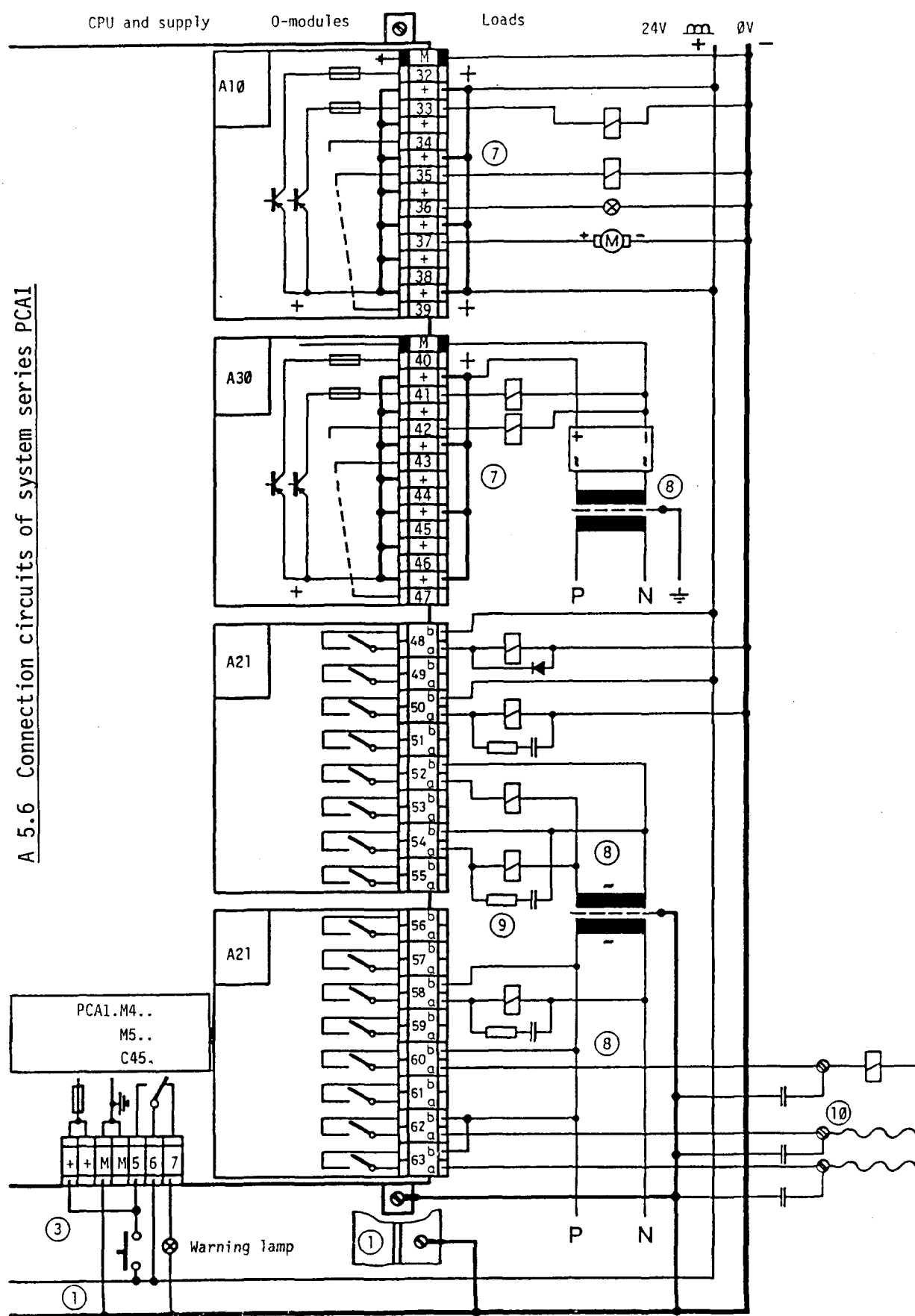
- ① The PLC-housing, the supply terminal M, and the negative pole of the 24VDC supply (except with opto-isolated I/s) are to be connected to a good, common ground.
- ② The entire 24V supply can be a pulsating DC. It is only necessary to have a smoothed, regulated voltage where this is demanded by the transmitter or the load. Proximity switches for example, have to some extent, close voltage limits and will in most cases only tolerate ripple of up to 10%.
- ③ Watchdog monitoring (C00 255) is active in the circuit shown. If a mains failure should occur, all outputs are reset. To start again when power returns, a start pulse is necessary.
- ④ If in sink operation, the load resistors (L) are connected to a regulated +24V supply, NPN proximity switches can also be fitted here.
- ⑤ NAMUR proximity switches are connected to NAMUR inputs type E11.\*
- ⑥ With the opto-isolated input circuit type E20 - independent of the type of connection - the closing of a contact or the driving of a proximity switch, produces an "H" signal. In this event the supply voltages can be of differing potentials.
- ⑦ Some positive terminals on the output modules A10 and A30 should (in spite of the internal connection) be looped in order that the current does not exceed 4A per double terminal.
- ⑧ The opto-isolated O-modules type A21 and A30 can be supplied from separate circuits.
- ⑨ If relay modules type A21 are used, then with iron-free inductances in particular, it is recommended that these are provided with a resistor (R=Z) or an RC element.
- ⑩ Lines which are long or subject to heavy interference are - when using type A21 relay modules - to be connected to ground by means of a capacitor at the switch cabinet terminals. Recommended values for Y- or B-capacitors are 3.3 to 22 nF, 250VAC.

\*) See chapter B 1.1.2 for details





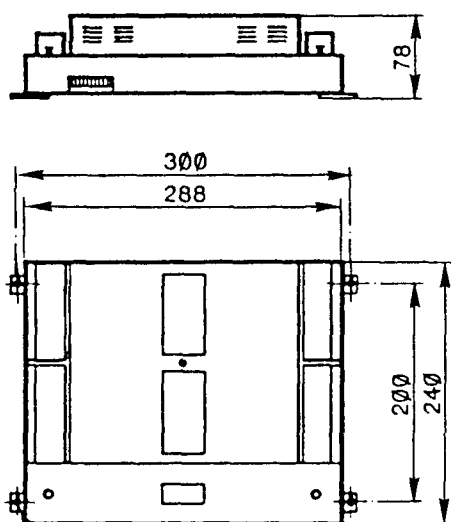
A 5.6 Connection circuits of system series PCA1



### A 5.7 Dimensions of system series PCA1

Small housing  
for 4 I/O modules

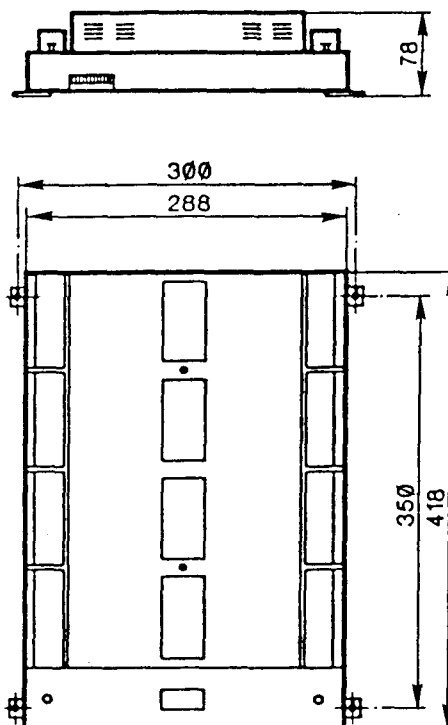
max. 32 or 56 I+O



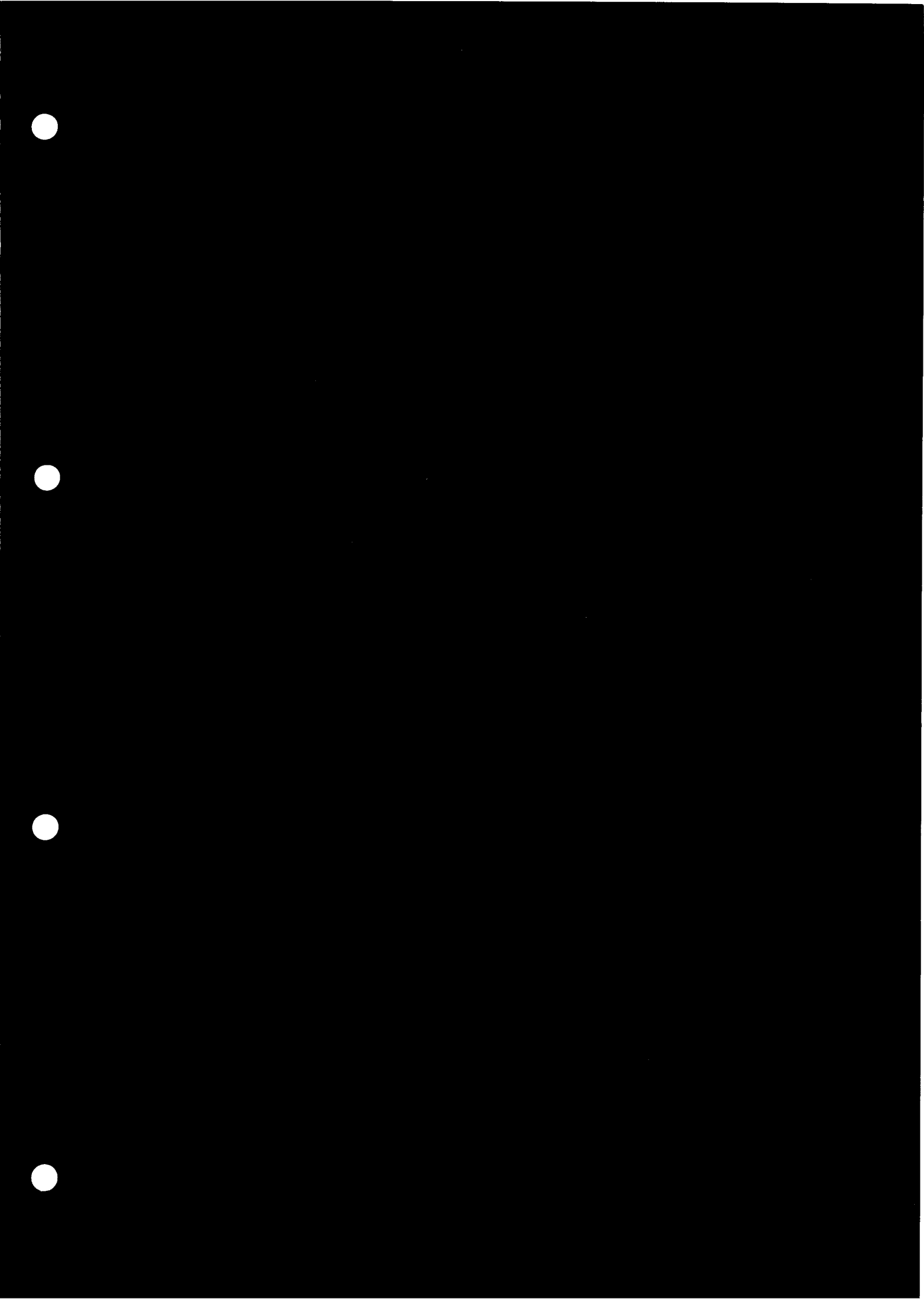
for cheese-head screws M4

Large housing  
for 8 I/O modules

max. 64 or 112 I+O



System type	Basic module, CPU incl. housing	System type	Basic module, CPU incl. housing
PCA141	PCA1.M41	PCA147	PCA1.M47
PCA151	PCA1.M51	PCA156	PCA1.M56
		PCA157	PCA1.M57 + PCA1.C45



**Part B**      **Input/output modules as well as  
additional and display modules**

**Chapter B 1**    **Plug-in input/output modules  
(pluggable onto basic modules)**

**Chapter B 2**    **Programming units, additional units  
and accessories**

## B 1 Plug-in input/output modules

### B 1.1 I+O modules of series PCA1

#### - Modules with 8 digital inputs

PCA1.E10 - electrically connected,  
24V- smoothed or pulsating,  
Input current: 10mA

PCA1.E11 - for NAMUR proximity switch,  
24V- smoothed  
Input current: 0...6mA

PCA1.E20 - opto-isolated,  
24V- smoothed or pulsating,  
Input current: 12mA

PCA1.E50 - 110...240VAC, opto-isolated  
Input current: 10mA, 220VAC

#### - Modules with 8 digital outputs

PCA1.A10 - 5...36VDC electrically connected,  
1(2)A, positive switching

PCA1.A21 - 250VAC/3A, opto-isolated,  
output with relay contacts

PCA1.A30 - 5...36VDC, opto-isolated,  
1(2)A, positive switching

PCA1.A50 - 24...240VAC/1A opto-isolated, Triac

#### - Combined digital input/output modules

PCA1.B10 - 4 inputs 24VDC smoothed or pulsating, electrically connected,  
4 outputs 24VDC, 1(2)A electrically connected, positive switching

PCA1.B80 - 8 inputs, 24VDC smoothed or pulsating, electrically connected  
6 outputs, 8...32VDC, 5mA...0.5A positive switching,  
smoothed and short-circuit protected

PCA1.B90 - 8 inputs 24VDC smoothed or pulsating, electrically connected,  
6 outputs 24VDC, 0.5A electrically connected, positive switching

#### - Combined date-time and input module

PCA1.E40 - Date-time with power reserve  
7 digital inputs 24VDC smoothed or pulsating,  
electrically connected  
Input current: 10mA

- Analog input/output modules

PCA1.W1.. - 6 input channels of 8 bits each,  $0 \dots 5V$  ( $0 \dots 10V$  bzw.  $0 \dots 20mA$ ) electrically connected  
 $0 \dots 2$  output channels of 7 bits each,  $0 \dots 10V$  ( $0 \dots 2.56V$ ) electrically connected

PCA1.W2.. - 2 or 4 analog output channels of 12 bits  
 $0 \dots 10V$  ( $0 \dots 5V$ ,  $-5 \dots 5V$ ,  $-10 \dots 10V$ )

PCA1.W3.. - 4 input channels of 12 bits ( $0 \dots 10V$ ,  $-5 \dots 5V$ ,  $-10 \dots 10V$ )  
 $0$  or 2 output channels of 12 bits  $0 \dots 10V$  ( $0 \dots 5V$ ,  $-5 \dots 5V$ ,  $-10 \dots 10V$ )

PCA1.W40 - 6 input channels of 8 bits for PT 100 temperature sensor for sensors with 2, 3 or 4 conductors

- Preselector modules for input of numerical values

PCA1.F11 - for direct selection of 4 two-digit BCD-preselector switches

PCA1.F12 - for direct selection of 8 two-digit BCD-preselector switches

- Data line switching module with conversion  $20mA/RS 232c$

PCA1.F21 - for 1 interface with conversion  $20mA/RS 232c$

PCA1.F22 - for 2 interfaces with conversion  $20mA/RS 232c$

- Counter module up to  $10kHz$

PCA1.H1.. - Counter, frequency generator and frequency measurement

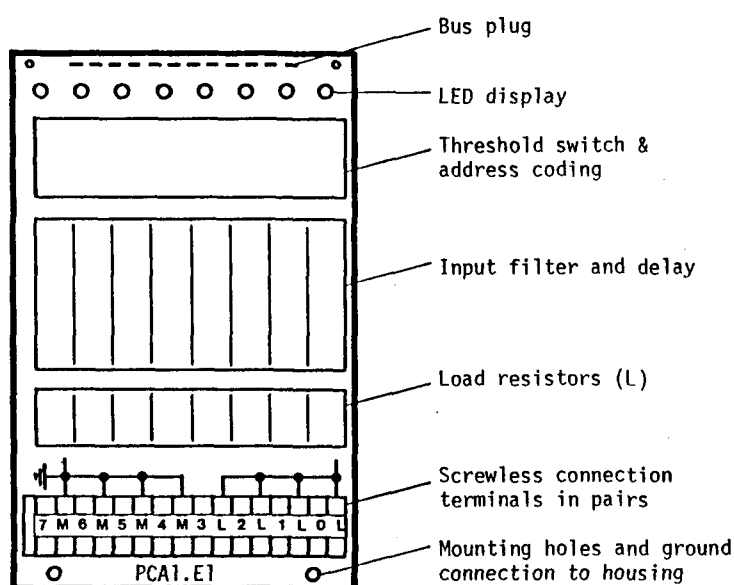
- Internal power consumption of the PCA1 modules

### B 1.1.1 Type PCA1.E1Ø Electrically connected input module

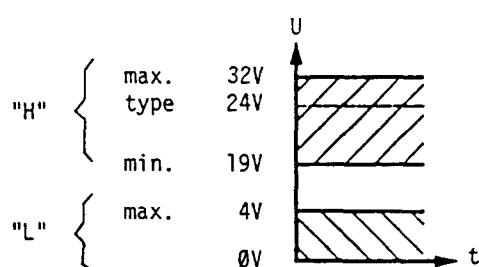
#### Technical data

Number of inputs per module	8, electrically connected
Input voltage $V_{in}$	24VDC, smoothed or pulsating
Input current at 24VDC	10mA
Input delay (typical)	8ms

#### Presentation and terminal layout



#### Definition of input voltages



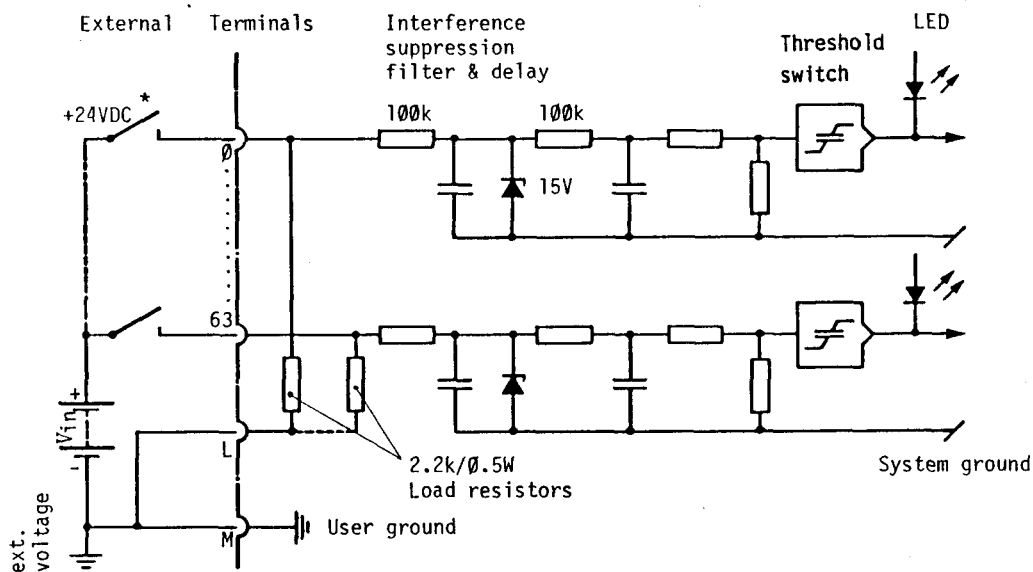
Because of the input delay of 8ms, pulsating DC is adequate as external supply voltage.

Connection terminals for the I+O modules: By depressing the grey rib with a screwdriver, the screwless terminal is opened for one wire of max. 1.5mm<sup>2</sup>. Two terminals for the same connection are located opposite one another to facilitate installation of jumpers when needed. Plug-in connectors on request.

### Input circuit

This module can be used either in source or sink operation, depending on the external circuitry.

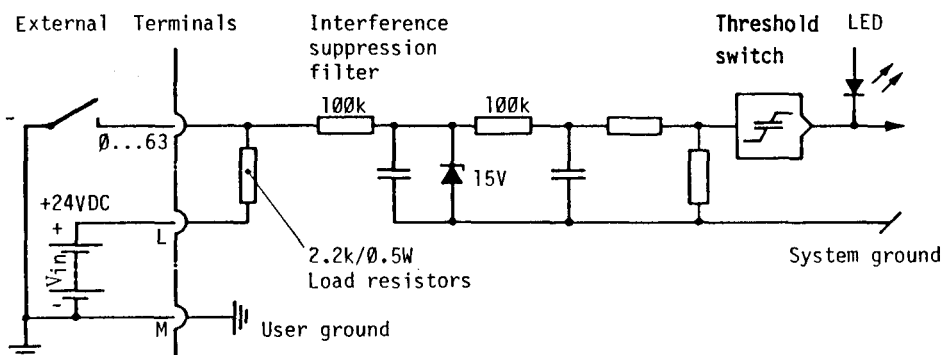
#### Source operation or positive logic (normal case):



\*) PCA1.E10 is also suitable for NAMUR proximity switches which can carry a current of 10mA at 24VDC and 2.2kΩ.

Switch closed (positive at input): "H" ≙ LED ON  
 Switch open (negative at input): "L" ≙ LED OFF

#### Sink operation or negative logic:



Switch closed (negative at input): "L" ≙ LED OFF  
 Switch open (positive at input): "H" ≙ LED ON



### B 1.1.2 Type PCA1.E11 Input module for NAMUR proximity switches

On the basis of the object distance NAMUR proximity switches give a current of  $0 \dots 6\text{mA}$ . To take these special conditions into consideration, two resistors are changed per input in the NAMUR version as opposed to the standard PCA1.E10.

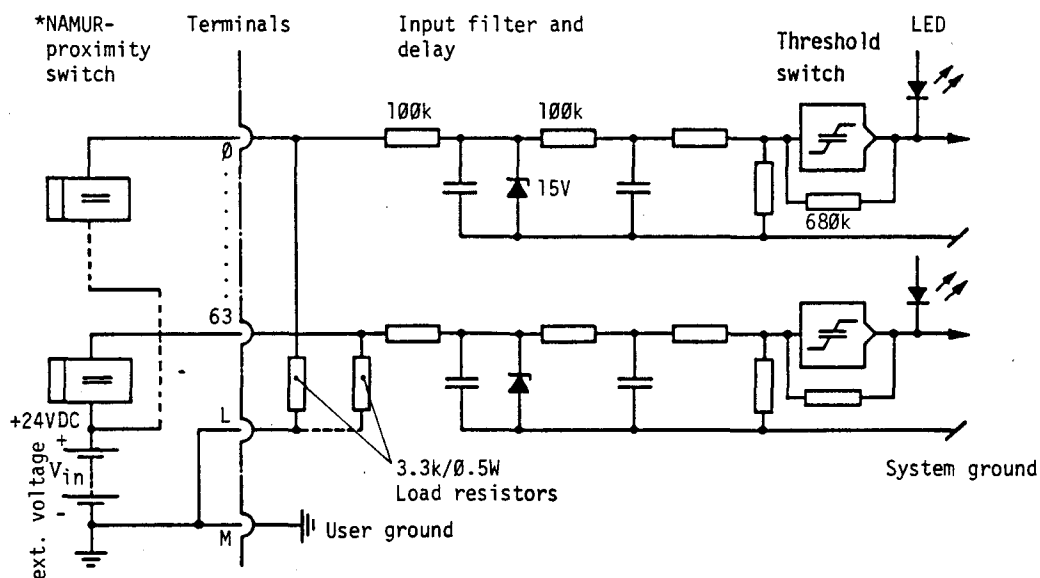
#### Technical data

Number of inputs per module 8, electrically connected

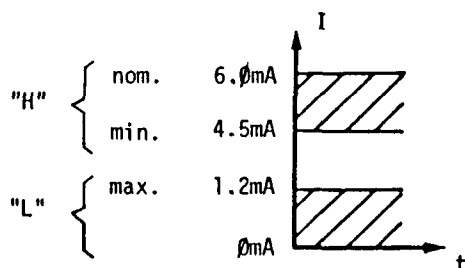
Voltage source in series with NAMUR proximity switches  $V_{in}$  24VDC smoothed

Input delay (typical) 8ms

#### Input circuit



#### Definition of input current



"H": LED ON = proximity switch de-energized

"L": LED OFF = proximity switch energized

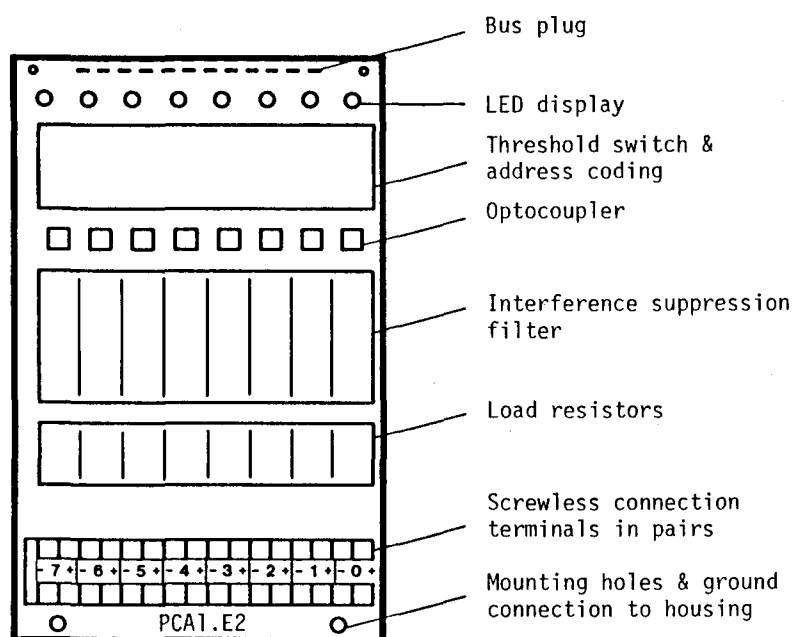
\*) PCA1.E11 is suitable for NAMUR proximity switches which can carry a current of 6mA at 24VDC and 3.3k $\Omega$ .

### B 1.1.3 Type PCA1.E20 Opto-isolated input module

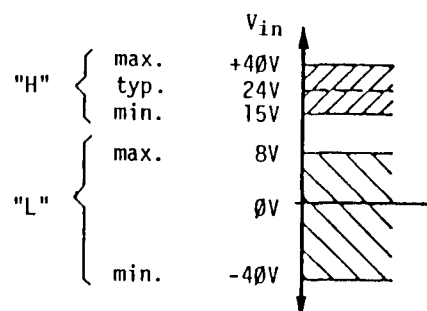
#### Technical data

Number of inputs per module	8, electrically isolated between process, CPU and mutually
Input voltage $V_{in}$	24VDC, smoothed or pulsating
Input current at 24VDC	12mA
Input delay (typical)	7ms
Dielectric strength of optocouplers	min. 2000V

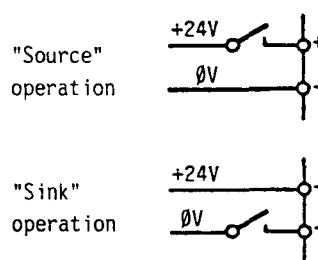
#### Presentation and terminal layout



#### Definition of input voltage $V_{in}$



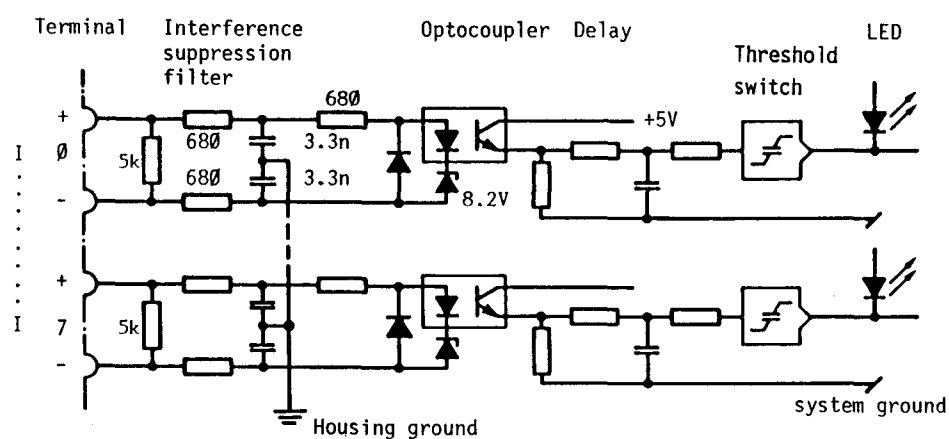
#### Input circuit operating modes



Pulsating DC is adequate as supply voltage because of 7ms input delay.

The LED lights in both cases when the input contact is closed.

## Input circuit



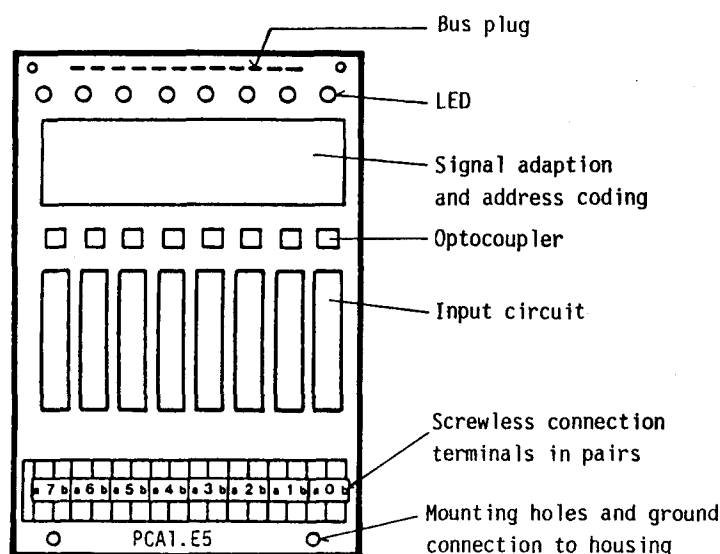
"H"  $\hat{=}$  LED ON  $\hat{=}$  voltage at input  
 "L"  $\hat{=}$  LED OFF  $\hat{=}$  no voltage at input

### B 1.1.4 Type PCA1.E50 Opto-isolated input module for VAC

#### Technical data

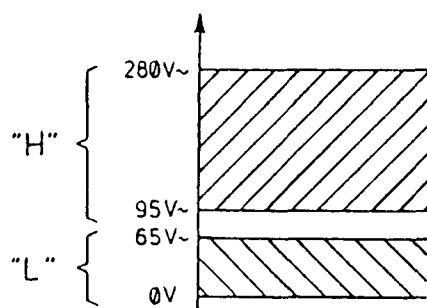
Number of inputs per module	8, galvanically isolated
Input voltage range	95...280VAC eff. (110...240VAC nom.)
Input voltage at 220VAC	10mA
Overvoltage max.	1500V/10µs 500V/ 3ms
Input delay (typical)	typ. 15ms
Isolation voltage of optocoupler	2500V eff.
Isolation resistance of optocoupler	100MΩ

#### Presentation and terminal layout

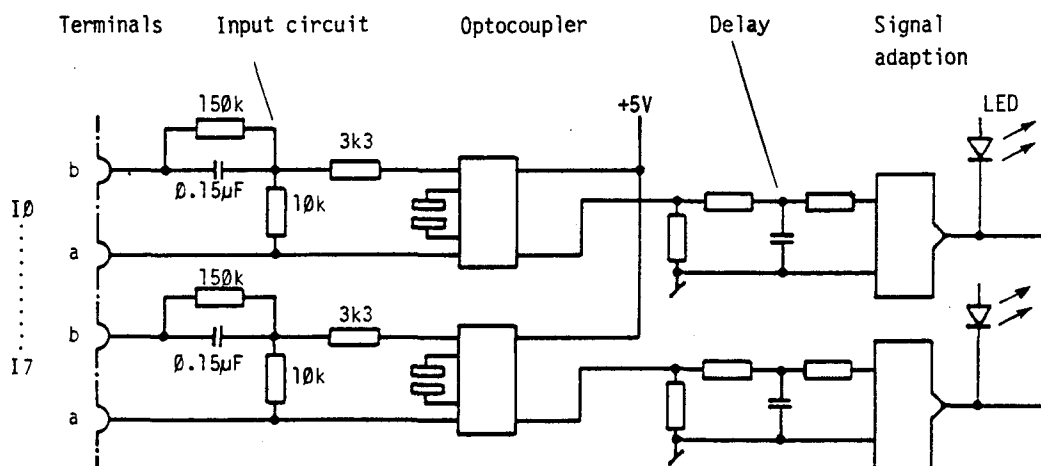


For opto-isolation very long lasting (>100'000h) optocouplers are used. This results from the use of threshold switches in the diode circuit of the optocoupler.

#### Definition of input voltage



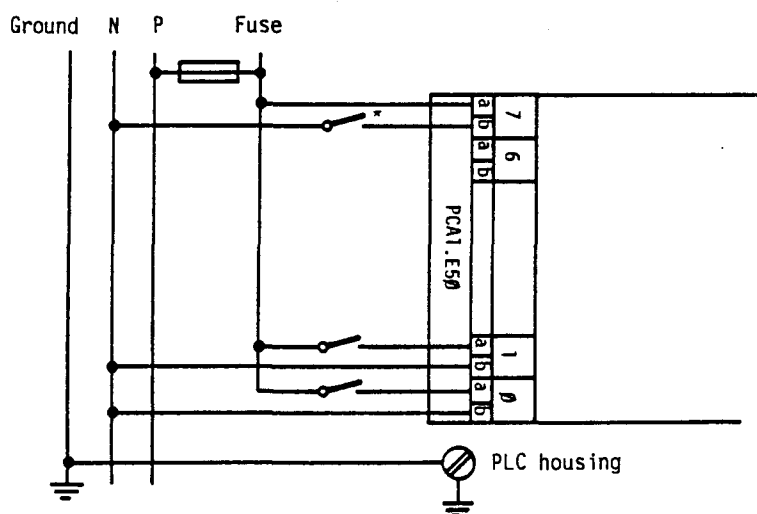
## Input circuit



## Warning

For reasons of protection of data transmission lines, displays and user input elements use low voltage material when connecting low voltage on the PLC.

All connections of an E50-module are to be connected on the same circuit; that means at one point in such a way that they are all protected against one AC-phase by one fuse.



\*) The neutral conductor is only to be interrupted if local regulations are not violated.

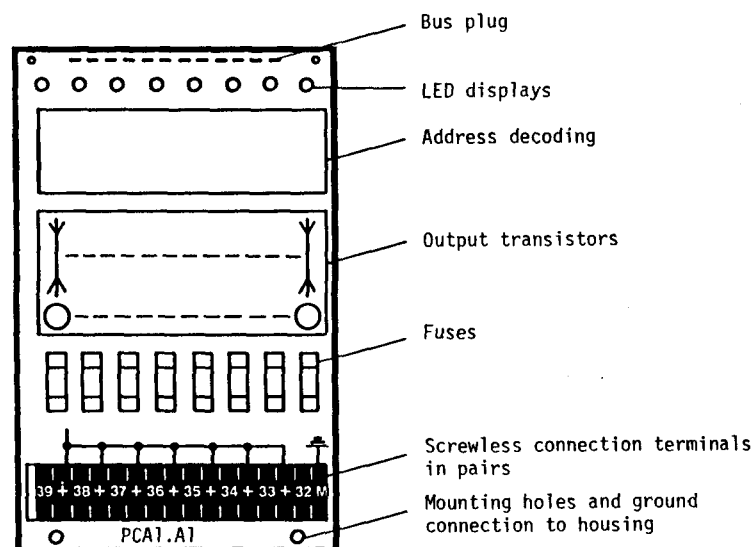
### B 1.1.5 Type PCA1.A1Ø Electrically connected output module for 1(2)A

#### Technical data

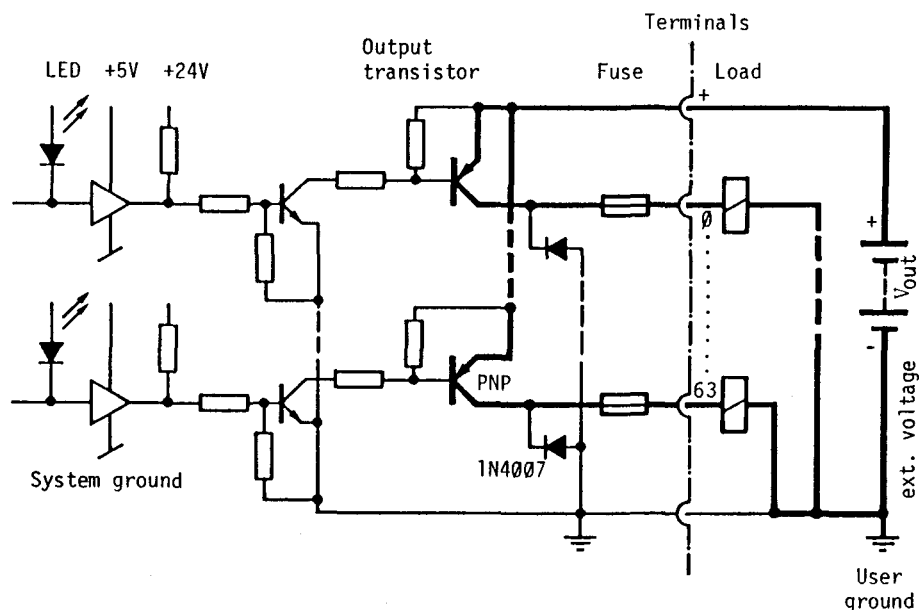
Number of outputs per module	8, electrically connected
Output current	5mA - 1A (2A)* When operated at 5...25VDC, the load resistance should be at least 24Ω.
Short-circuit protection	1.6A quick-acting fuse
Operating mode	Source operating positive switching
Total current	See diagram
Voltage range $V_{out}$	5...36VDC, smoothed or pulsating
Voltage drop	max. 1.5V at $I = 1A$
Output delay (typical)	10μs (With an inductive load, the turn-off delay is greater due to the protective diode.)

\* Two outputs per module can carry a load of 2A each if the total current does not exceed that shown in the diagram. For such outputs, a quick-acting 2.5A fuse should be used. Please note however, that the voltage drop at the terminals is approx. 2.5V with a load of 2A.

#### Presentation and terminal layout



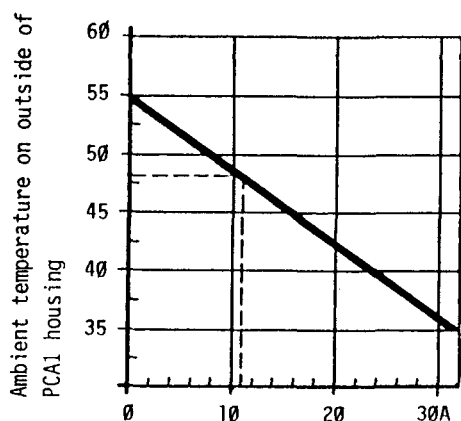
## Output circuit



Output conducting (set)       $\hat{=}$  LED ON  
 Output non-conductive (reset)       $\hat{=}$  LED OFF

Max. permissible total current for complete PCA1 (housing for 8 I/O modules)

The average (thermal) continuous total current is relevant.



Mean continuous total current  
 for all outputs of a PCA1

(Housing for 8 I/O modules)

Example: 40 outputs assigned  
 $V_{out} = 24V$

I mean

8 multiplex outputs at 10mA (10%ED)	0.01A
6 display lamps at 2W (100%ED)	0.50A
16 valves at 24W (40%ED)	6.40A
2 valves at 48W (25%ED)	1.00A
8 control relays at 8W (100%ED)	2.70A

Mean total current      10.61A  
 =====

Permissible ambient temperature 48°C  
 =====

### Note:

In spite of the internal loops of the positive, several terminals are to be used since the current is not to exceed 4A per double terminal.

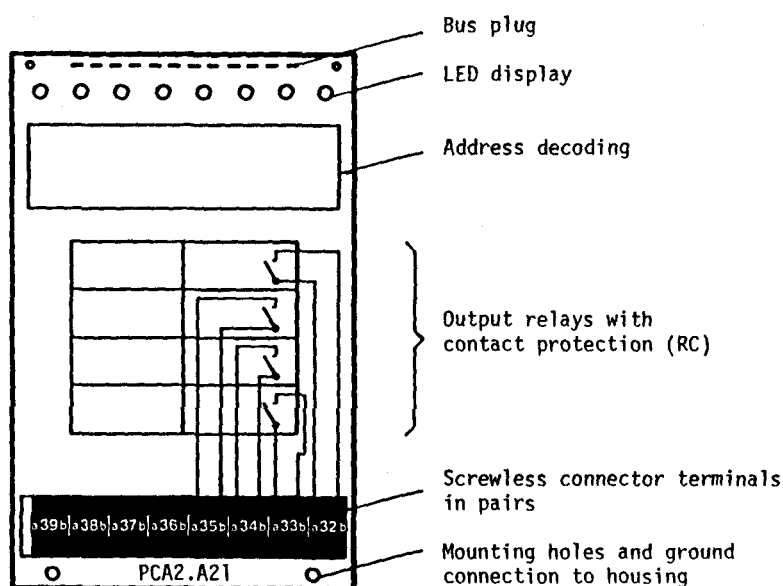
### B 1.1.6 Type PCA1.A21 Output module with relay contacts

#### Technical data

Number of outputs per module	8, galvanically isolated normally-open contacts
Power rating	3A, 250VAC AC1 1A, 250VAC AC11 (3A, 24VDC DC1)* (1A, 24VDC DC11)*
Contact protection	3.3nF mit 33Ω
Contact life (AC1)	3A, 220VAC 0.1 mio. switching cycles 1.5A, 220VAC 0.5 mio. switching cycles 0.3A, 220VAC 5 mio. switching cycles

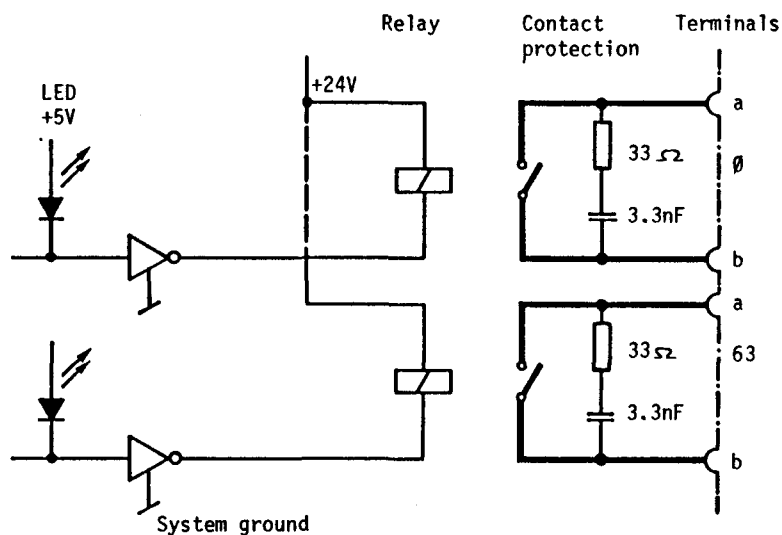
\*) Transistor outputs A10 or A30 should be used when switching DC for reasons associated with contact life and to ensure positive switching.

#### Presentation and terminal layout





## Output circuit



## Important

For safety reasons however, it is recommended that extra-low voltages (up to 50V) and low voltages (51 to 250V) should not be used on the same card, or that one channel should be left unused between them.

If highly inductive, 220VAC loads are to be switched (e.g. control relays or valves), it is recommended that an additional spark protection be connected across the load or the contact. Thus, arcing to the coil circuit can be prevented successfully. The following values are recommended:

$$R (\Omega) \approx \text{load } Z (\Omega)$$

$$C (\mu\text{F}) \approx \text{current (A)}$$

For DC-voltages the transistor output modules are recommended.

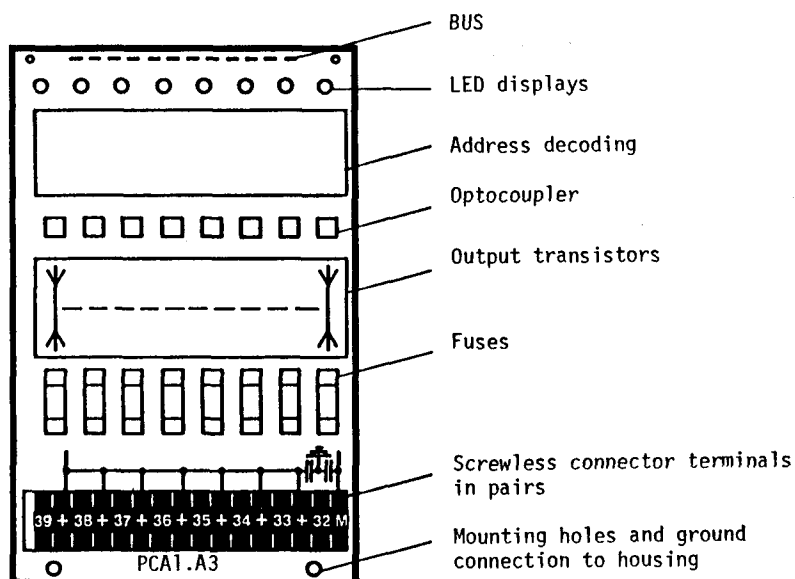
### B 1.1.7 Type PCA1.A3Ø Opto-isolated output module for 1(2)A

#### Technical data

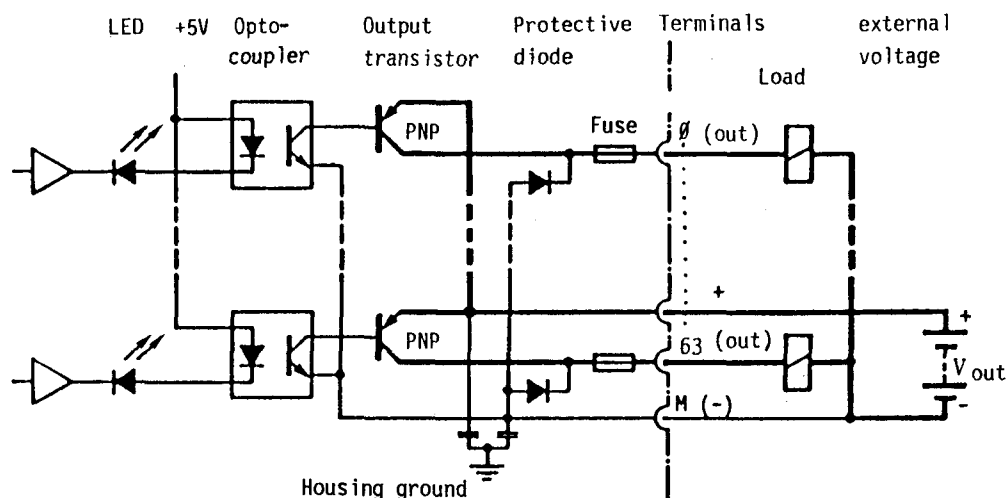
Number of outputs per module	8, galvanically isolated between process and CPU
Output current	5mA - 1A (2A) * When operated at 5...24VDC, the load resistance should be at least 24Ω.
Operating mode	Source operation (pos. switching voltage)
Short-circuit protection	1.6A quick-acting fuse
Total current	refer to graph
Voltage range $V_{out}$	5...36VDC
Voltage drop	max. 1.5V at $I = 1A$
Isolation voltage of optocouplers	2000V
Output delay (typical)	500μs (i.e. approx. 7 cycles at 70μs)

\*) Two outputs per module can carry a load 2A each if the total current does not exceed that shown in the figure. For such outputs, a quick-acting 2.5A fuse should be used. Please note, however, that the voltage drop at the terminals is approx. 2.5V with a load of 2A.

#### Presentation and terminal layout



## Output circuit



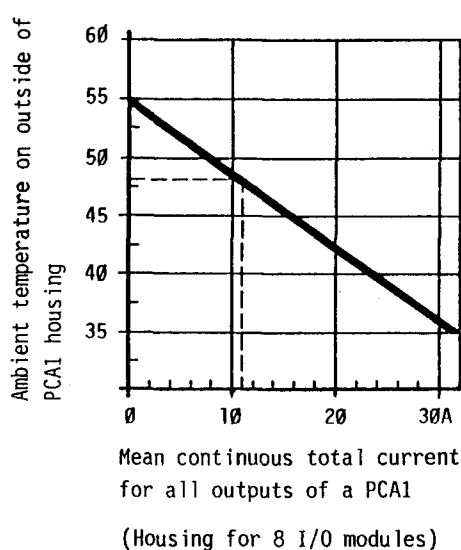
Output conducting (set)       $\hat{=}$  LED ON  
 Output non-conductive (reset)       $\hat{=}$  LED OFF

### Note

Terminal M is to be connected to the negative of the external voltage. It is used for the internal supply of the module. Accordingly the positive terminal is omitted on the first output per card (in the example above on A0). However because the positive terminals are looped, connection is via one of the remaining positive terminals.

### Max. permissible total current for the entire PCA1 (housing for 8 I/O modules)

The average (thermal) continuous total current is relevant.



Example: (24V)	I mean
8 valves at 18W 100%ED	6.0A
4 valves at 48W 30%ED	2.4A
4 control relays at 12W 100%ED	2.0A
Mean total current	10.4A
Max. ambient temperature	48°C

### Note:

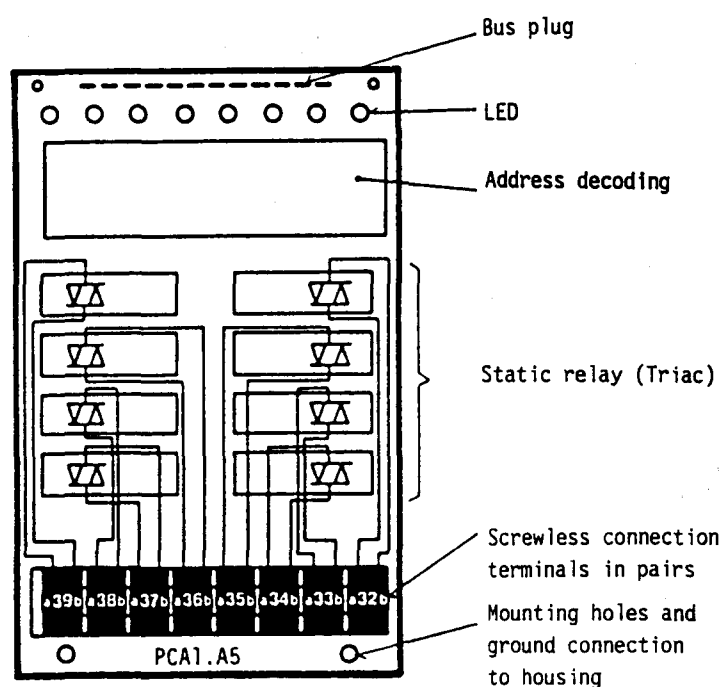
In spite of the internal loops of the positive, several terminals are to be used, since the current is not to exceed 4A per double terminal.

### B 1.1.8 Type PCA1.A50 Output module for VAC with static relay (Triac)

#### Technical data

Number of outputs per module	8, galvanically isolated
Output voltage range	24...280VAC eff. (24...240VAC nom.)
Output current nom.	1A eff.
Output current min.	60mA eff.*
Overcurrent max.	28A peaks 20ms, non-repetitive 7A peaks 1s, non-repetitive
Overvoltage max.	600V peaks, non-repetitive
Voltage drop max.	1.4V
Isolation voltage of optocoupler	2500V eff.
Isolation resistance of optocoupler	100MΩ

#### Presentation and terminal layout



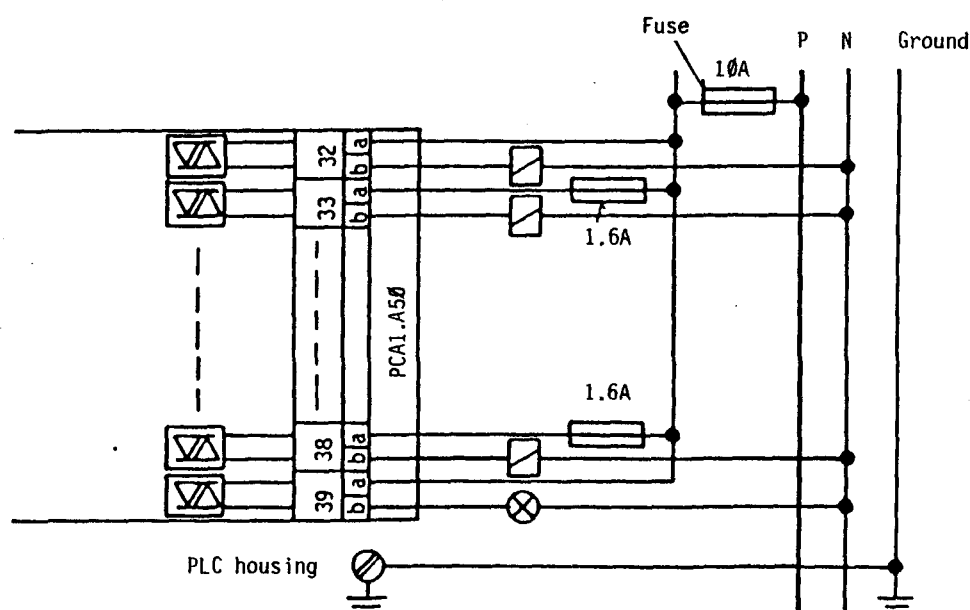
\*) Important: Due to minimal current of 60mA, for example contactors with a hold-power of <13VA have to be provided by an adequate shunt over the coil!

The output module PCA1.A50 with static relay can be used to control resistor loads (lamps, heating equipment) and to control inductive loads (motors, valves, contactors). The outputs are opto-isolated against the CPU and against one another. The integrated zero-switches who set load at the zero-passage, have a very positive effect on lifetime, number of switch operations and interference suppression.

### Warning

For reasons of protection of data transmission lines, displays and user input elements use low voltage material when connecting low voltage on the PLC.

All connections of an A50-module are to be connected on the same circuit; that means at one point in such a way that they are all protected against one AC-phase by one fuse. Each load circuit may be protected individually by a fuse of max. 1.6A.



### B 1.1.9 Type PCA1.B10 Electrically connected input/output module

The B10 module is a combination of modules E10 and A10. The I/O-division and therefore also the modularity can be reduced to four.

#### Technical data

##### Inputs:

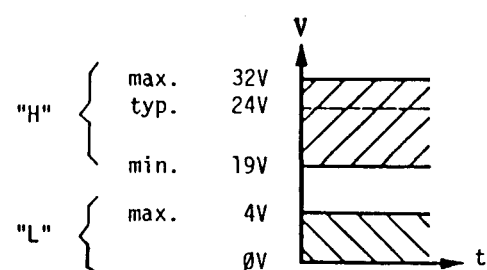
Number of inputs per module	4, electrically connected
Input voltage $V_{in}$	24VDC, smoothed or pulsating
Input current at 24V	10mA
Input delay (typical)	8ms
Operating modes	Source or sink operation, depending on connection

##### Outputs:

Number of outputs per module	4, electrically connected
Output voltage	5mA - 1A (2A) *
	When operated at 5...24V, the load resistance should be at least 24Ω.
Short-circuit protection	1.6A quick-acting fuse
Operating mode	Source operation (pos. switching voltage)
Total current	See diagram for type PCA1.A10
Voltage range $V_{out}$	5...36VDC, smoothed or pulsating
Voltage drop	max. 1.5V at $I = 1A$
Output delay (typical)	10μs (with an inductive load, the turn-off delay is greater due to the protective diode.)

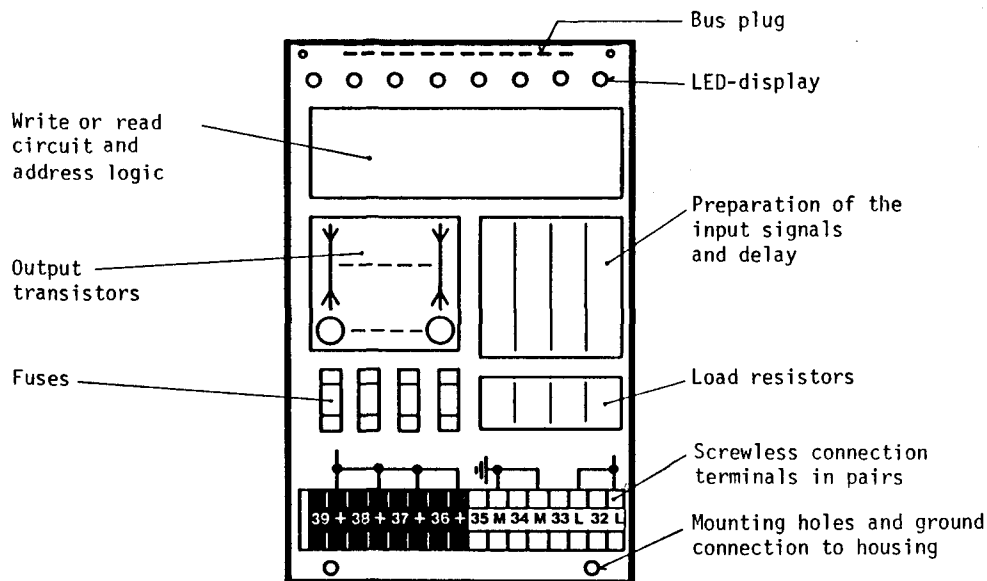
\*) Two outputs per module can carry a load of 2A each if the total current does not exceed that shown in the figure. For such outputs, a quick-acting 2.5A fuse should be used. Please note however, that the voltage drop at the terminals is approx. 2.5V with a load of 2A.

#### Definition of the input voltages



Pulsating DC is adequate as supply voltage because of the 8ms input delay.

## Presentation and terminal layout



## Input/output circuit

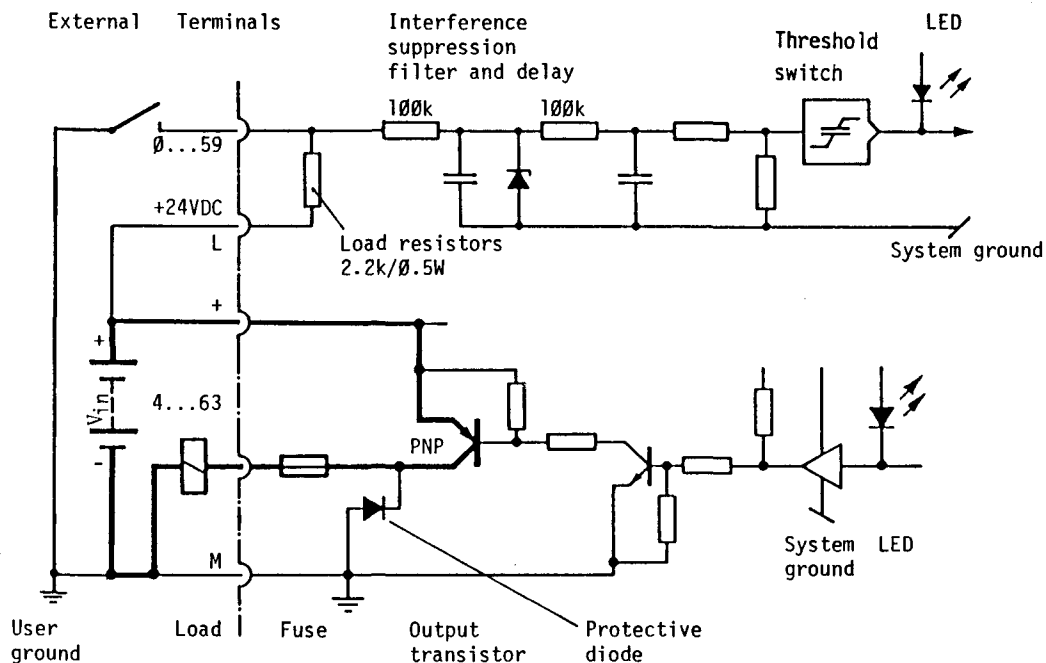
The inputs can be used in either source or sink operation, depending on the external circuitry.

The outputs can only be driven in source operation.

## Inputs in sink operation or negative logic

Switch closed (negative at input) : "L"  $\hat{=}$  LED OFF

Switch open (positive at input) : "H"  $\hat{=}$  LED ON

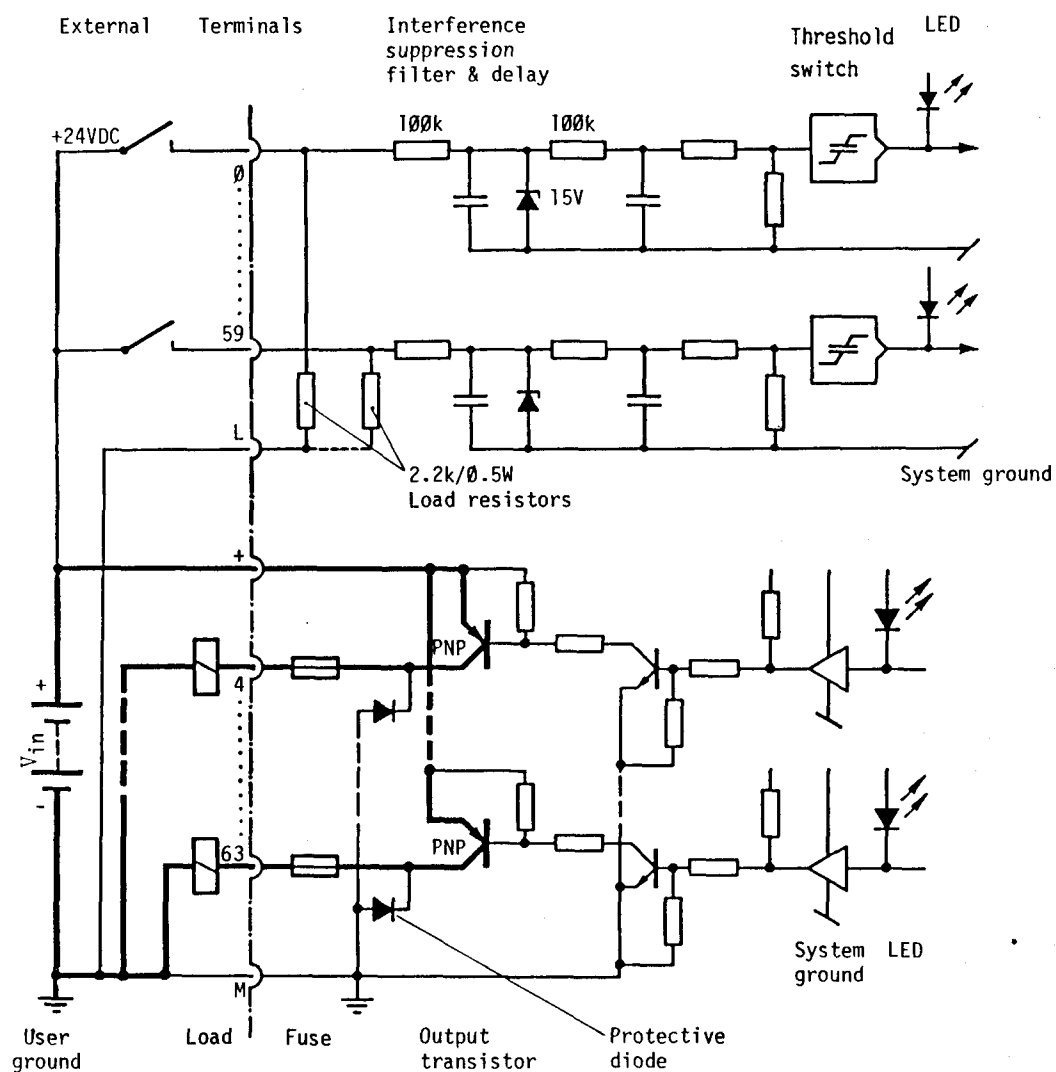


Output conducting (set)  $\hat{=}$  LED ON } Source operation  
 Output non-conductive (reset)  $\hat{=}$  LED OFF }

### Inputs in source operation or positive logic (normal case)

Switch closed (positive at input): "H"  $\hat{=}$  LED ON

Switch open (negative at input) : "L"  $\hat{=}$  LED OFF



Output conducting (set)	$\hat{=}$ LED ON	} Source operation
Output non-conductive (reset)	$\hat{=}$ LED OFF	

Max. permissible total current for complete PCA1 (housing for 8 I/O modules)

Refer to data on PCA1.A10 output module



### B 1.1.10 PCA1.B80 Compact input/output module with short-circuit-protected outputs

The PCA1.B80 module is a compact input/output module similar to the PCA1.B90, but with short-circuit-protected outputs. The inputs and outputs are electrically connected and fed by the same power supply unit. As they use the same addresses, only the instructions OUT, SEO and REO can be used for the outputs. Any interrogation commands refer to the corresponding inputs.

#### Technical data

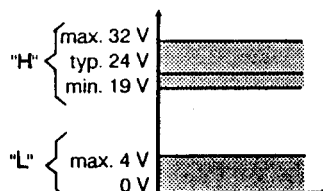
##### Inputs

Number of inputs per module	8, electrically connected
Input voltage $V_{in}$	24VDC, smoothed or pulsating
Input current at $V_{in} = 24V$	10mA
Input delay (typical)	9ms
Operating mode	Source or sink operation

##### Outputs

Number of outputs per module	6, electrically connected
Output current range	5mA - 0.5A In the voltage range 5 - 24VDC the load resistance has to be at least 480.
Operating mode	Source operation
Voltage range $V_{out}$	8 - 32V smoothed
Residual ripple of $V_{out}$	max. 10%
Voltage drop	max. 1.5V at $I = 0.5A$
Output delay (typical)	10μs In case of inductive load, the output delay is greater due to the freewheeling diode.

##### Input voltage



Owing to the input delay of 9ms, pulsating DC-voltage is sufficient for the external power supply (in source operation).

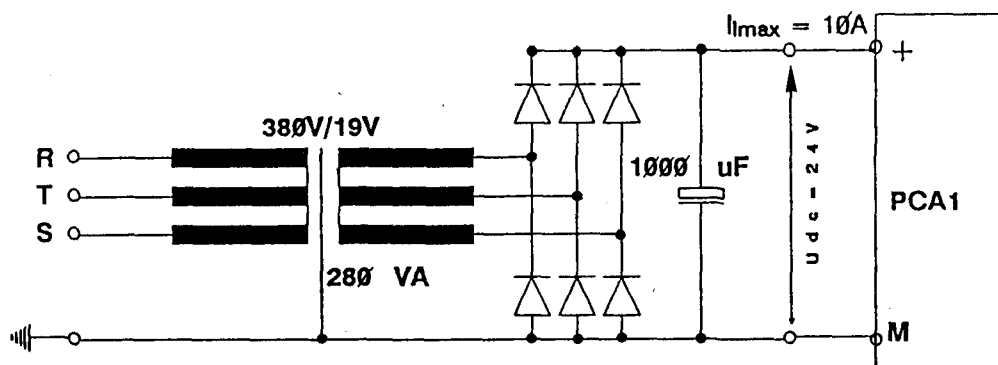
##### What to do in the event of a short-circuit

In a short-circuited load circuit, the output current is limited to 1A. If the short-circuit remains, the output is switched off after 0.5 - 2s. From this moment on, every 0.5s a new attempt is made of switching it on again. When the short-circuit is removed, the output is automatically switched on again.

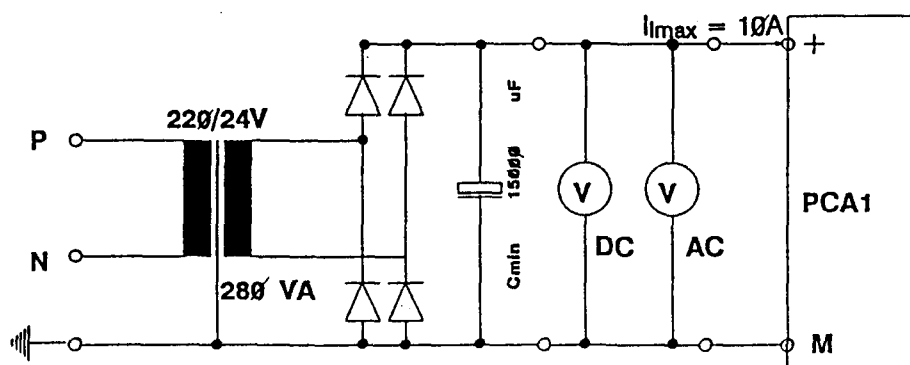
### User power supply of the PCA1 when using the PCA1.B80 module

The short-circuit protection feature makes higher demands on the power supply of the PCA1.B80 module. Therefore, two suggestions will be made in the following with regard to the user power supply.

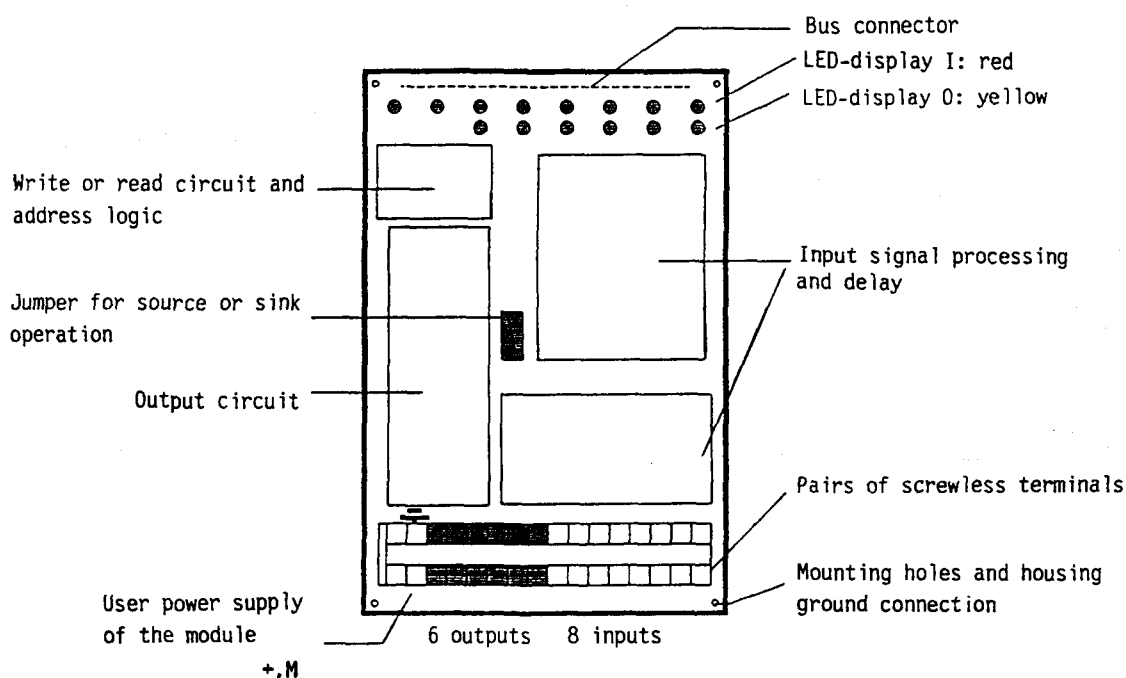
#### When using a 3-phase transformer



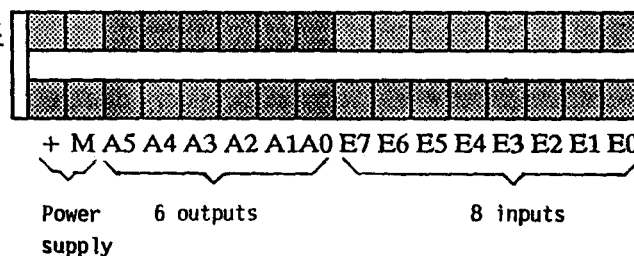
#### When using a 1-phase transformer



### Presentation



### Terminal assignment



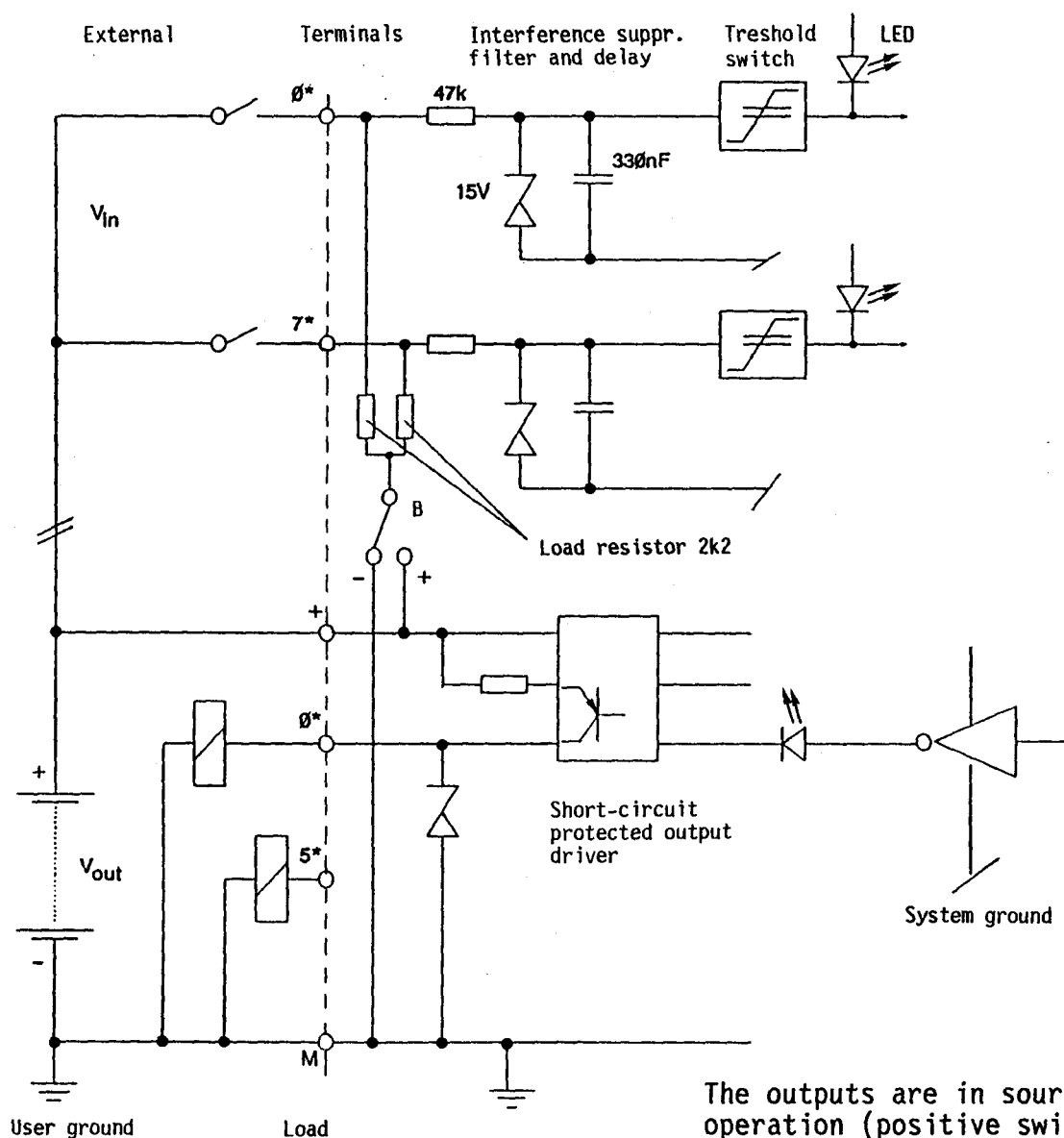
The terminal assignment is valid for basic address 0.

### Electric input and output circuit

Depending on the external circuitry, the inputs can be used in source or sink operation. Outputs can only be used in source operation.

#### Inputs in source operation or positive logic (normal case)

Switch closed (positive at input): "H" = LED ON  
 Switch open (negative at input) : "L" = LED OFF  
 Jumper B is in position "-".



The outputs are in source operation (positive switching)

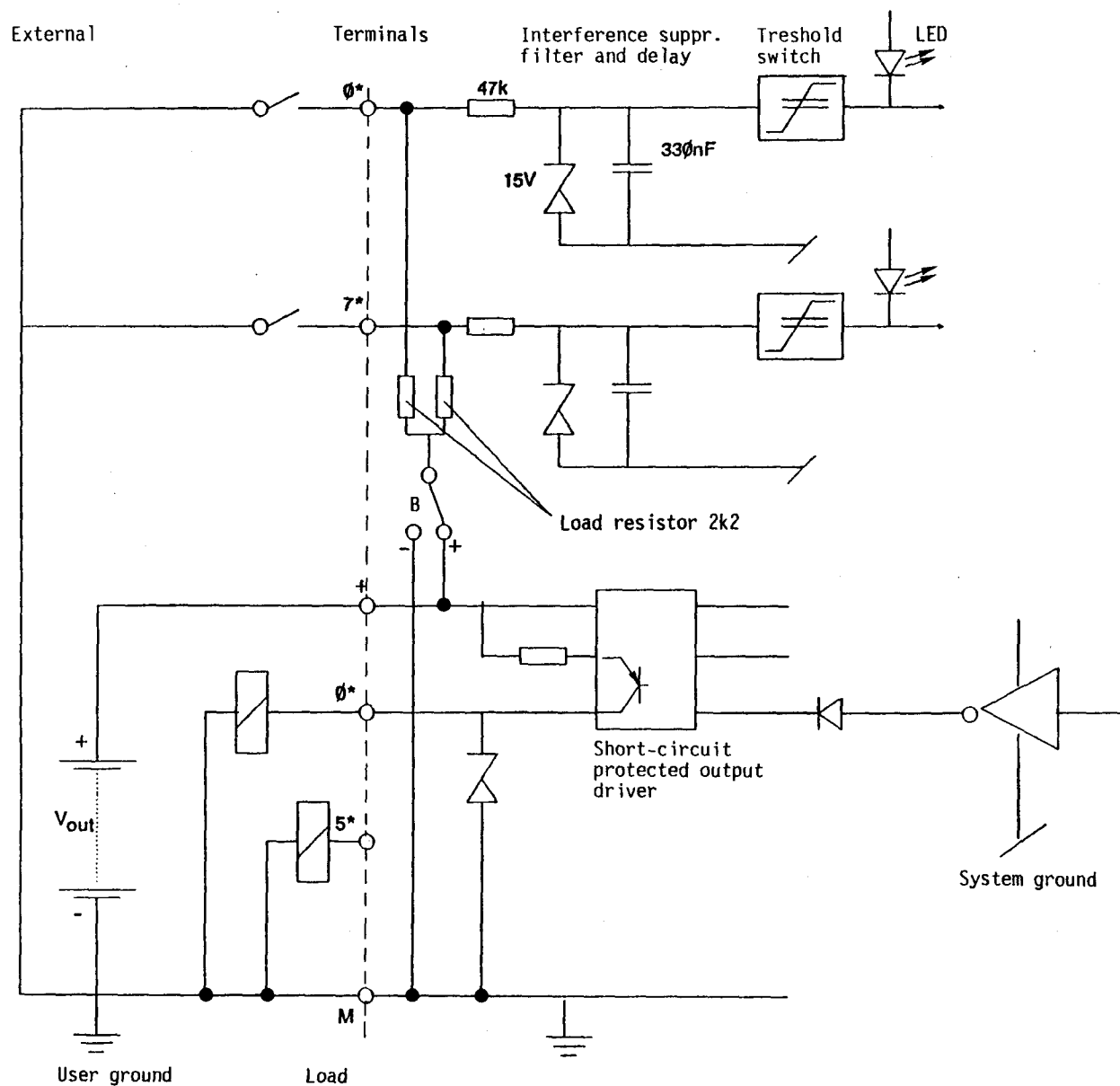
\*) Absolute address = basic address + relative address

$V_{out}$ : smoothed voltage

$V_{in}$ : smoothed or pulsating voltage

### Inputs in sink operation or negative logic

Switch closed (negative at input): "L" = LED OFF  
 Switch open (positive at input) : "H" = LED ON  
 Jumper B is in position "+".



The outputs are in source operation (positive switching)

\*) Absolute address = basic address + relative address

$V_{out}$ : smoothed voltage

### B 1.1.11 Type PCA1.B90 Electrically connected compact I/O module

The I/O capacity of the PCA1 series can be expanded economically to 56 or 112 inputs and outputs through this module. I/O circuits use a common supply voltage and operate in the source mode. Inputs and outputs use the same addresses. Only the three instructions OUT, SEO and REO can be used for outputs. Interrogation commands refer to the respective inputs.

#### Technical data

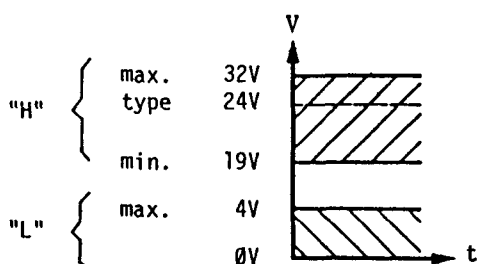
##### Inputs:

Number of inputs per module	8, electrically connected
Input voltage $V_{in}$	24VDC, smoothed or pulsating
Input current at 24V	10mA
Input delay (typical)	9ms
Operating mode	Source operation, sink operation by commuting jumper B

##### Outputs:

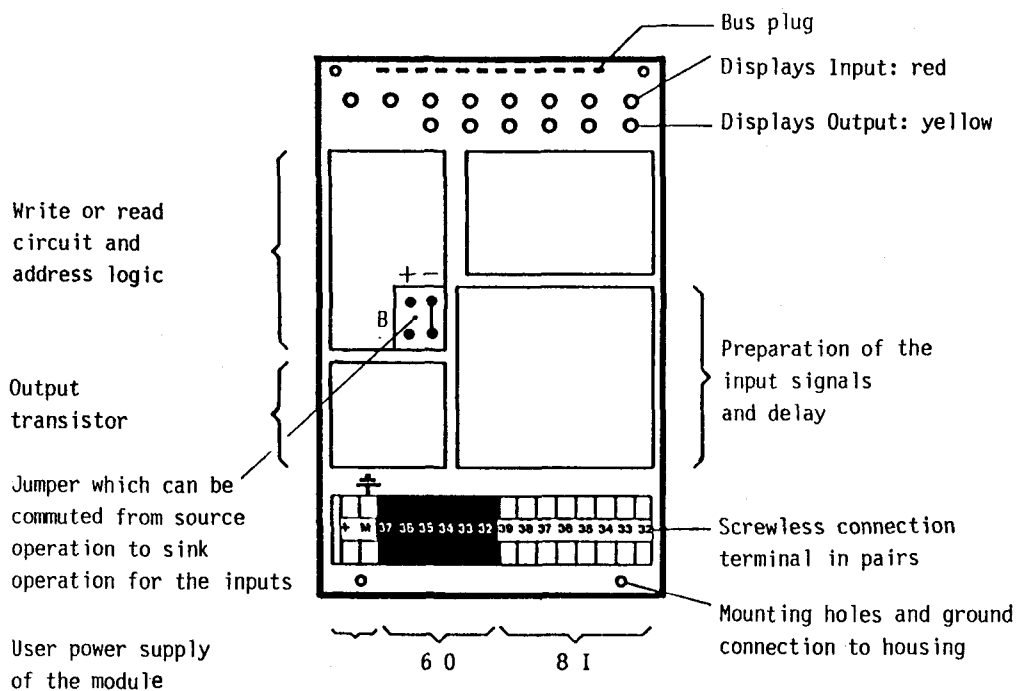
Number of outputs per module	6, electrically connected
Output voltage	5mA - 0.5A When operated at 5...24VDC, the load resistance should be at least 48Ω.
Operating mode	Source operation (positive switching)
Voltage range $V_{out}$	5...36VDC, smoothed or pulsating
Voltage drop	max. 1.5V at $I = 0.5A$
Output delay (typical)	10μs (With an inductive load, the turn-off delay is greater due to the free-wheeling diode.)

#### Definition of the input voltages



Pulsating DC is adequate as supply voltage because of the 9ms input delay.

## Presentation and terminal layout

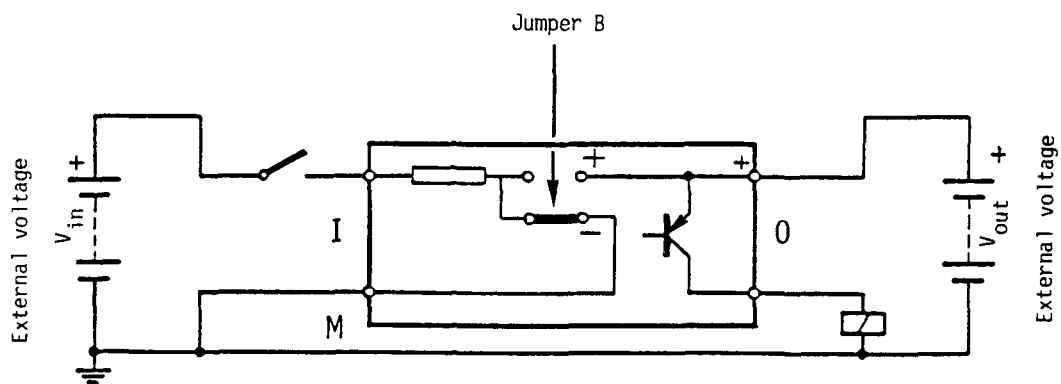


## Input/output circuit

All inputs are switched to source operation (-) (factory setting). The inputs can be switched to sink operation by commuting jumper B to "+".

The outputs may only be used in sink operation.

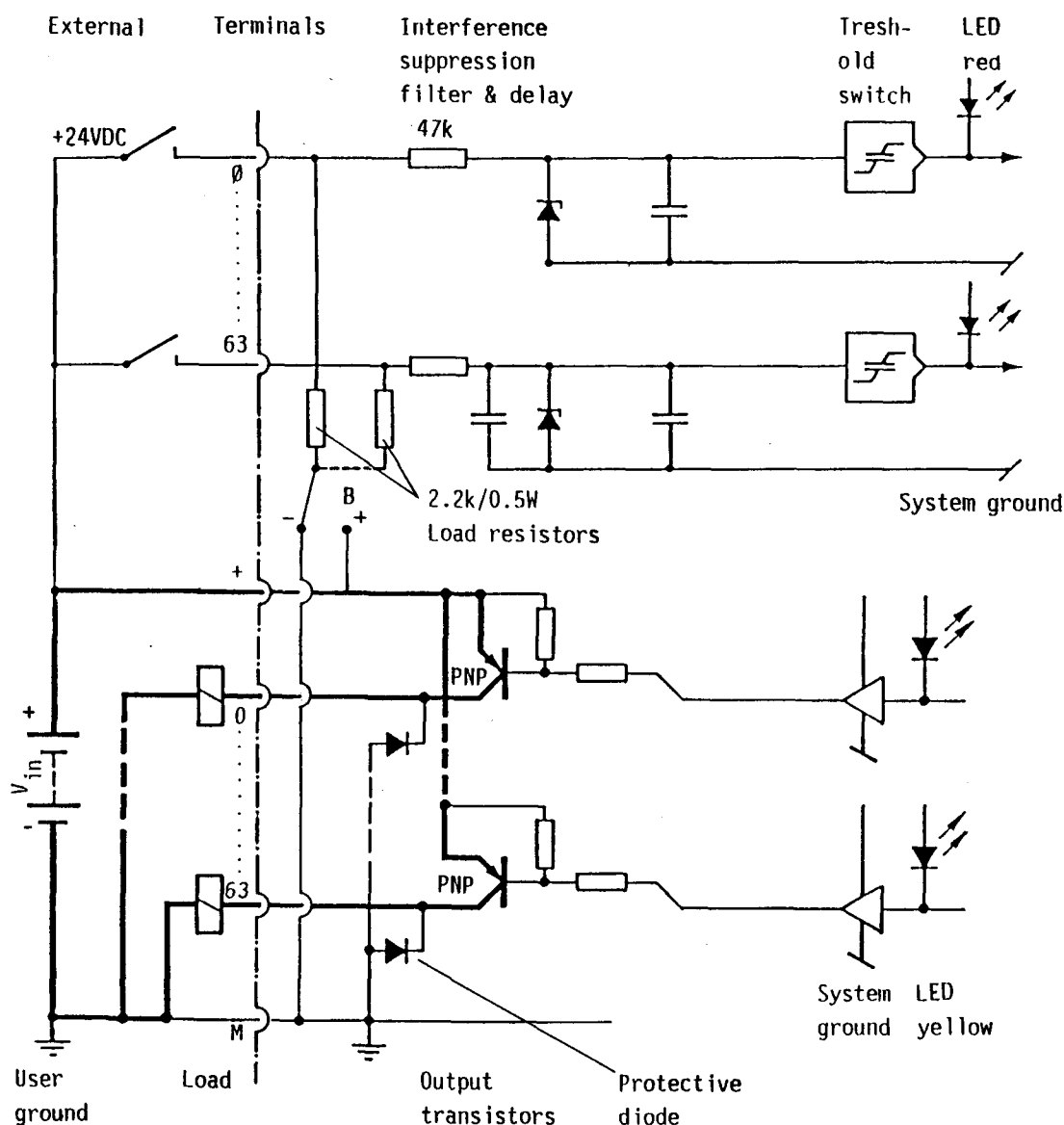
## Connection of inputs and outputs



Factory setting: jumper B on "-": source operation

Inputs in source operation or positive logic  
(factory setting: jumper B on "-")

Switch closed (positive at input): "H" = LED ON  
Switch open (negative at input): "L" = LED OFF



Output conducting (set) = LED ON  
Output non-conductive (reset) = LED OFF } Source operation

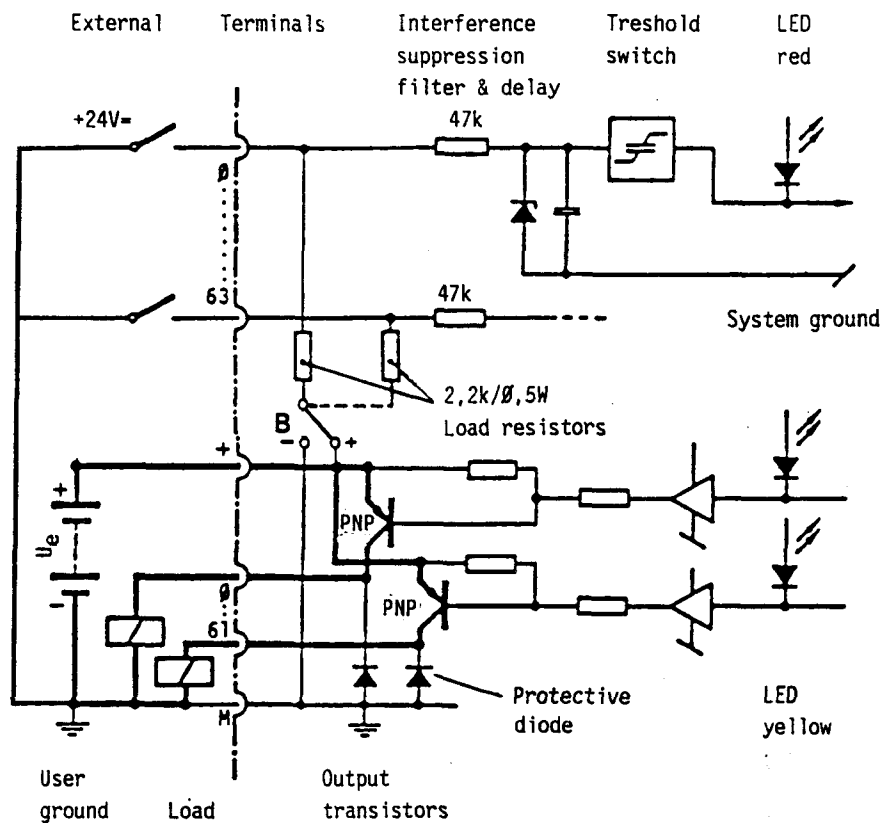
Inputs in sink operation or negative logic, outputs in source operation  
(jumper B on "+")

Inputs: Sink operation

- Switch closed  
(- at input): H  $\Rightarrow$  LED OFF
- Switch open  
(+ at input): L  $\Rightarrow$  LED ON

Outputs: Source operation

- Output conducting  
(set)  $\Rightarrow$  LED ON
- Output non-conductive  
(reset)  $\Rightarrow$  LED OFF





### B 1.1.12 Type PCA1.E40 Combined date-time and input module (only PCA14)

In addition to 7 inputs, the module PCA1.E40 contains a precise date-time with power reserve. This buffered date-time can only be evaluated with the system series PCA14 in connection with its software date-time.

#### Technical data

##### Inputs:

Number of inputs per module	7, electrically connected (addr. 1...7)
Input voltage $V_{in}$	24VDC, smoothed or pulsating
Input current at 24VDC	10mA
Input delay (typical)	9ms
Operating mode	Source or sink operation

##### Date-time:

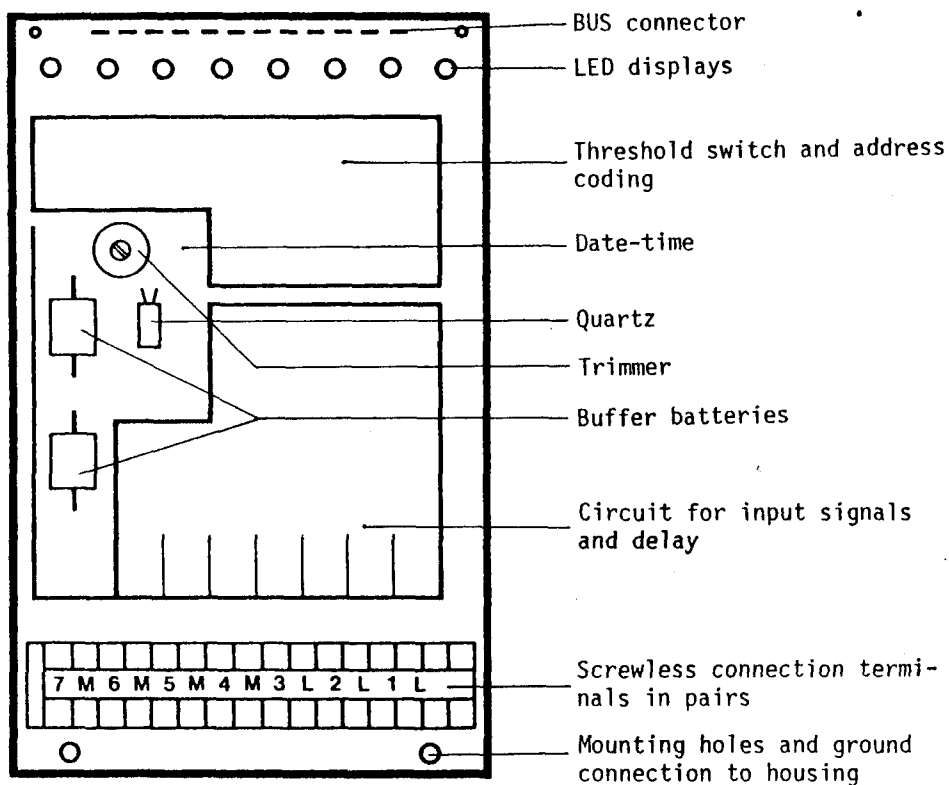
Accuracy	<15s/month at $T = 15 - 30^{\circ}\text{C}$
Power reserve	2 months due to NiCd battery <sup>3)</sup>
Date-time values	Day of the week 01...07 <sup>2)</sup> Year 00...99 Month 01...12 Day of the month 01...31 <sup>1)</sup> Hours 00...23 Minutes 00...59 Seconds 00...59
Internal power consumption of the module (5V)	15...70mA

1) The date-time takes the various months and leap years into account.

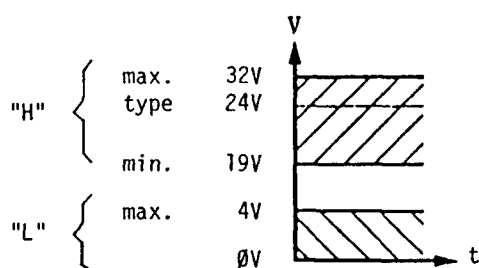
2) Day of the week 01 stands for Monday, 07 stands for Sunday.

3) Life of buffer battery approx. 5 years  
Spare part no. 4'507'11'950

## Presentation and terminal layout



## Definition of the input voltages



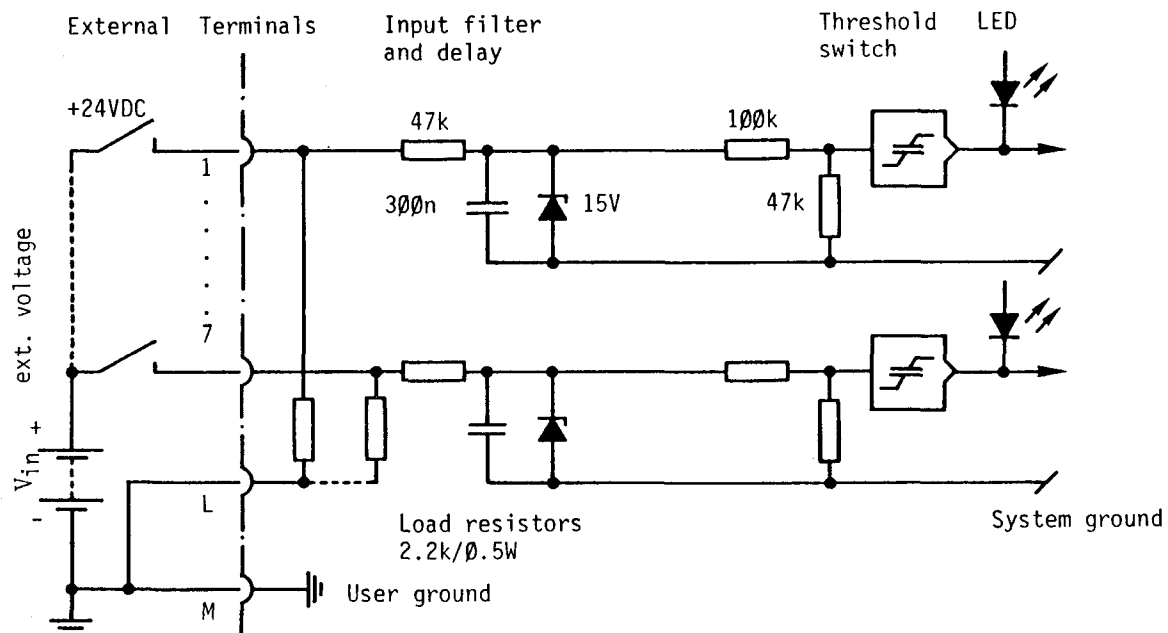
Pulsating DC-voltage is sufficient as supply voltage, because of the 9ms input delay.

The 7 inputs (addresses 1...7) can be used without restrictions and independently of the date-time. The address 0 is reserved for the data transfer from and to the date-time.

### Input circuit

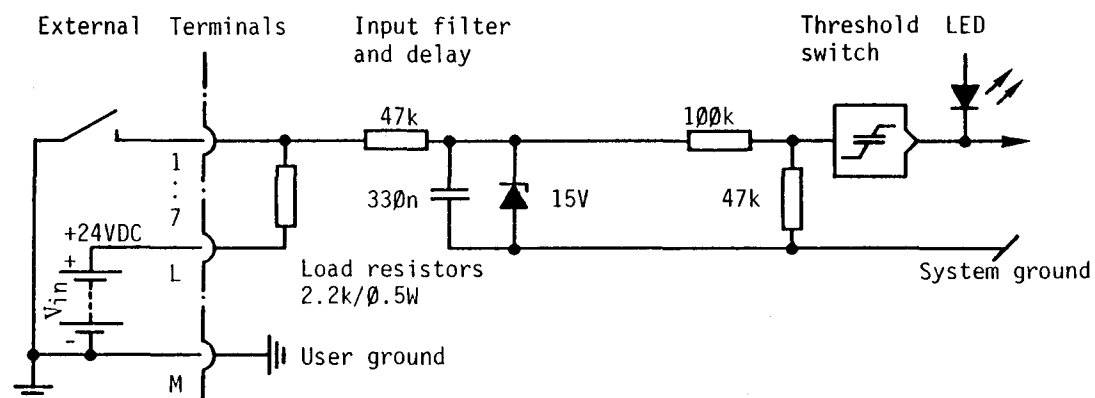
Depending on the external circuitry this module can be used either in source or sink operation.

Source operation or positive logic (normal case):



Switch closed (positive at input): "H"  $\hat{=}$  LED ON  
Switch open (negative at input): "L"  $\hat{=}$  LED OFF

Sink operation or negative logic:



Switch closed (negative at input): "L"  $\hat{=}$  LED OFF  
Switch open (positive at input): "H"  $\hat{=}$  LED ON

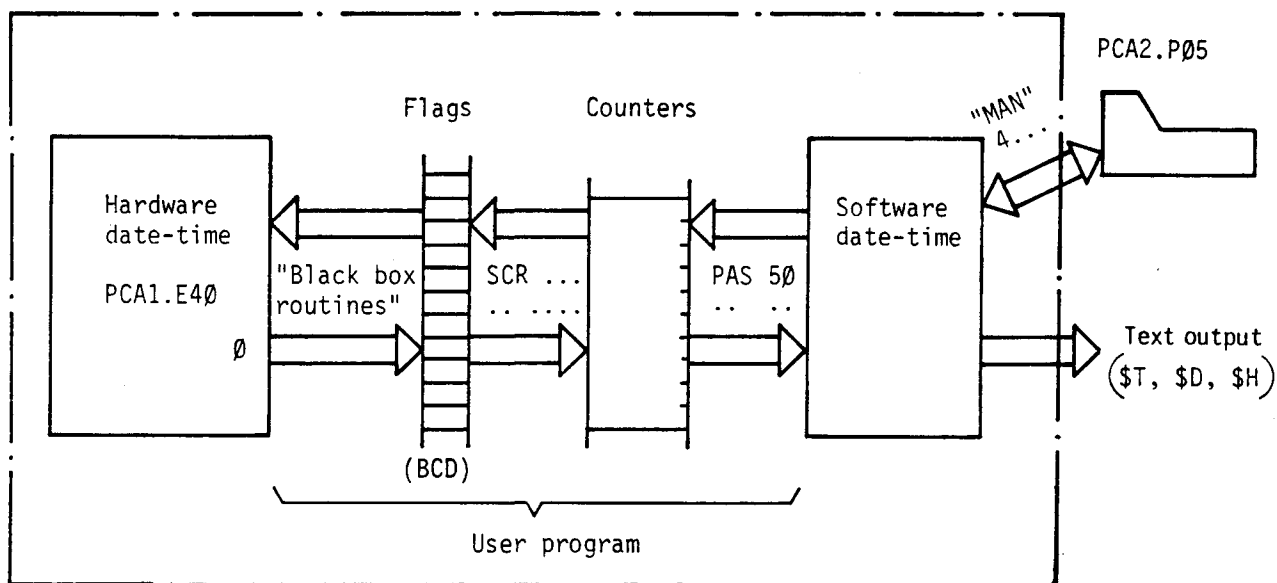
### Handling of the date-time

Owing to its higher accuracy, the hardware date-time is considered the master as compared with the software date-time. The comfortable instructions such as PAS 50 and the special text characters \$T, \$H and \$D (see PCA14 manual), however, refer only to the software date-time. It is therefore necessary to synchronize the hardware and the software date-time at times (e.g. every 24h). Moreover, the date and time values of the hardware date-time must be set on the first start-up.

Make sure that synchronization of the software date-time and setting of the hardware date-time are performed only when required in order to prevent the hardware date-time from being permanently blocked.

Its handling will be described in detail on the following pages.

### Principle of the data transfer between software and hardware date-time



As evident from the above figure, a flag field (for the whole contents 60 or 68 flags) as well as 1 counter must be reserved for the duration of the data transfer between both date-times. The transfer from the hardware date-time to the flag field or vice versa is effected serially with the address 0. The addresses 6 and 7 are used as control signals.

Address 0: This address is used for the data transfer between the date-time and the flags.

Address 6: With address 6 a clock is generated. With every clock signal a data bit is received or transmitted by the hardware date-time.

Address 7: Chip select. In order to activate the data transfer, this address must be set to "H". As soon as the transmission is finished, address 7 must be reset to "L".



### Function of the control bits

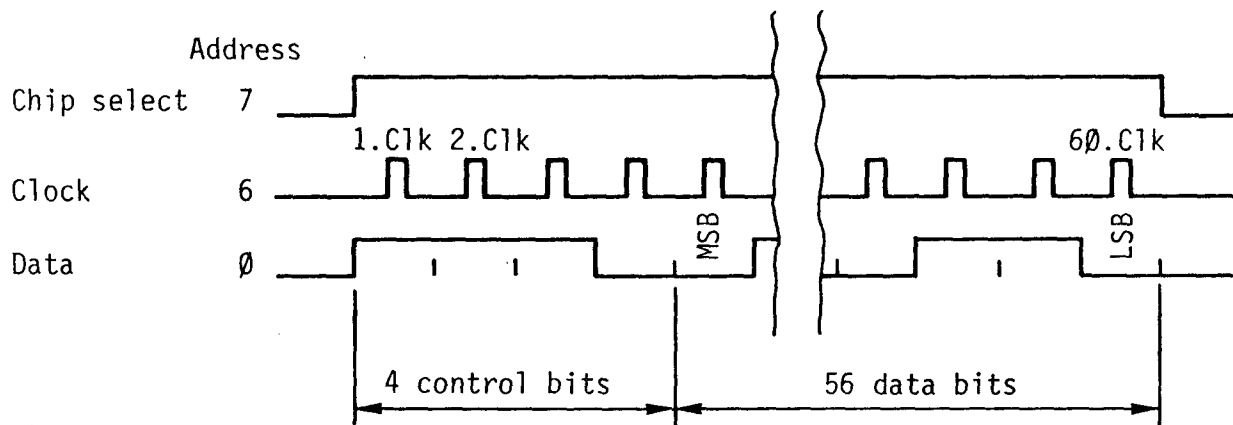
The 4 control bits tell the date-time "what to do". The first three bits received by the date-time define the data to be transmitted. The 4th bit is used to determine whether the date-time is set or read.

These 4 control bits must be transmitted before every data transfer, irrespective of whether the date-time is set or read.

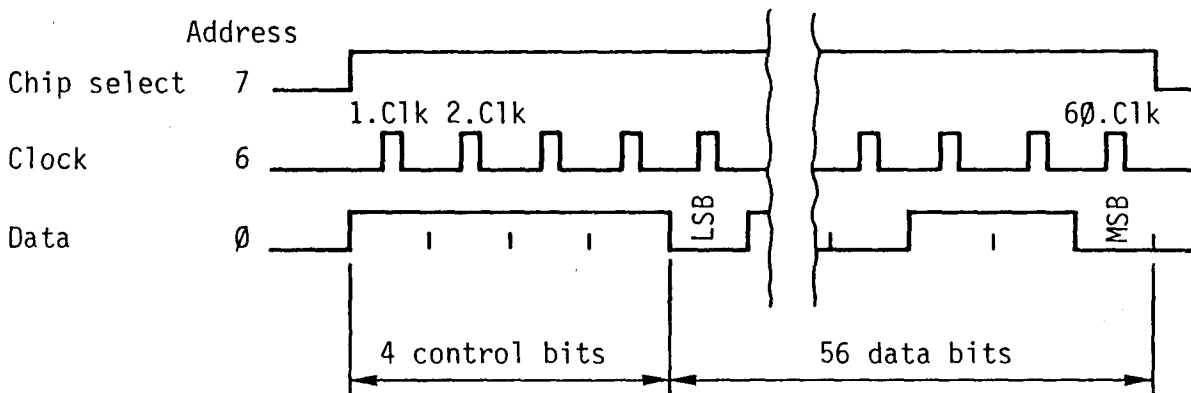
1.	2.	3.	4.	Bit
1	1	1	x	Whole contents
1	1	0	x	Year
1	0	1	x	Day of the week
1	0	0	x	Month
0	1	1	x	Day of the month
0	1	0	x	Hours
0	0	1	x	Minutes
0	0	0	x	Seconds
x	x	x	0	<u>Set</u> date-time
x	x	x	1	<u>Read</u> date-time

Transfer diagram

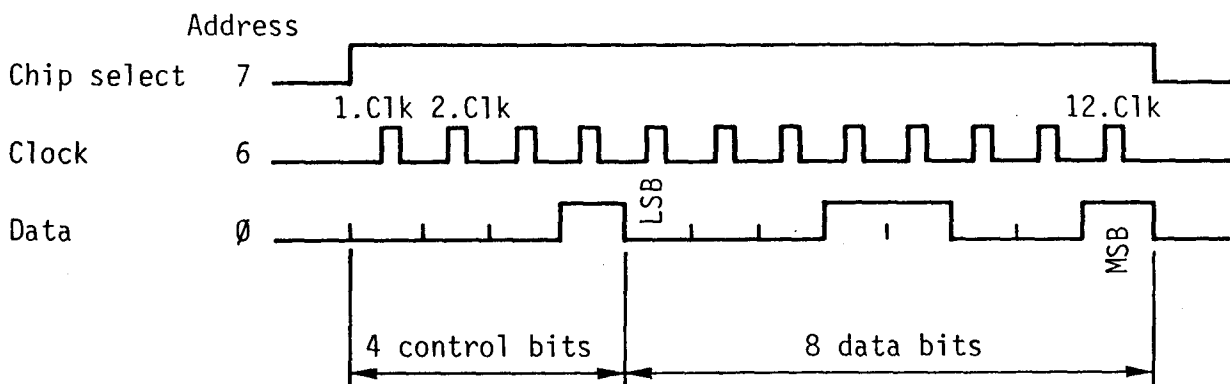
a) Setting the whole date-time contents



b) Reading the whole date-time contents



c) Reading the seconds



## Examples

### 1. Setting the hardware date-time (whole contents)

During the first startup of the hardware date-time, the correct values must be set. Proceed as follows:

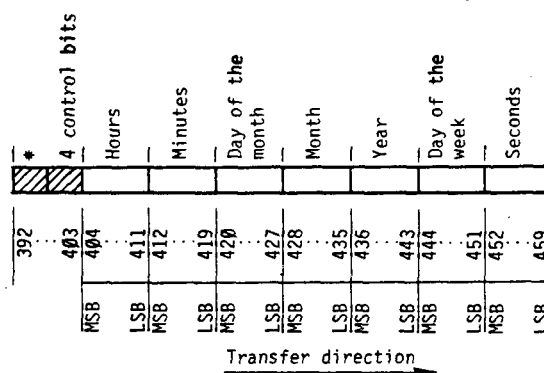
- The current date-time values are introduced into the software date-time (e.g. with a PCA2.P05, see chapter "Operating modes").
- In the STEP-mode the following routine is selected and executed. The hardware date-time automatically accepts the values of the software date-time and keeps on running, irrespective of whether the PLC stays switched on.

This procedure can be repeated, if after months the deviation from the actual date-time has become too great.

#### Program

4020	29	PAS	50	Seconds
21	17	17	260	
22	15	SCR	260	
23	20	20	459	
24	29	PAS	50	Day of the week
25	11	11	260	
26	15	SCR	260	
27	20	20	451	
28	29	PAS	50	Year
29	12	12	260	
4030	15	SCR	260	
31	20	20	443	
32	29	PAS	50	Month
33	13	13	260	
34	15	SCR	260	
35	20	20	435	
36	29	PAS	50	Day of the month
37	14	14	260	
38	15	SCR	260	
39	20	20	427	
4040	29	PAS	50	Minutes
41	16	16	260	
42	15	SCR	260	
43	20	20	419	
44	29	PAS	50	Hours
45	15	15	260	
46	15	SCR	260	
47	20	20	411	

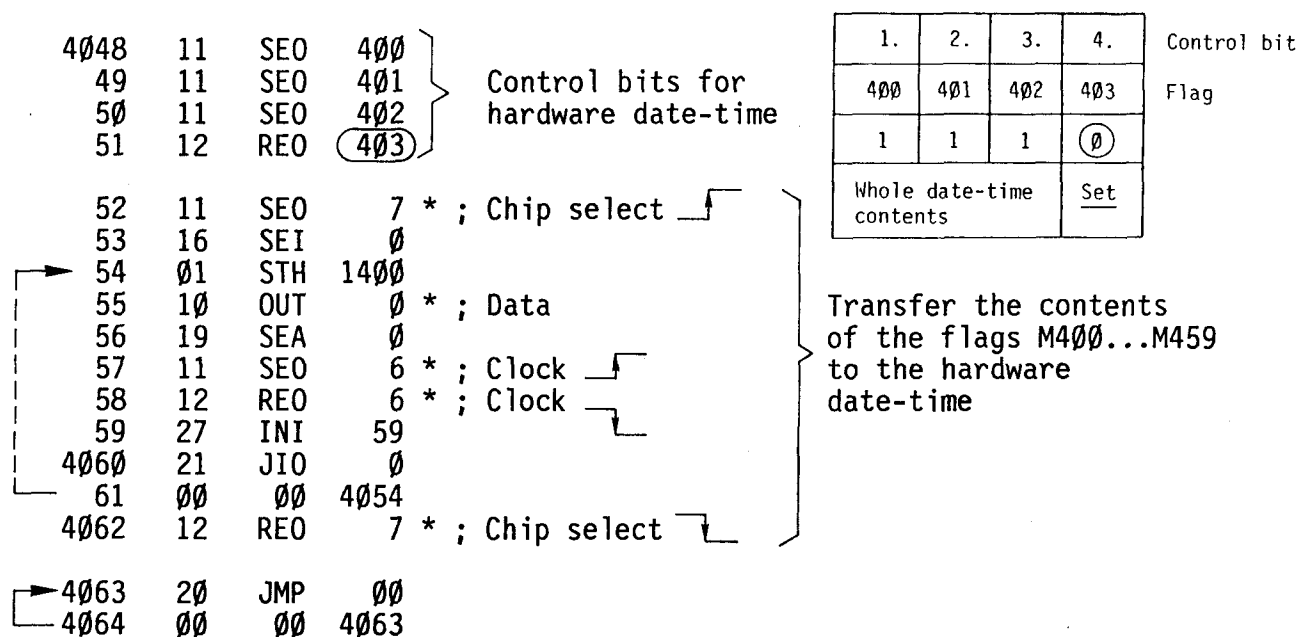
Transfer contents of the software date-time to flags



Flags → Hardware date-time

\*) With code 20 in the 2nd line of the instruction SCR 20 bits BCD are transferred. Therefore, the flags 392...403 must also be reserved, with M400...M403 serving as control bits for the hardware date-time. On the whole, 68 flags are required for setting the hardware date-time.



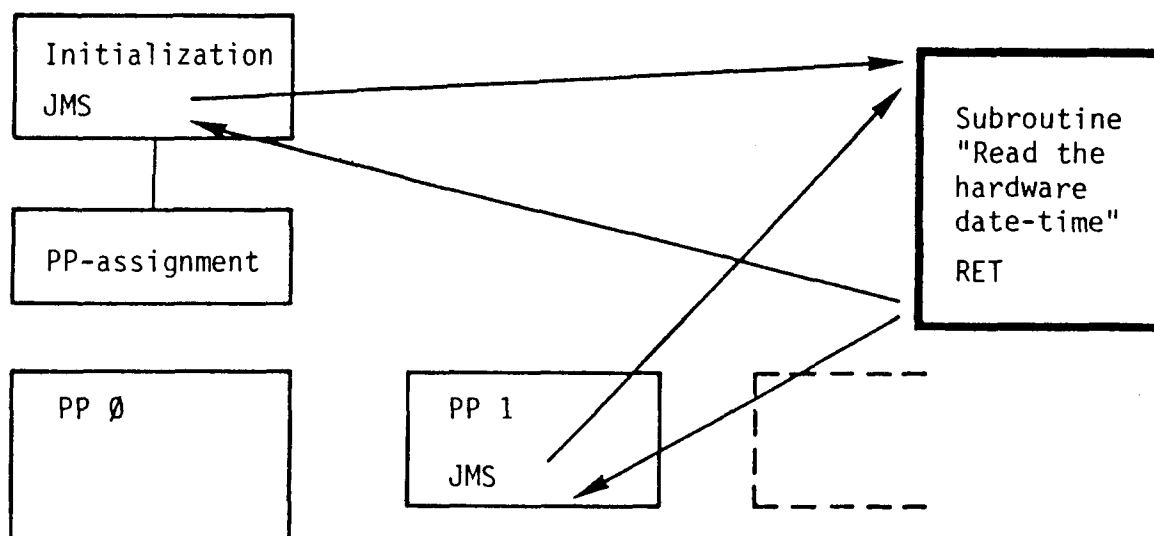


\*) These addresses do not depend on the plug-in location of the module (example for addr. 0...7).

## 2. Reading the hardware date-time (whole contents)

The routine "Reading the hardware date-time" must be executed after each voltage failure upon switching on the PLC again. It can also be called in the main program depending on internal or external conditions, ensuring that the software date-time does never deviate much from the hardware date-time. It is of advantage to write the program "Reading the hardware date-time" as a subroutine.

### Program structure



## Subroutine: Read the whole contents

```

⇒ 56 11 SEO 459
57 11 SEO 458
58 11 SEO 457
59 11 SEO 456

```

Control bits for hardware date-time

```

60 11 SEO 7 * ; Chip select
61 16 SEI 59
62 01 STH 1400
63 10 OUT 0 * ; Data
64 19 SEA 0
65 11 SEO 6 * ; Clock
66 12 REO 6 * ; Clock
67 28 DEI 56
68 21 JIO 0
69 00 00 62
70 16 SEI 55

```

Control bits (M459...M456) to hardware date-time (control command)

```

71 01 STH 0 * ; Data
72 10 OUT 1400
73 19 SEA 0
74 11 SEO 6 * ; Clock
75 12 REO 6 * ; Clock
76 28 DEI 0
77 21 JIO 0
78 00 00 71
79 12 REO 7 * ; Chip select

```

Transfer date from hardware date-time to flags M455...M400

```

80 15 SCR 260
81 16 16 415
82 29 PAS 50
83 01 01 260

```

Day of the week

```

84 15 SCR 260
85 16 16 423
86 29 PAS 50
87 02 02 260

```

Year

```

88 15 SCR 260
89 16 16 431
90 29 PAS 50
91 03 03 260

```

Month

```

92 15 SCR 260
93 16 16 439
94 29 PAS 50
95 04 04 260

```

Day of the month

```

96 15 SCR 260
97 16 16 447
98 29 PAS 50
99 06 06 260

```

Minutes

```

100 15 SCR 260
101 16 16 455
102 29 PAS 50
103 05 05 260

```

Hours

```

104 15 SCR 260
105 16 16 407
106 29 PAS 50
107 07 07 260
108 24 RET 0

```

Seconds

1.	2.	3.	4.	Control bit
459	458	457	456	Flag
1	1	1	①	
Whole date-time contents			Read	

Transfer contents of flags M400...M455 to software date-time

Seconds	Day of the week	Year	Month	Day of the month	Minutes	Hours	4 control bits
400	407	408	415	416	423	424	431
432	439	440	447	448	455	456	459
MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB

Transfer direction

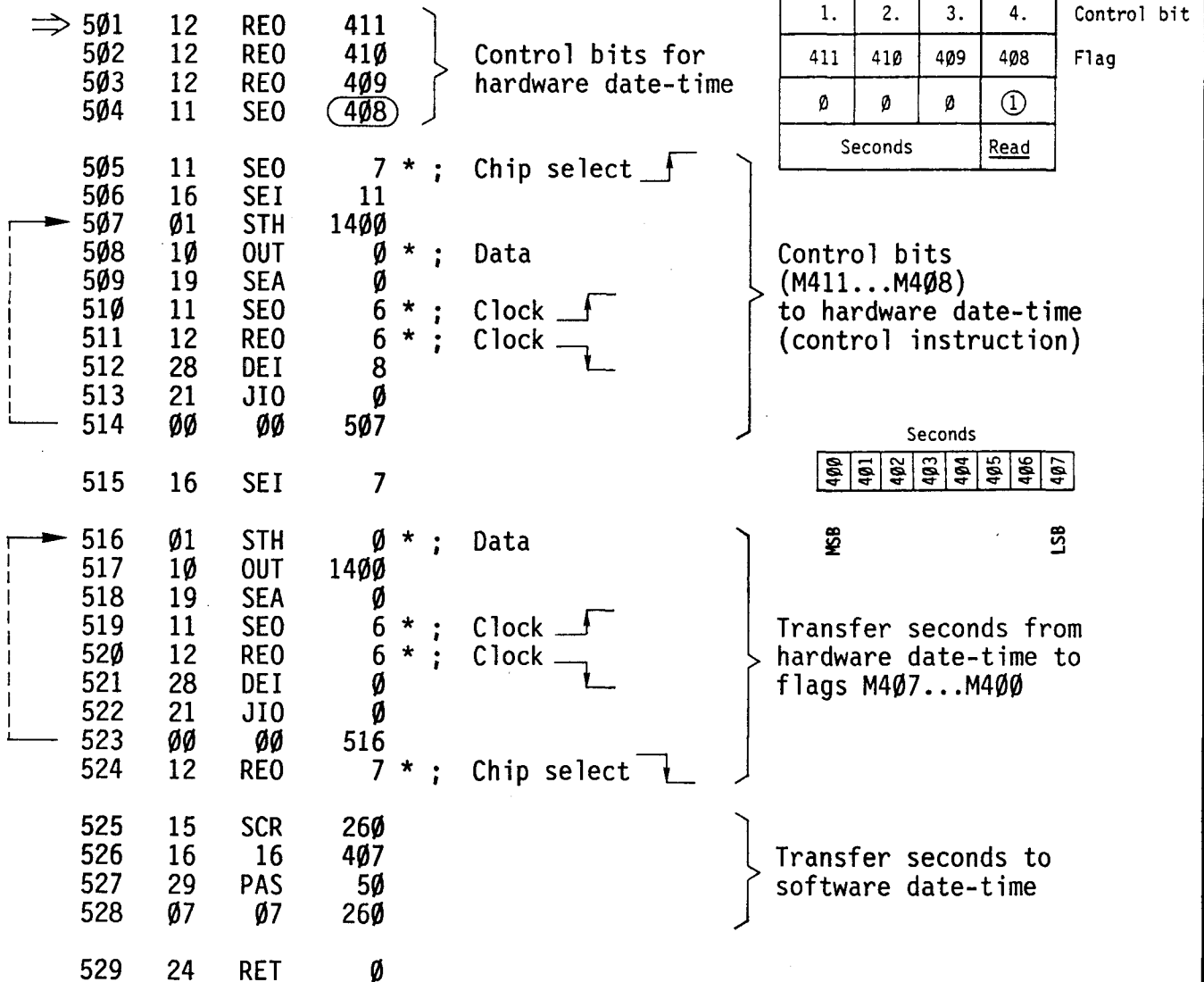
Hardware date-time → Flags

\*) These addresses depend on the plug-in location of the module.

### 3. Transferring the seconds from the hardware date-time (to software date-time)

As is well known, it is also possible to transfer only single values of the date-time. If the software date-time is regularly synchronized with the hardware date-time, it may be sufficient to transfer only the seconds (accuracy of the software date-time: <3s/day).

#### Subroutine: Read the seconds



\*) These addresses depend on the plug-in location of the module.

### B 1.1.13 Type PCA1.W1.. Analog I/O module with 8- or 7-bit resolution

#### Technical data

##### Inputs:

Number of channels	6, electrically connected
Voltage range	0...5V <sup>1)</sup>
Resolution	8 bits (1/256 $\approx$ 0.4%)
Accuracy (absolute deviation)	1 1/2 bits $\approx$ 0.6%
Input impedance	$\geq 1\text{M}\Omega$ <sup>1)</sup>
Time constant of input filter	0.2ms
A/D conversion time	< 100µs

All inputs are protected against positive and negative overvoltages.

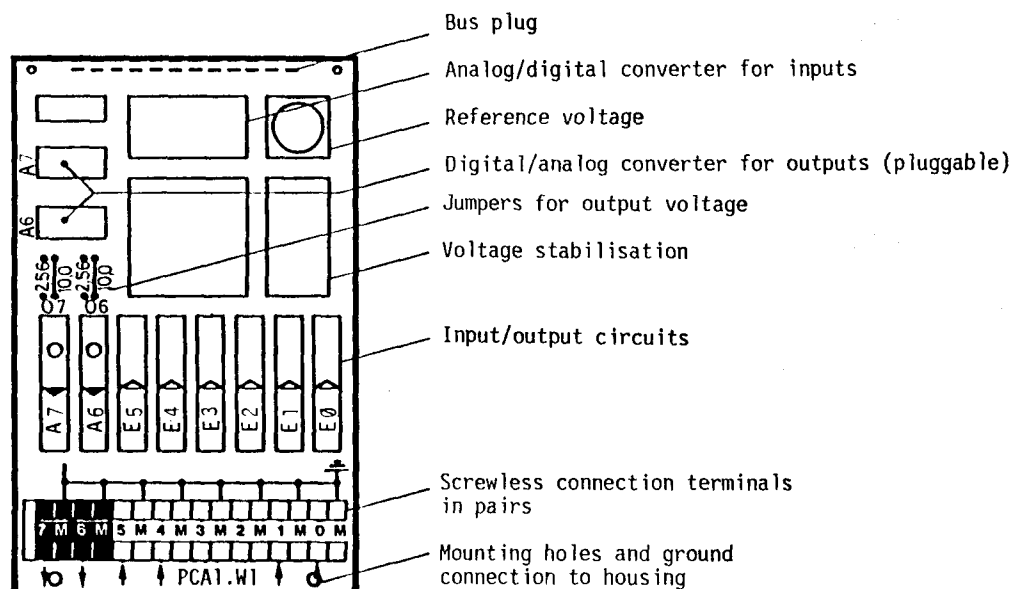
##### Outputs:

Number of channels	0, 1 or 2 <sup>2)</sup>
Voltage range	0...10V, can be changed to 0...2.56V
Resolution	7 bits (1/128 $\approx$ 0.8%)
Accuracy	1 1/2 bits $\approx$ 1.0%
Load impedance	$\geq 1\text{k}\Omega$
Power consumption (5V)	30...40mA
(24V)	25mA

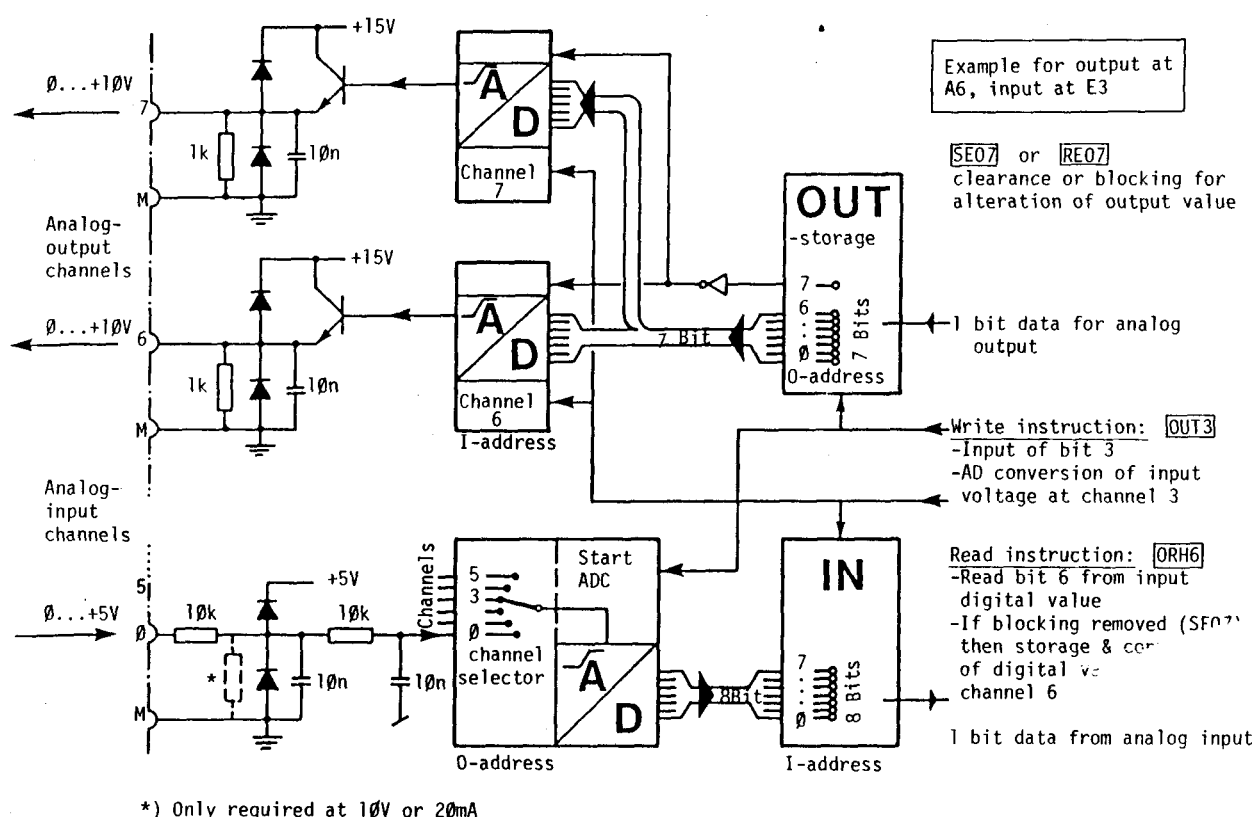
1) Special variants      PCA1.W1.. Z09: 0...20mA input impedance 296Ω  
PCA1.W1.. Z10: 0...10V input impedance 20kΩ

2) Number of analog outputs      without output: PCA1.W10  
with 1 output: PCA1.W11 (A7)  
with 2 outputs: PCA1.W12 (A7 and A6)

#### Presentation



# Input/output circuit and block circuit diagram



## Programming example for address location 0...7

Read analog input voltage present on channel 3 (ADDR 3).

The corresponding binary value is to be transferred to counter 260.

```
100 OUT 32) ; Select I-channel 3 and trigger A/D conversion
101 SCR 260 ; Transmit binary value (8 bits) to counter 260
102 24 72)
```

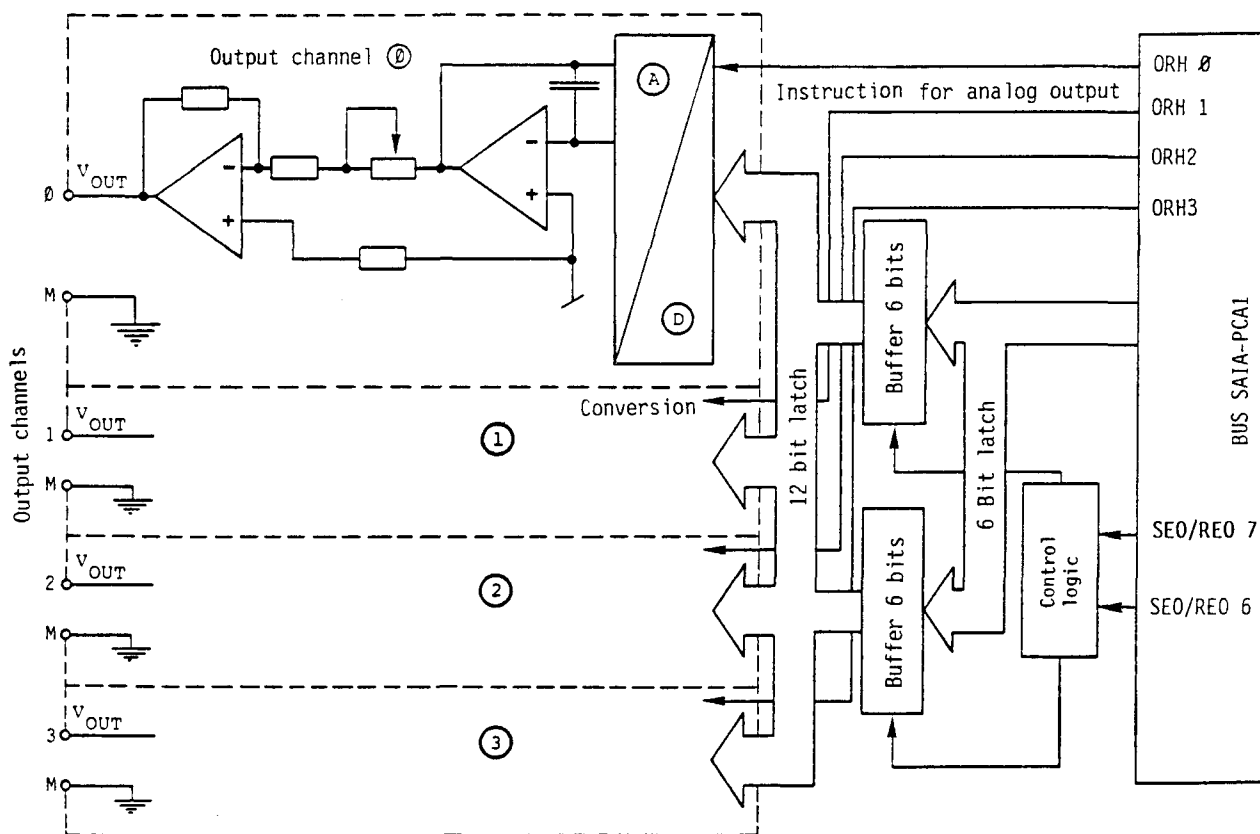
Transfer an analog value to 0-channel 6 (ADDR 6).

The numerical value (0...255) is stored in counter 310.

```
200 SCR 310 ; Transmit value 0...255 from counter
201 21 712) ; to D/A converter
202 SE0 72) ; Clearance for altering the output value
203 ORH 62) ; Storage of binary value, conversion
                and output to output channel 5
204 RE0 72) ; Blocking of output value
```

- 1) The counter value of 0...255 corresponds to an output voltage of 0...10V. The resolution, however, is only 7 bits.
- 2) If this module uses, for example, the addresses 24 to 31, it must be noted that the highest address of the card is 31. This means that input channel 3 corresponds to address 27, the output channel corresponds to address 30 and the block or clear command is assigned to address 31.

### Block circuit diagram PCA1.W2

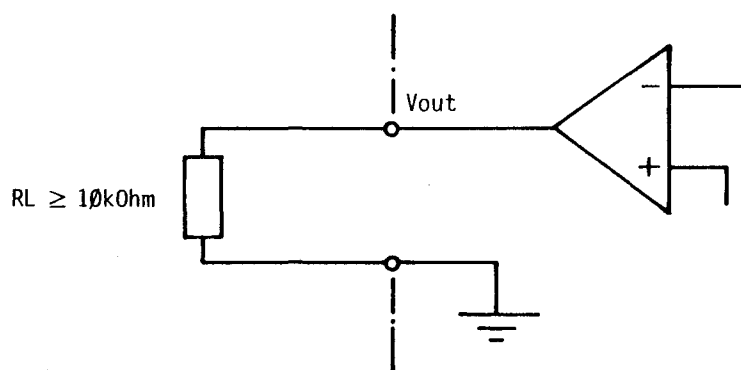


### Connection to the process

A voltage output is made up of the plug-in D/A-converter and the two soldered-in amplifiers.

The standard output voltage is 0...10V. For special applications, appropriate precision resistors are soldered in.

The signals are always measured potential to ground.



## Software

### Output analog value

The 12-bit digital value to be output must be applied at the inputs of the D/A-converters. By means of an instruction (ORH 0...3) this value is stored and output as analog value by the D/A-converter.

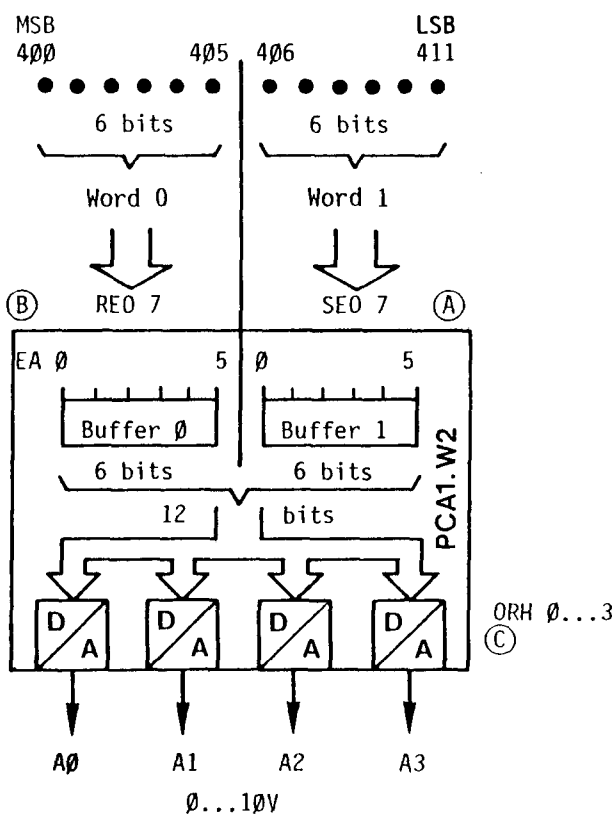
The unchanged analog values of all 4 outputs are available to the process as long as they are not redefined by means of a new instruction.

### Procedure

With the series PCA1 only 8 element addresses are available per I/O-module. In order to process the 12-bit data, they are split up into two words consisting of 6 bits each and processed one after the other.

The following steps must be distinguished:

- Transfer the first 6 bits (starting with LSB) to buffer 1 (SEO 7)
- Transfer the second 6 bits (up to MSB) to buffer 0 (REO 7)
- Select the output channel with ORH 0...3 and trigger D/A-conversion at the same time.



### Program for EA 0...7

```
(SEA 0)
(SEO 7)*      Word 1
STH 411)
OUT 5)*      Transfer 6 bits to buffer 1 (A)
STH 410)
OUT 4)*
.
.
STH 406)*
OUT 0)*
```

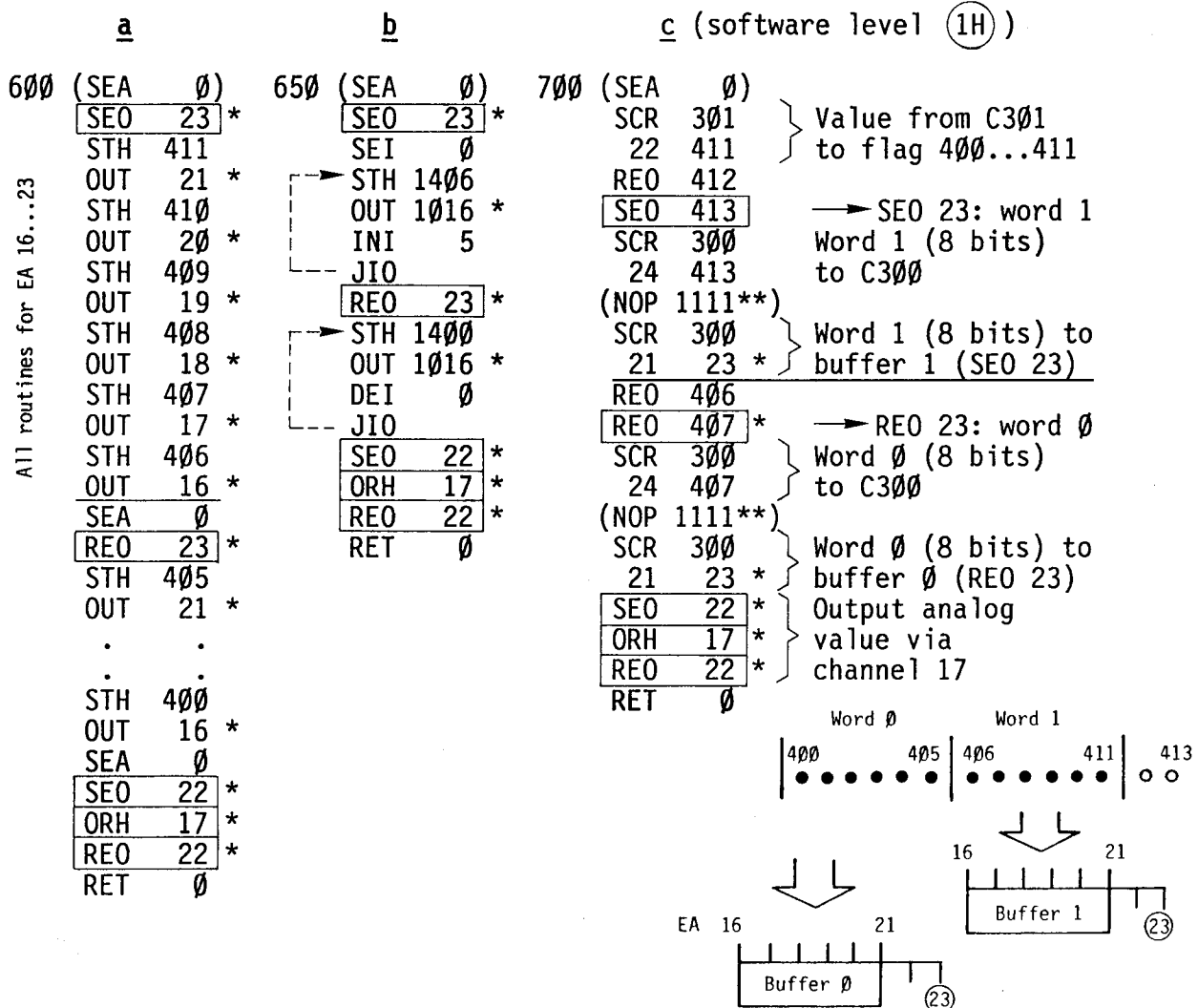
```
SEA 0
(REO 7)*      Word 0
STH 405)
OUT 5)*      Transfer 6 bits to buffer 0 (B)
.
.
STH 400)
OUT 0)*
SEO 6
ORH 0...3)*   Select output channel 0...3 and output analog value (C)
REO 6)*
```

\*) If the module is placed to a position other than 0, the corresponding basic address must be added.

### Analog value output in the form of subroutines

The following versions a to c are distinguished by their software levels, program lengths, execution times and the number of program changes. Due to the standard execution time of 2.13 ms the PP-change is blocked and the serial interface is no longer operated for this period. If the interface is to function with a baud rate of 4800 or 9600 baud simultaneously, either version a or b can be used or version c with the commands NOP 1111 (operation of the data interface) given in brackets.

Subroutine version	Number of program lines	Execution time PCA14/15	Number of program changes (incl. RET) PCA14/15
a	31	3.09 ms	11
b	15	4.31 ms	13
c	18	2.13 ms	1



For versions a and b flags 400...411 are used. Version c uses counter C301 as an output register. 14 flags 400...413 are used in version c to load the buffers.

\* For basic address 16.

\*\* PCA14 as of version V6.034 for a baud rate of 9600 bauds.



B 1.1.15 Type PCA1.W3.. 12-bit analog input and output moduleTechnical dataInputs:

Number of input channels	4
Input circuit	Differential with filter
Signal ranges: - voltage	1) $0V \dots +10V$ 2) $-5V \dots +5V$ 3) $-10V \dots +10V$
- current	1) $0 \dots +20mA$ 2) $-10 \dots +10mA$ 3) $-20 \dots +20mA$
Resolution	12 bits = $1/4096$
Accuracy (measured value)	typ. 0.4% (max. 0.8% during bipolar operation)
Repeatability	$\pm 2$ LSB*
Input impedance - voltage	$\geq 1 M\Omega$
- current	499 $\Omega$
Time constant of the input filter	0.1ms
A/D-conversion time	$\leq 30\mu s$
Max. admissible voltage	$\pm 15V$

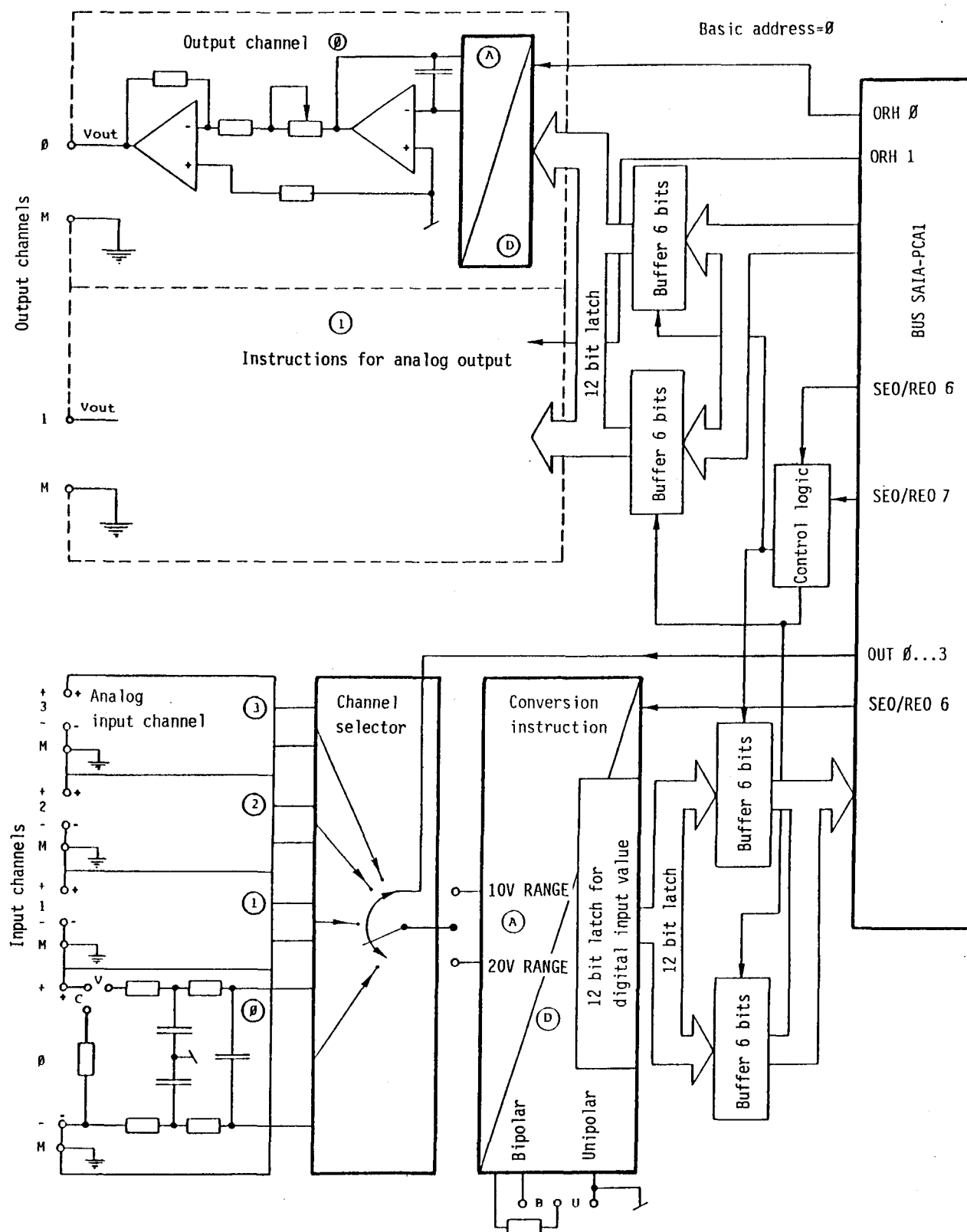
Outputs:

Number of output channels	max. 2
Resolution	12 bits = $1/4096$
D/A-conversion	$\leq 20\mu s$
Signal ranges: - voltage	Standard: $0V \dots +10V$ Spezial { $0V \dots +5V$ $-5V \dots +5V$ $-10V \dots +10V$
Accuracy (actual value) in range $0 \dots 5V$ or $0 \dots 10V$	typ. $0.4\% \pm 30mV^{**}$ ; max. $1\% \pm 30mV^{**}$
Load impedance	$\geq 10k\Omega$
Current consumption 5V	100...120mA
25V	60...100mA

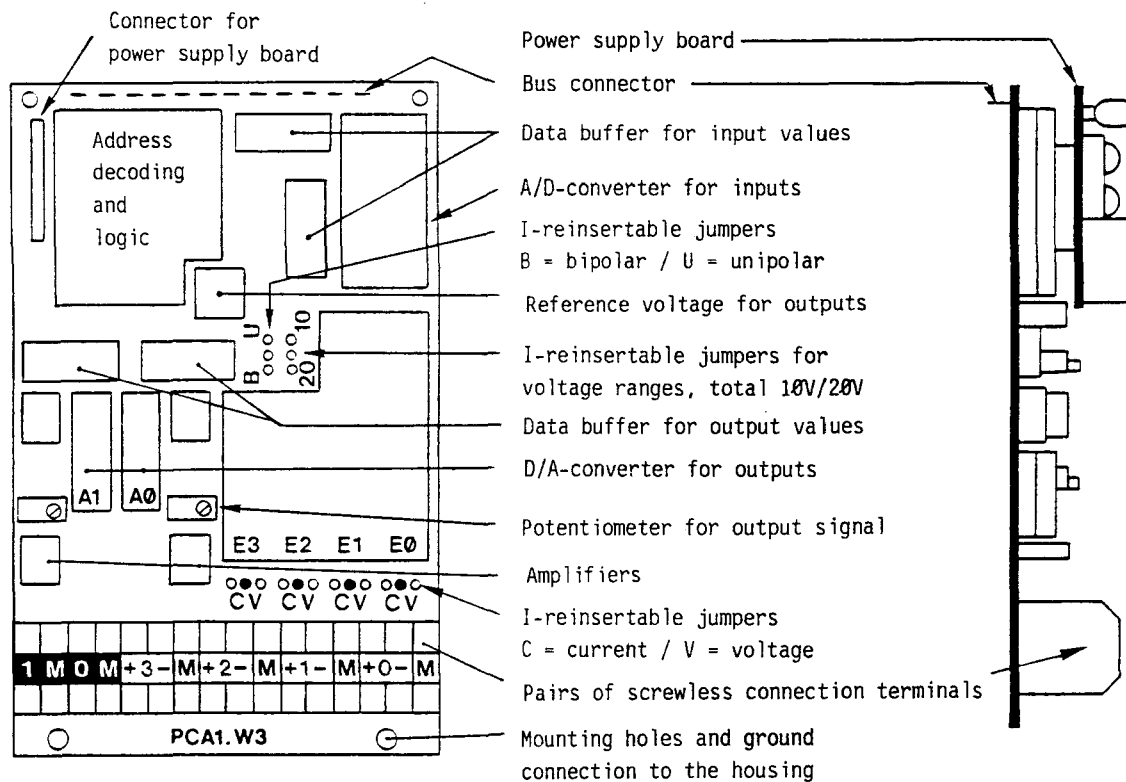
\*) LSB: Least Significant Bit; e.g. 10V divided by 4096: approx. 2.5mV

\*\*\*) Max. constant offset value

Block circuit diagram PCA1.W3..



## Presentation



## Versions, order specifications

Type PCA1.W3Ø with 4 I-channels, without output channel

Type PCA1.W32 with 4 I-channels + 2 output channels (AØ +A1)

Signal ranges for inputs : selectable by jumpers

Signal ranges for outputs: Ø...10V (other ranges of values on request)

## Connection to the process

### Connection of the input channels

The common-mode voltage range of all input channels is  $\pm 10\text{V}$ , i.e., both potentials of each input channel must be within  $\pm 10\text{V}$  with respect to the ground. Under this condition correct registration of the measured data is ensured.

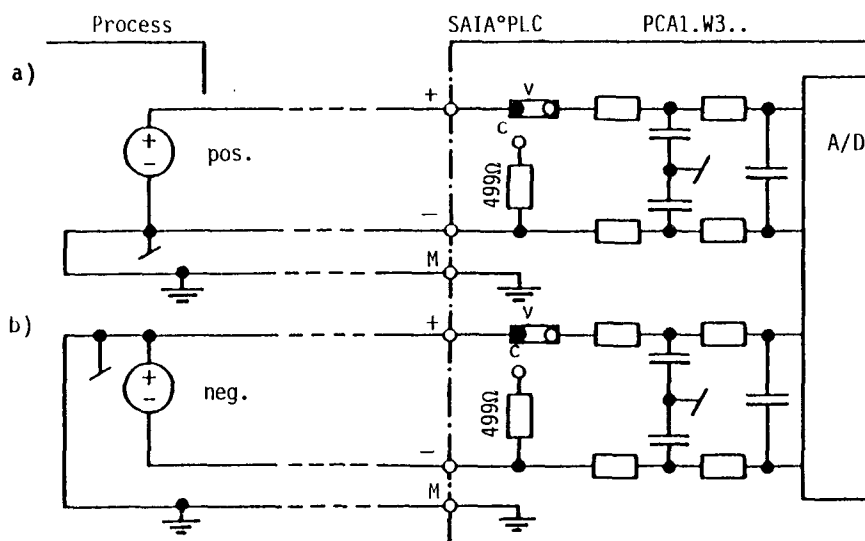
### Preselection of the I-ranges:

- The process ground or measuring amplifier ground must be connected to the user ground of the PLC.
- The input voltage range of  $10/20\text{V}$  is preselected jointly for all inputs of a module via the connector.
- Whether bipolar voltages ( $\pm V$ ) or unipolar voltages are to be registered, is preselected jointly for all inputs of a module via the connector B/U.
- Operation with current can be selected for each input individually via the plug (C = current, V = voltage). If the connector is plugged into C, a precision resistance of  $499\Omega$  is switched into this input circuit, the voltage of which is evaluated. The current range depends on the selected voltage range ( $10\text{V} \approx 20\text{mA}$ ).

The following table shows the three basic ranges with respect to the corresponding digital value:

Digital value	Unipolar U operation (connector 10V)	Bipolar operation B	
		(connector 10V)	(connector 20V)
4095	+10V (+20mA)	+5V (+10mA)	+10V (+20mA)
2048	+5V (+10mA)	0V (0mA)	0V (0mA)
0	0V (0mA)	-5V (-10mA)	-10V (-20mA)

In case of unipolar operation the positive potential is applied to the plus-terminal. Figures a and b show the connection scheme for the measurement of positive or negative voltages respectively.



## Software

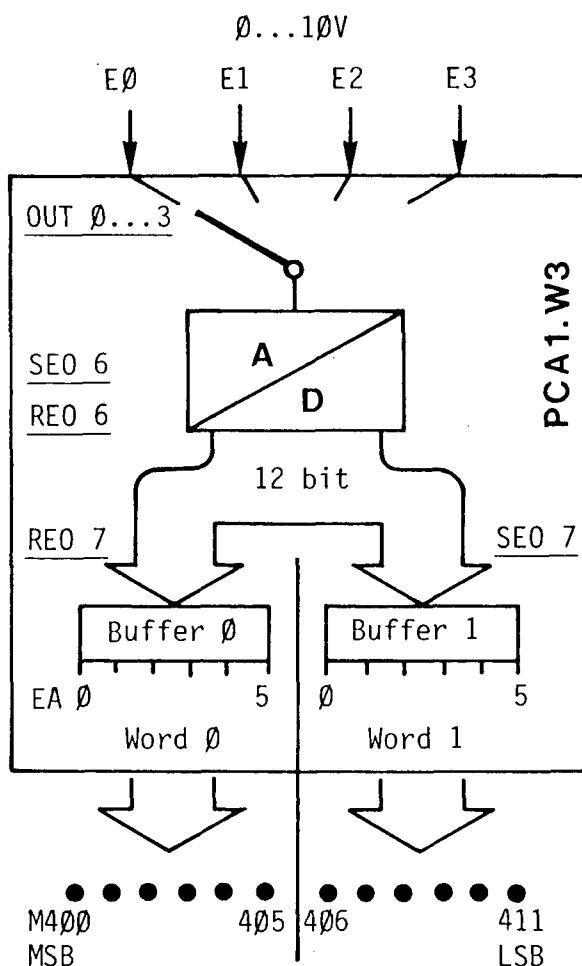
With the version PCA1 only 8 element addresses are available per I/O-module. In order to process the 12-bit data, they are split up into two words consisting of 6 bits each and processed one after the other.

Word 0: contains the high-order 6 bits including MSB  
 Word 1: contains the low-order 6 bits including LSB

### Read analog value (input channels)

For reading an analog value the following 3 steps are necessary:

- Select input channel (OUT 0...3)
- Initiate actual A/D-conversion (SEO 6, REO 6)
- Select the 6-bit word group 0 or 1 (REO/SEO 7)



### Program for EA 0...7

```
(SEA 0)
OUT 0...3 *      Select input
                  channel 0...3
                  Word 1
SEO 7 *
SEO 6 *          *A/D-conversion
REO 6 *
STH 5 *
OUT 411 *
STH 4 *          Transfer 6 bits from
OUT 410 *        buffer 1 to flags
.         411...406
.
STH 0 *
OUT 406 *        *
```

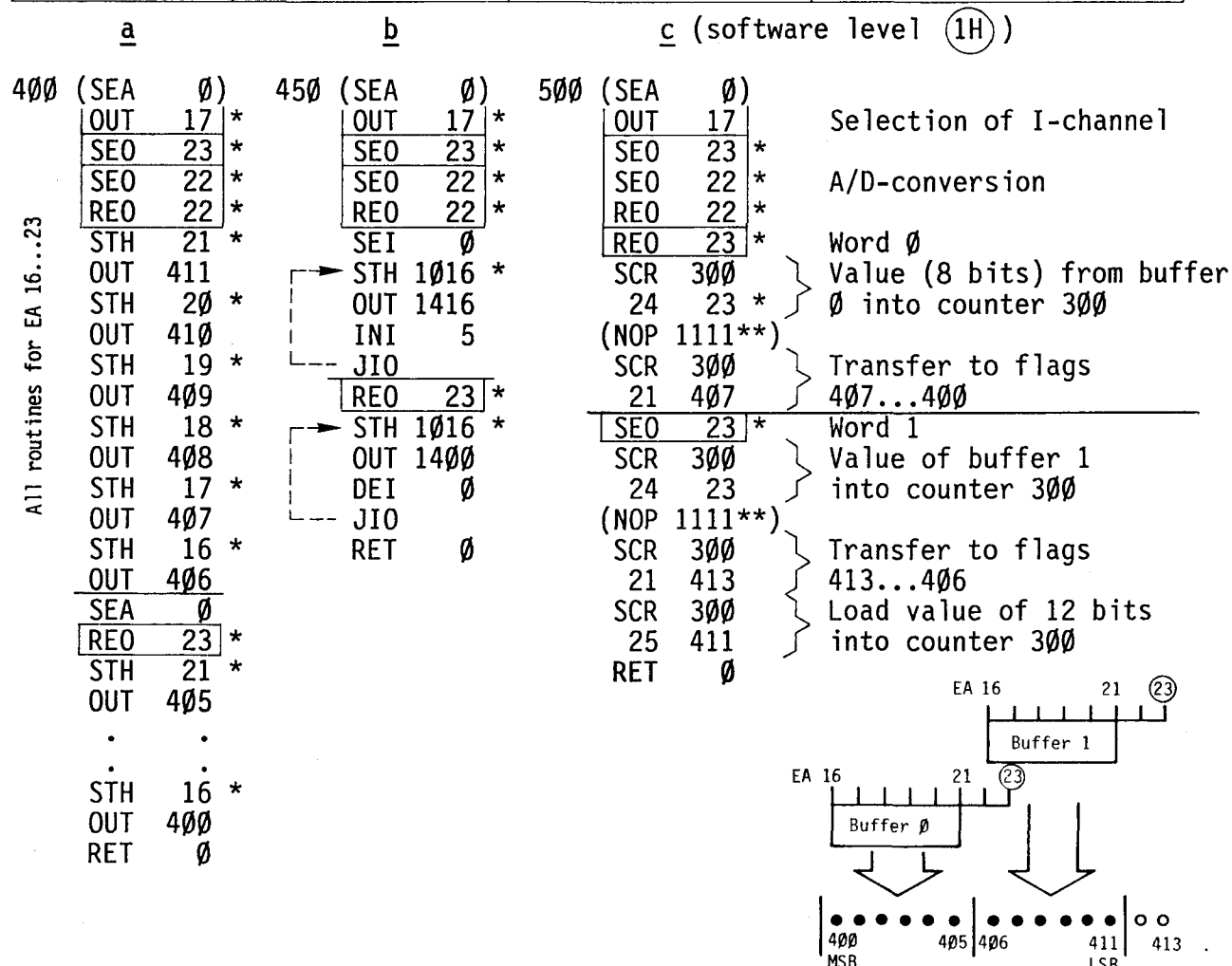
```
SEA 0
REO 7 *          Word 0
STH 5 *
OUT 405 *        Transfer 6 bits from
.         buffer 0 to flags
.         405...400
STH 0 *
OUT 400 *        *
```

\*) If the module is placed to a position other than 0, the corresponding basic address must be added.

Read the analog value in the form of a subroutine (input channel)

The following versions a to c are distinguished by their software levels, program lengths, execution times and the number of program changes. Version c results in the shortest execution time. With the standard execution time of 2.03 ms, however, the PP-change is blocked and the serial interface is no longer operated for this period. If the serial interface is to function with a baud rate of 4800 or 9600 bauds simultaneously, either version a or b can be used or version c with the commands NOP 1111 (operation of the data interface) given in brackets.

Subroutine version	Number of program lines	Execution time PCA14/15	Number of program changes (incl. RET) PCA14/15
a	30	3.10 ms	11
b	15	4.35 ms	13
c	17	2.03 ms	1



With all three versions the analog value is available as 12-bit binary value in the flag area 400...411. With version c the flags 412 and 413 are also used (because of the transfer of 8 bits instead of 6 bits). The routine c finally transfers the value to counter C300.

\* For basic address 16.

\*\* PCA14 as of version V6.034 for a baud rate of 9600 bauds.

### Output analog value (output channels)

The 12-bit digital value to be output must be applied at the inputs of the digital/analog converters. This value is stored by means of an instruction (ORH 0 or 1) and output as analog value by the D/A-converter. The unchanged analog values of the 2 outputs are available to the process as long as they are not redefined by another instruction.

In order to output an analog value from a bit pattern in the flag area, 3 steps are necessary:

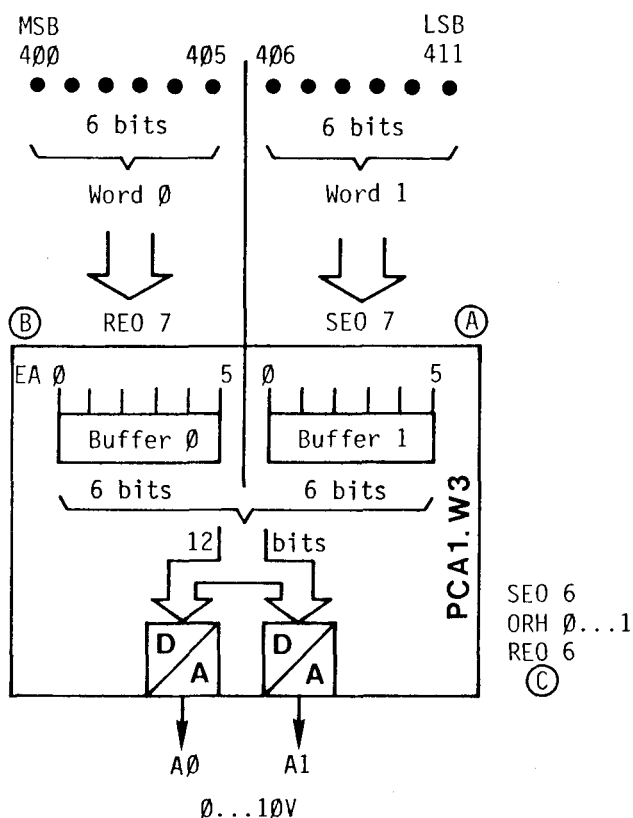
- A) Transfer the first 6 bits (starting with LSB) to buffer 1 (SEO 7)
- B) Transfer the second 6 bits (up to MSB) to buffer 0 (REO 7)  
Release of the D/A-conversion (SEO 6)
- C) Select the output channel with ORH 0...1 and trigger the D/A-conversion at the same time. Block D/A-conversion again (REO 6).

#### Program for EA 0...7

```
(SEA 0)
SEO 7 * Word 1
STH 411
OUT 5 *
STH 410
OUT 4 *
.
.
STH 406
OUT 0 *
} Transfer 6 bits to buffer 1 (A)
```

```
SEA 0
REO 7 * Word 0
STH 405
OUT 5 *
.
.
STH 400
OUT 0 *
SEA 0
SEO 6 *
} Transfer 6 bits to buffer 0 (B)
```

```
ORH 0...1 *
REO 6 *
} Release and blocking of the D/A-conversion
Select output channel 0...1 and output (C)
```

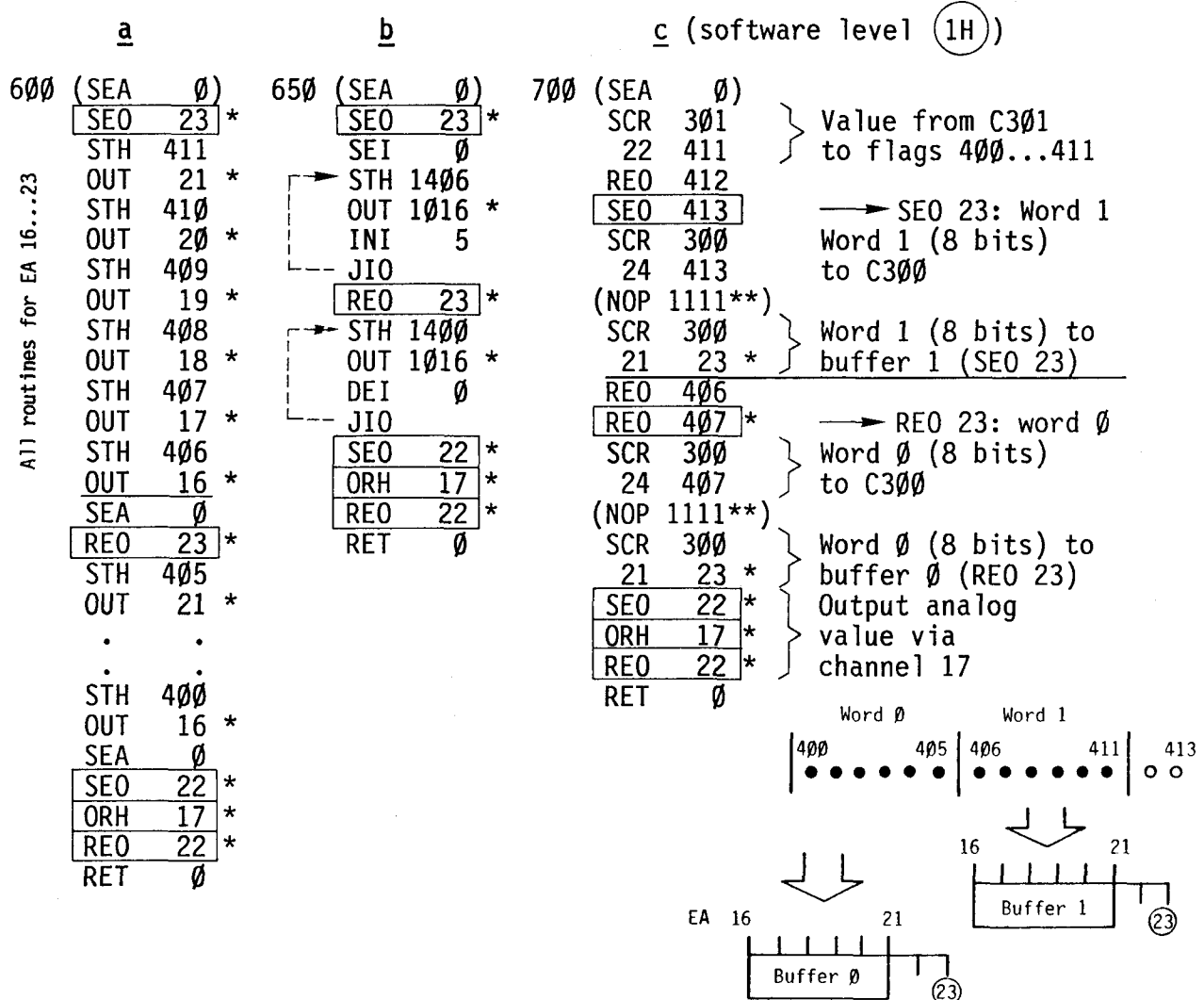


\*) If the module is placed to an address other than 0, the corresponding basic address must be added.

### Analog value output in the form of subroutines (output channels)

The following versions a to c are distinguished by their software levels, program lengths, execution times and the number of program changes. Version c results in the shortest execution time. Due to the standard execution time of 2.13 ms, however, the PP-change is blocked and the serial interface is no longer operated for this period. If the serial interface is to function simultaneously with a baud rate of 4800 or 9600 bauds, either version a or b can be used or version c with the commands NOP 1111 (operation of the data interface) given in brackets.

Subroutine version	Number of program lines	Execution time PCA14/15	Number of program changes (incl. RET) PCA14/15
a	31	3.09 ms	11
b	15	4.31 ms	13
c	18	2.13 ms	1



For versions a and b flags 400...411 are used. Version c uses counter C301 as an output register. 14 flags 400...413 are used in version c to load the buffers.

\* For basic address 16.

\*\* PCA14 from version V6.034 onwards for a baud rate of 9600 bauds.



### B 1.1.16 Type PCA1.W40 Analog input module for temperature sensor PT 100

#### Technical data

Number of inputs	6, electrically connected 2-, 3- or 4-wire technology, independent of each other
Temperature sensor	PT 100
Measuring ranges	-20°C to 150°C or 0° to 400°C 1)
Resolution	8 bits (1/256 $\approx$ 0,4%)
Accuracy (absolute deviation)	3 bits ( $\approx$ 1.2%)
Power supply per sensor	2mA
Time constant	dependent on the sensor response time
Internal power requirement 5V	40mA
24V	40mA

1) Measuring range selectable by jumpers:

Measuring range	Jumpers
-20°C to 150°C	A ; D (factory setting)
0°C to 400°C	B ; C

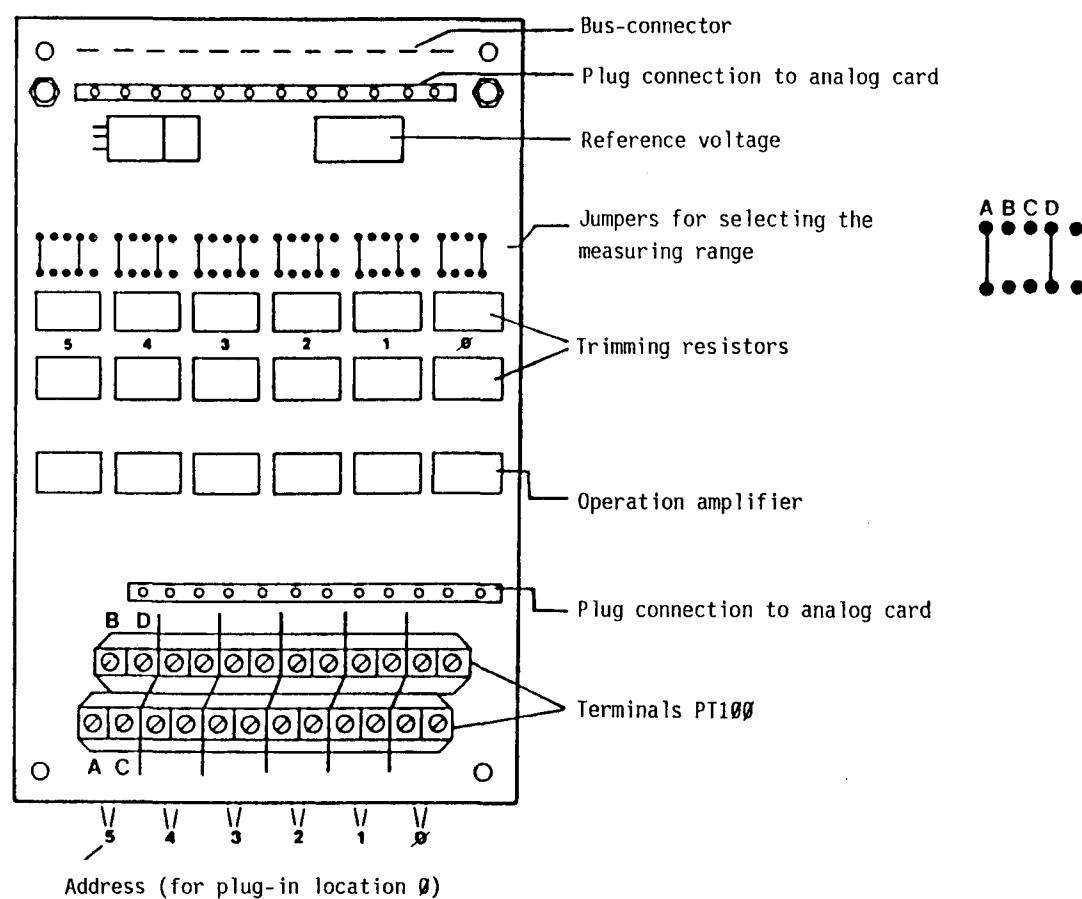
#### Resistance table PT 100/binary value PCA1.W40

Sensor temp. °C	Sensor res. R $\Omega$	Binary value	
		Meas. range -20°C - 150°C	Meas. range 0°C - 400°C
-20	92.2	0	(0)
0	100.0	30	0
65	125.15	128	42
150	157.28	255	96
200	175.76	(255)	128
400	246.60	(255)	255

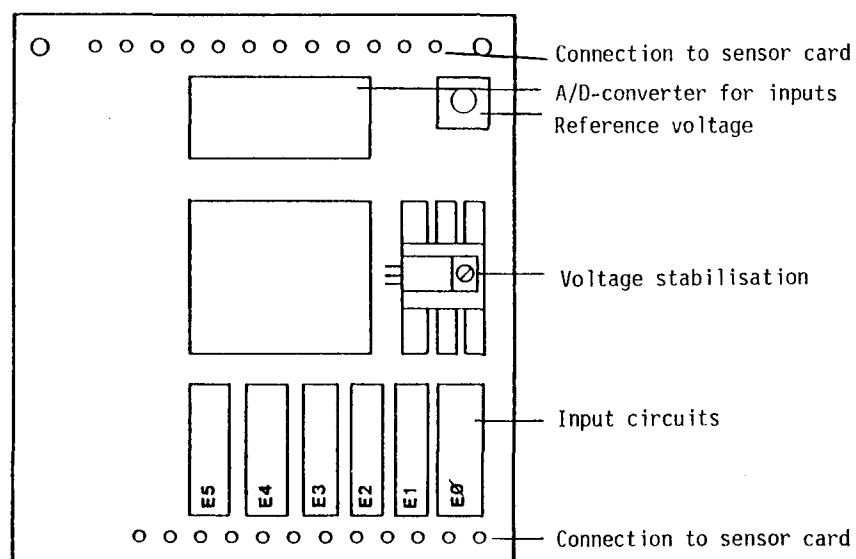
## Presentation

The analog module for the PT 100 temperature sensor consists of two pc-boards arranged on top of one another.

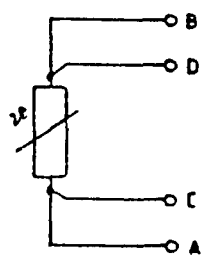
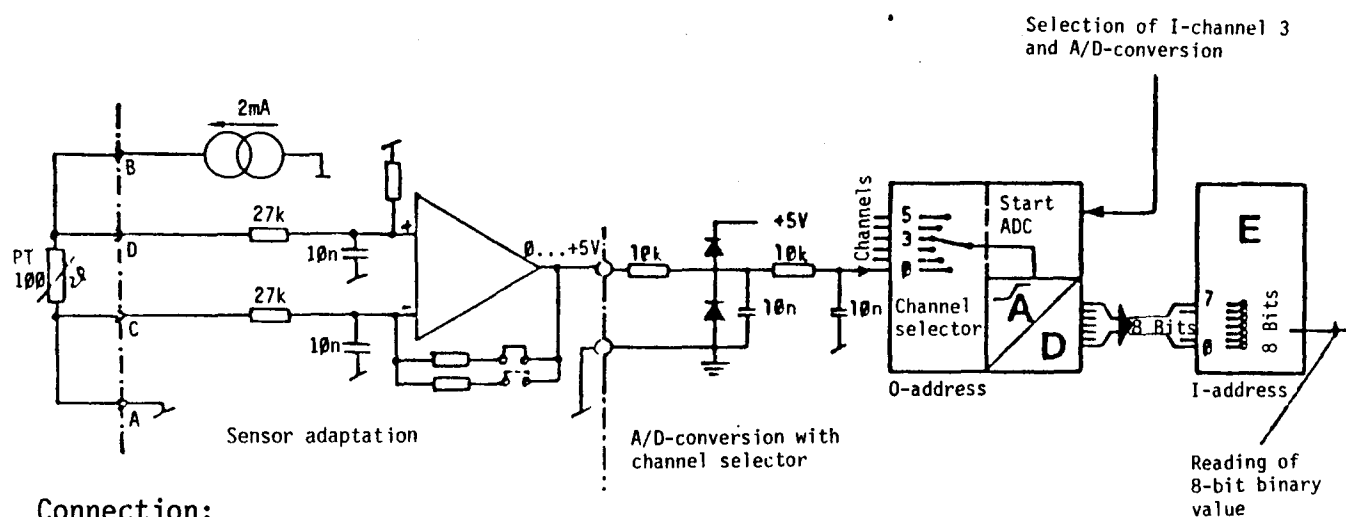
### Sensor adapter card (lower)



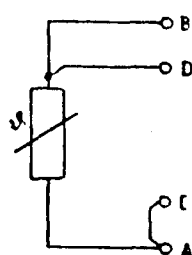
### Analog/digital card (upper)



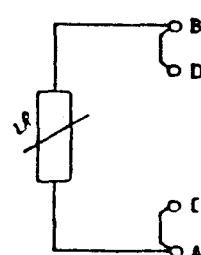
## Input/output circuit and block circuit diagram



4-wire technology



3-wire technology



2-wire technology

## Programming example for address range 0...7

Reading in the analog input value at channel 3 (ADDR 3). The corresponding binary value is to be transferred to counter C260.

100	OUT	3 <sup>1</sup>	Select I-channel 3 and start A/D-conversion
101	SCR	260	Read binary value of 8 bits to counter C260
102	24	7 <sup>1</sup>	

Please note the basic address, i.e. on which location the module is mounted.

Example with basic address 24: OUT 3 → OUT 27 (24+3)

SCR 260 → SCR 260  
24 7 → 24 31 (24+7)

### B 1.1.17 Type PCA1.F11/F12 Preselector module for entering numerical values

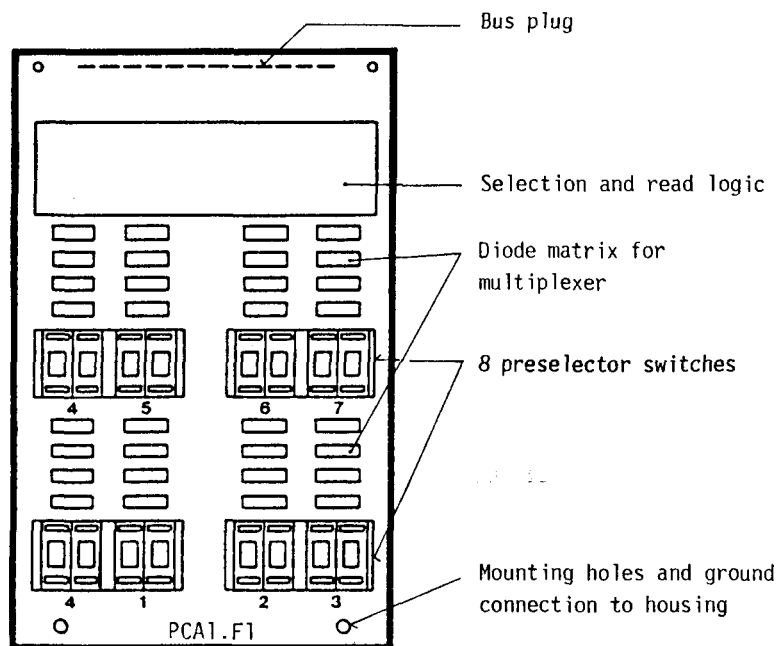
#### Application

With the preselector module numerical values can directly be entered without external wiring. If they are transmitted to the non-retentive flags or to counter registers, these values can be used as times, counter states or preselections of analog values.

#### Technical data

Number of input circuits	8
Range of digital values	00...99
Input mode	Multiplex
Internal power consumption of the module (5V)	30mA

#### Presentation and switch allocation

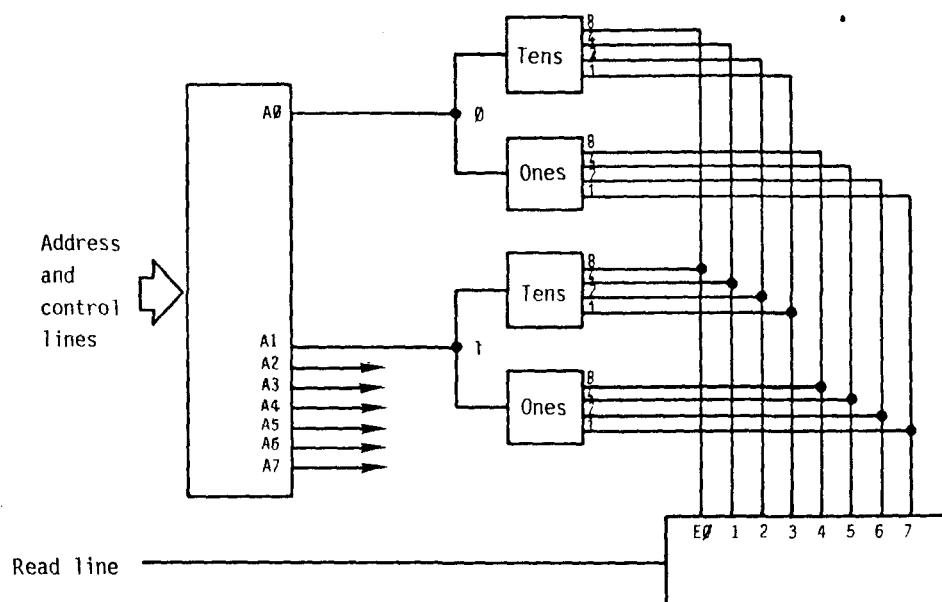


The following versions are available:

- PCA1.F11 with 4 pairs of preselectors, addresses 0...3
- PCA1.F12 with 8 pairs of preselectors, addresses 0...7

Due to removable BCD switches on sockets, every desired combination is feasible.

## Principle scheme



The allocated pair of preselector switches (ones and tens) is activated by setting of output A0...A7. The preselected value can be read from the 8 address elements E0...E7 and afterwards be written on a non-retentive flag or be loaded into the desired register by a set timer or set counter operation. The activated outputs have to be reset afterwards.

### Programming example:

The preselector module uses the address range 24...31.

- a) The 2-digit value selected by preselector 2 shall now be read and loaded into counter register 262.

```

.      .
(SEA   0)
SEO    26 ; Setting the pair of preselector switches (addr. 24+2)
SCR    262 ; Setting the counter with
16     31 ; BCD-input x 1
REO    26 ; Resetting the pair of preselector switches
.      .

```

- b) The value of pair 6 of the preselector switches shall be loaded into non-retentive flags 424...431.

```

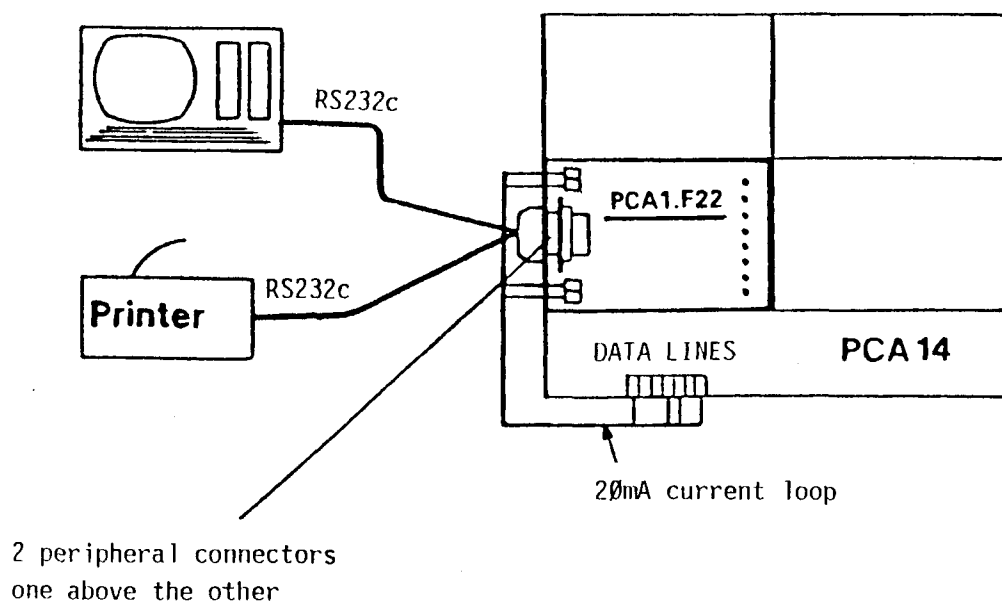
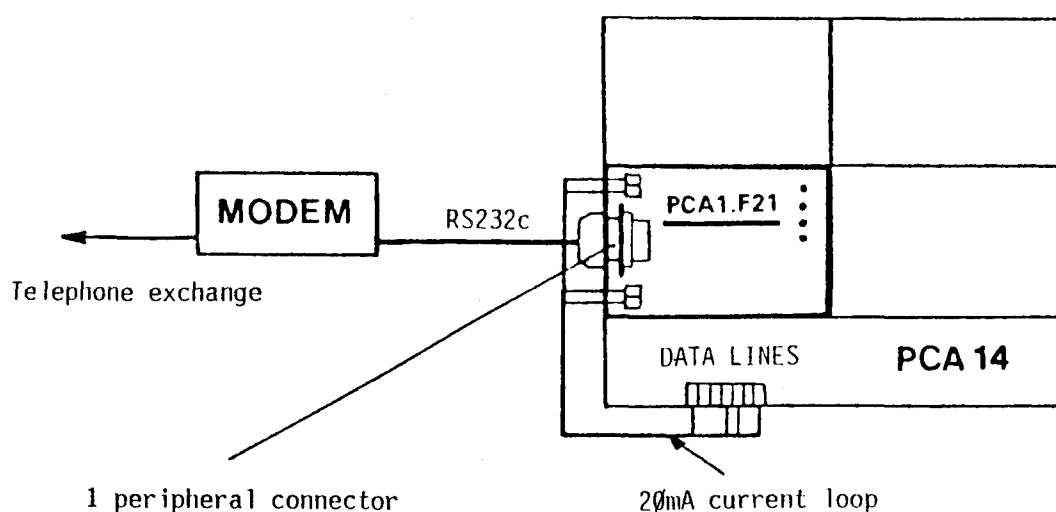
.      .
(SEA   0)
SEO    30 ; Setting the pair of preselector switches (addr. 24+6)
SEI    0
STH    1024
OUT    1424 } Transmission of value (8 bits)
INI    7
JIO    --
REO    30 ; Resetting the pair of preselector switches

```

### B 1.1.18 Type PCA1.F21/PCA1.F22 Data line switching module (only PCA14)

#### Application

The module PCA1.F21 is fitted with one, the module PCA1.F22 with two serial interfaces of the type RS 232c. Via the DATA LINES of the CPU PCA1.M4.. data can be transferred between the SAIA®PLC and the peripheral units connected to the PCA1.F2. The module PCA1.F21 is particularly suitable for connection to a modem.



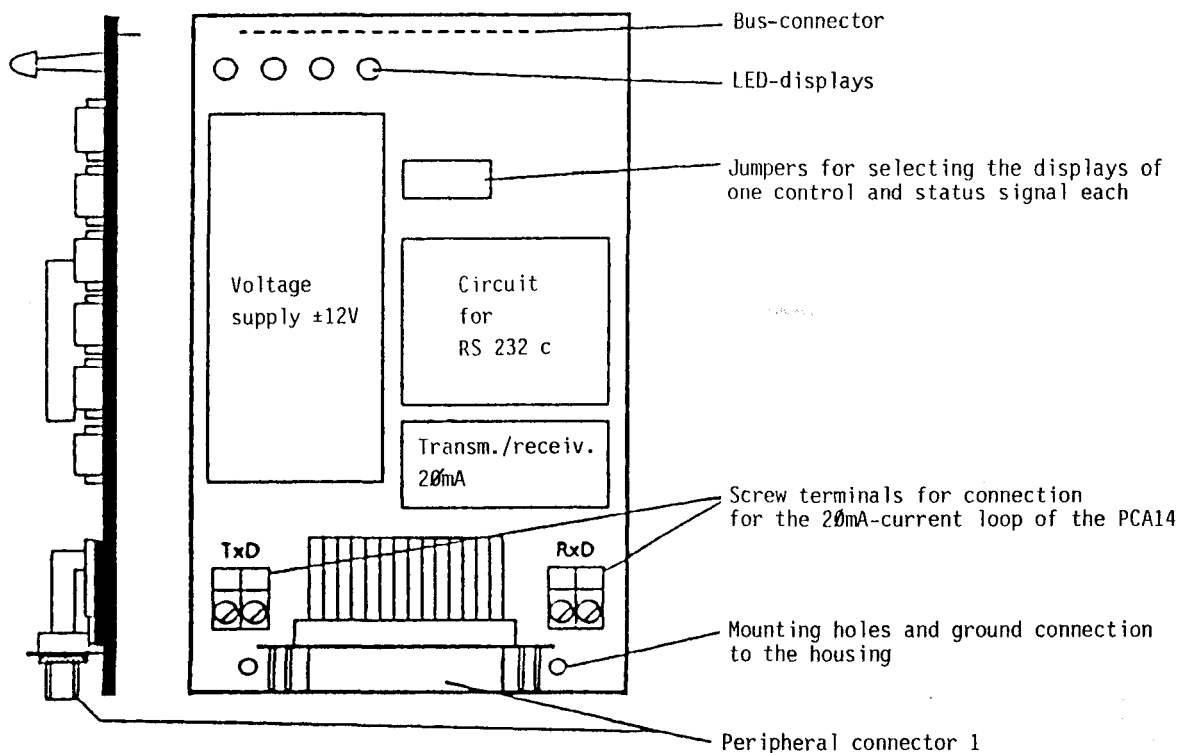
Technical data

	PCA1.F21	PCA1.F22	
Number of peripheral interfaces	1	2	
Type of interface	RS 232c	RS 232c	
Used addresses	8	8	
Data transfer	The data transfer is performed between the CPU PCA1.M4.. via PCA1.F21/F22 and the connected peripheral units.		
Management of the peripheral interfaces	By means of the user program with the corresponding control and status signals		
Number of control and status signals per peripheral interface	Total 6 <div>CTS } DSR } Readable signals (status signals) DCD }</div> <div>RTS } DTR } Settable signals (control signals) ADC }</div>		
Transmission speed	110 to max. 9600 bauds*, defined in the software by the PAS 100 instruction		
Signal level of the data lines (according to standard RS 232c)	"L" : + 12V "H" : - 12V		
Level of control and status signals (acc. to standard RS 232c)	"L" : - 12V "H" : + 12V		
Connector for RS 232c	25-pole miniature connector, female (for details refer to section "Pin assignment")		
Power consumption (internal)		F21	F22
	5V	125 mA	230 mA
	24V	26 mA	43 mA

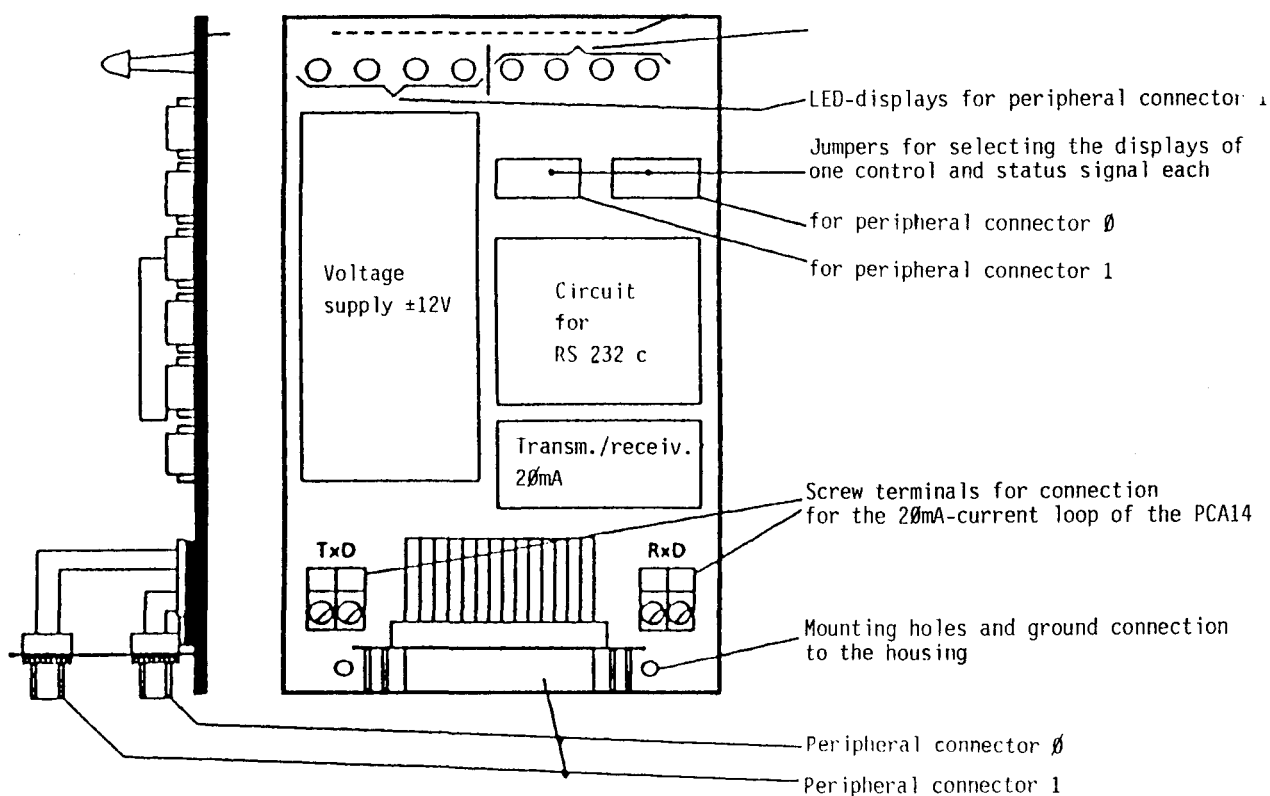
\*) High baud rates depend on the program structure.

## Presentation

### PCA1.F21



### PCA1.F22

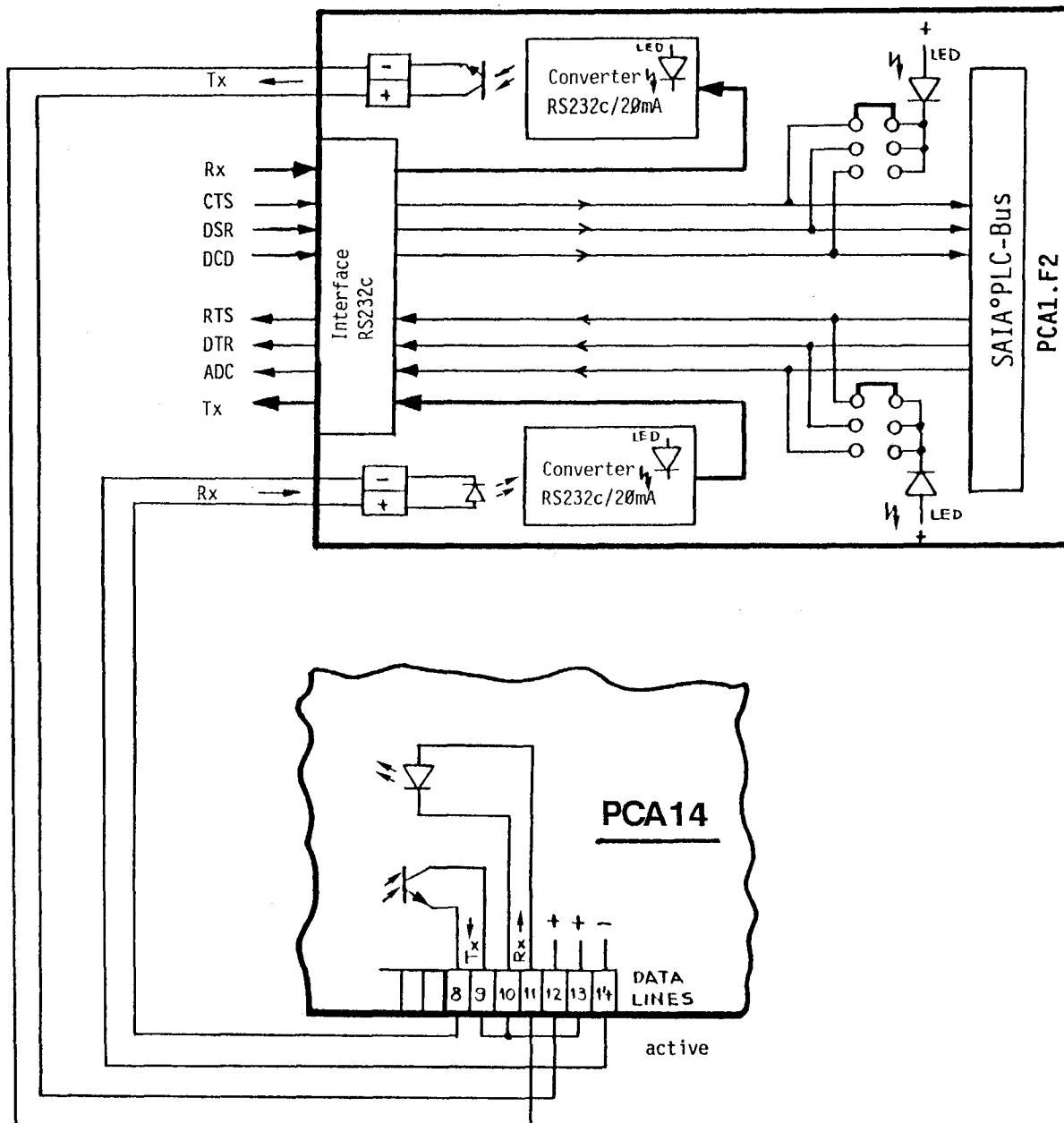




### DATA LINES connection between PCA1.F2 and PCA14

Like an I/O-module, the module PCA1.F2 can be plugged into any location on the PCA14. Wiring must be effected in such a way that the 20mA-current loop of the PCA14 is active.

The external connection CPU ---> F2 is performed observing the same rules which apply to the cable layout of a 20mA-current loop. Two PCA1.F2-modules can be connected in series resulting in an increase of the number of interfaces to max. 4.



### Address assignment and function of the signals

The peripheral interface of the PCA1.F21 or the two interfaces of the PCA1.F22 respectively must be managed by the user program. In order to make this possible, 3 status and 3 control signals each which can be set or read in the user program are available for each connector.

### Address assignment

	Address *	Abbreviation	Treatment
Connector 0 (PCA1.F22 only)	0	SEL 0	Settable and readable
	1	DTR DSR	Only settable Only readable
	2	RTS CTS	Only settable Only readable
	3	ADC DCD	Only settable Only readable
Connector 1	4	SEL 1	Settable and readable
	5	DTR DSR	Only settable Only readable
	6	RTS CTS	Only settable Only readable
	7	ADC DCD	Only settable Only readable

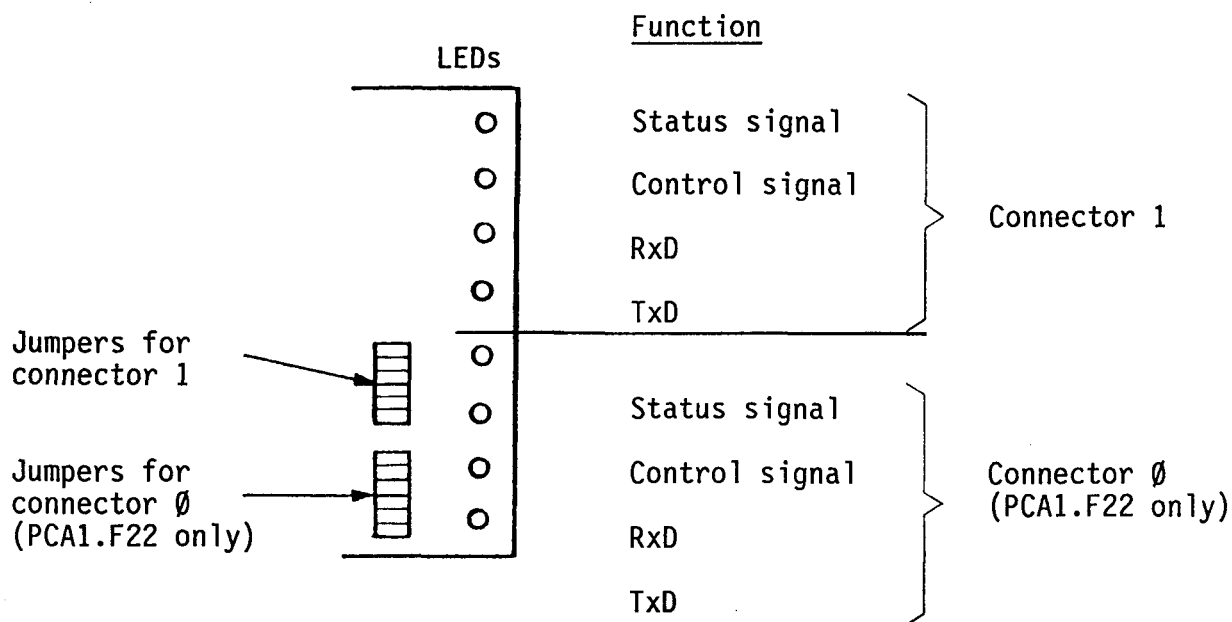
\*) The addresses are valid for the mounting location 0. The respective basic address must be added for other locations.

### Function of the control signals

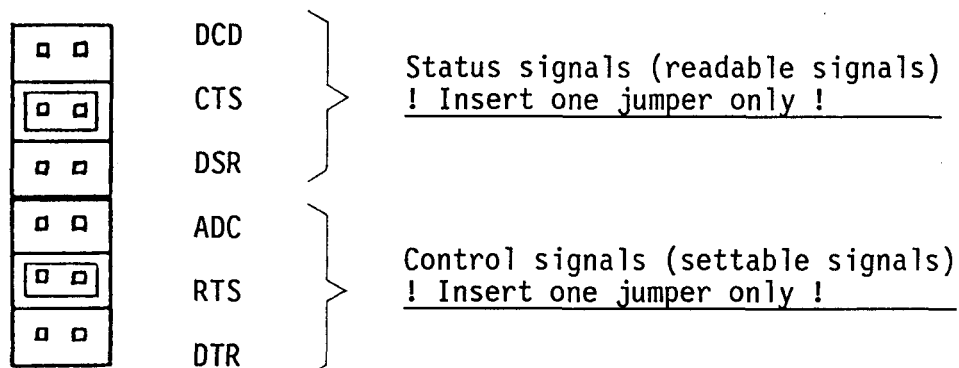
SEL 0, 1 (Select)	<p>With the instruction SE0 SEL 0, 1 the data lines (TxD, RxD) of the respective peripheral connector 0 or 1 are connected to the DATA LINES of the PCA14.</p> <p>With the read commands (e.g. STH SEL 0, 1) it can be determined which peripheral connector was connected to the DATA LINES.</p>
DTR (Data Terminal Ready)  RTS (Request to Send)  ADC (Auto Dialer Control)	<div style="display: flex; align-items: center;"> <div style="font-size: 3em; margin-right: 10px;">}</div> <div style="margin-right: 10px;">1)</div> <div> <p>These three signals are <u>control signals</u> as described in the standard RS 232c. They can be <u>set</u> in the user program, thus supplying certain instructions or states to the connected peripheral unit. The signals can be interpreted in different ways depending on the peripheral unit.</p> </div> </div>
DSR (Data Set Ready)  CTS (Clear to Send)  DCD (Data Carrier Detect)	<div style="display: flex; align-items: center;"> <div style="font-size: 3em; margin-right: 10px;">}</div> <div style="margin-right: 10px;">1)</div> <div> <p>These three signals are <u>status signals</u> as described in the standard RS 232c. They can be <u>read</u> in the user program. The individual signals are interpreted depending on the peripheral unit and must be processed correspondingly in the user program.</p> </div> </div>

- 1) Similar to the input/output module PCA1.B90 two signals each use the same address. (DTR/DSR, RTS/CTS, ADC/DCD). Consequently, one signal can only be set, the other one can only be read (see also "Address assignment").

## Meaning of the LEDs



Jumpers for status and control signals:



For each connector 1 status signal and 1 control signal each can be displayed on the corresponding LED. The jumpers can be reinserted during operation, which permits checking the function of the connected peripheral unit.

If no jumper is inserted for the status or control signals, the corresponding LED is permanently illuminated.

The LEDs "TxD" and "RxD" light up, if data is being transmitted or received. Depending on the baud rate and telegram length only a short flash or a long flickering is recognized.

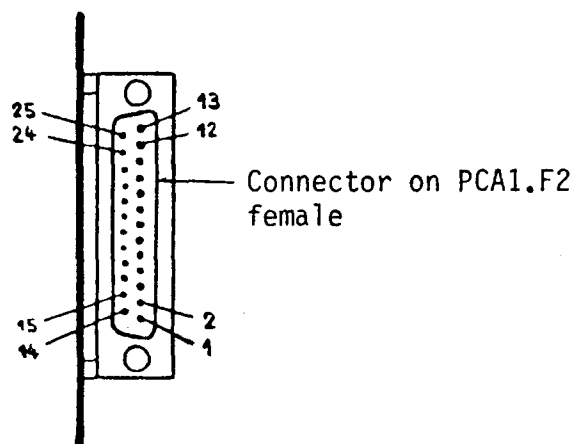
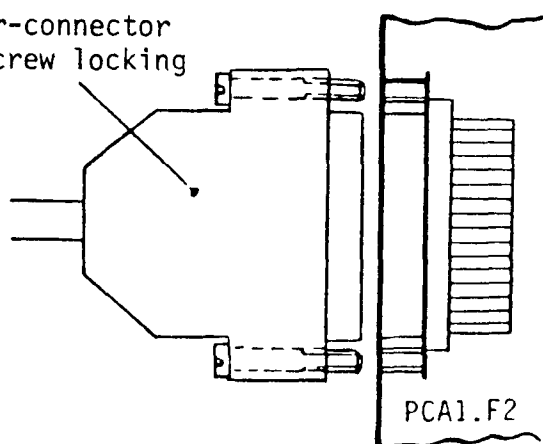
### RS 232c interface cable

The standardized guidelines hold true for laying the signal cable of the RS 232c, i.e. screened cable with a max. length of 15m (if possible not in the same cable duct as the power cables).

### Pin assignment (according to RS 232c)

Pin no.	Abbreviation	Signal name	Direction of signal	
			Periph.	PLC
1	PGN	Protective Ground		
2	TxD	Transmitted Data	←	
3	RxD	Received Data		→
4	RTS	Request to Send	←	
5	CTS	Clear to Send		→
6	DSR	Data Set Ready		→
7	SGN	Signal Ground		
8	DCD	Data Carrier Detect		→
9	ADC	Auto Dialer Control	←	
20	DTR	Data Terminal Ready	←	
18	- 12V	I <sub>max</sub> : 5mA		
21	+ 12V	I <sub>max</sub> : 5mA		

Counter-connector  
with screw locking

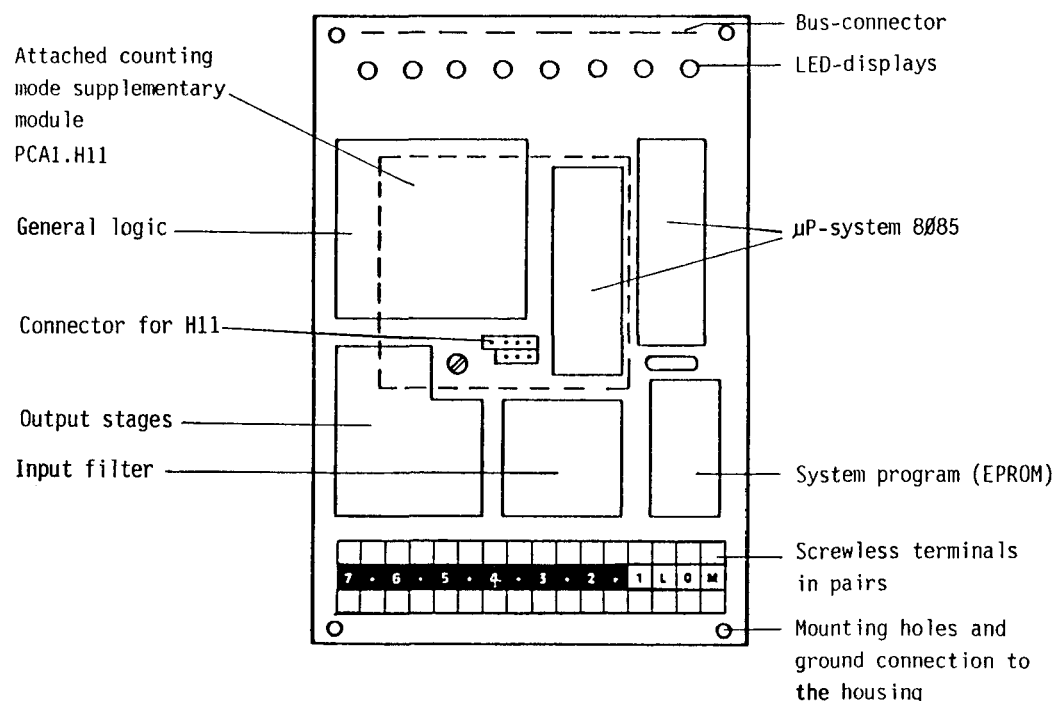


### B 1.1.19 Type PCA1.H1.. Rapid counter or pulse generator up to 10kHz, 6 decades

#### Applications

- Counting of pulses up to a frequency of 10kHz: For example, from pulse generators, which are used for the determination of angles of rotation, throughput quantities, number of items or digital lengths.
- Recognition of the sense of rotation with 2-channel incremental shaft encoders: For example, for positioning with DC-current motors and connected pulse generators.
- Output of control pulses (2-fold): This allows positioning of x-y-tables, palletizing devices, handling robots with an appropriate stepping motor control.
- Measuring of frequencies, period lengths or pulse lengths, e.g. for determining the speed, number of revolutions, flow, synchronization, frequency, etc.
- Output of register contents to display modules PCA2.D12 (4 decades) or PCA2.D14 (2 x 6 decades).

#### Presentation



#### Detailed documentation and software modules

The detailed manual is available in German and English and consists of about 100 pages.

It also includes software modules and practical examples of application. The software modules may also be used as macros for the SAIA°PCA ASSEMBLER.

Please contact our selling agencies.

## Technical data

### Counter module PCA1.H10

Number of counting systems	1
Counting frequency	max. 10kHz
Counting capacity	max. 999'999 (6 decades)
Counting direction	up and down
Data memory	volatile (data can be saved via CPU-registers)
Counter state display	with 2 display modules PCA2.D12
Inputs	<ul style="list-style-type: none"> <li>- clock for counting pulses</li> <li>- up/down for counting direction</li> </ul> <p>Display of the logic states by 2 LEDs</p> <p>24VDC/10mA, source or sink operation input delay 50µs</p>
Outputs	<p>Direct coincidence outputs</p> <ul style="list-style-type: none"> <li>- COOR: Low if Z = R</li> <li>- COOP: Low if Z = Ø</li> </ul> <p>High by setting in the user program</p> <p>Outputs comparator or display mode</p> <ul style="list-style-type: none"> <li>- Z &gt; R</li> <li>- Z = R</li> <li>- Z &lt; R</li> <li>- Z = Ø</li> </ul> <p>Display mode selectable via user program</p> <p>Display of the logic states by 6 LEDs</p> <p>5...32VDC/500mA, positive switching load resistance min. 48Ω for 5...24V</p>
Connection	Pairs of screwless terminals

### Counting mode supplementary module PCA1.H11 (can be plugged onto counter module)

Counting modes	phase decoder (M1) or up/down mode (M2), can be selected by plug-in jumpers
Phase decoder (M1)	2-phase at inputs A and B, type of pulse processing (x1, x2, x4) selectable with plug-in jumpers
Up/down mode (M2)	Pulses at input A counting up, Pulses at input B counting down
Inputs A and B	24VDC/10mA, source or sink operation input delay 50µs
Counting frequency	max. 10kHz

### Counter module PCA1.H10 as pulse generator

(the same module functions either as counter or pulse generator)

Number of channels	2
Frequency	max. 10kHz
Frequency selection	via user program divisible into steps of approx. 5%
Stability	better than 0.1% above the temperature range
Signal	symmetrical square-wave signal
Start generator	via the user program
Stop generator	after output of the programmed number of pulses or via inputs stop
Single pulse	via user program pulse length according to the programmed frequency
Outputs	<ul style="list-style-type: none"> <li>- F01: Generator 1</li> <li>- F02: Generator 2</li> </ul> <p>Supply voltage 5...32VDC/500mA, positive switching</p>

### Counter module PCA1.H10 as measuring module (identical hardware)

Number of channels	2
Measuring frequency	max. 5kHz
Accuracy	1% (25°C)
Modes (software)	<ul style="list-style-type: none"> <li>- Frequency measurement</li> <li>- Period length measurement</li> <li>- Pulse measurement</li> </ul>
Frequency measurement	Duration 6-digit in ms
Period length	Number of periods to be measured, 6-digit
Pulse length	Number of pulses to be measured, 6-digit
Inputs	E1 signal input
Outputs	<p>A7 duration of measurement</p> <p>A6 overflow</p>

### Available versions

PCA1.H10 Counter module for series PCA1  
(alternatively usable as pulse generator)  
PCA1.H11 Counting mode supplementary module (delivered separately)

In order to diminish the internal power consumption (at 5V) from 350mA to 190mA, a special version using CMOS technology was developed. It is referred to as PCA1.H10 Z16. This is now the standard version.

### B 1.2 Internal power requirement of the PCA1 modules

The internal power supply for 5V and 24VDC is provided by the power supply unit in the basic module or extension module respectively. The total current required for CPU, I/O-modules and programming or display module must not exceed the nominal power handling capacity.

Nominal power handling capacity of the internal power supply and constant loads of CPU, D11, D13, P10 and P05.

Nominal power handling capacity of the power supplies of PCA1.M4.., M5.., C45	5V side mA <u>1'700</u>	24V side mA <u>800</u>
Power requirement CPU M4..	600	0
CPU M5..	450	0
Extension C45 *	90	0
Power requirement D11	100	0
D13	10	0
(D12)	0	external
(P10)	(200)	0
(P05)	(150)	0

\*) It must be noted that the ..C45 extension is able to supply about 500mA more current than the M4/M5 modules, because of the removal of the CPU on the 5V side.



### Power requirement of the PCA1 I/O-modules

Series PCA1	I at 5V (A)		I at 25V (A)	
	H (max.)	L (min.)	H (max.)	L (min.)
E10/E11	68	11	0	0
E20	70	10	0	0
E40	70	15	0	0
E50	68	11	0	0
A10	146	86	7	18
A21	90	34	140	0
A30	100	26	7	7
A50	90	35	30	0
B10	112	54	4	9
B80	120	30	0	0
B90	105	50	50	50
F12	30	30	0	0
F21	125	125	25	25
F22	230	230	45	45
W12	40	30	25	25
W24	70	60	70	40
W32	120	100	100	60
W40	appr. 40	appr. 40	appr. 40	appr. 40
H10 Z16	190	190	55	55
H10	350	350	55	55
H11	22	22	--	--
R20	85	85	--	--
R20 + R25	95	95	--	--

H: all LED are on or max.

L: all LED are off or min.

#### Example:

	50% I/O = H	
	5V/mA	24V/mA
PCA1.M47	600	0
4 x B90	210 + 100	100 + 100
2 x A10	146 + 86	7 + 18
2 x A21	90 + 34	140
1 x P10	200	0
TOTAL	1466 mA	365 mA

( < 1700 mA )    ( < 800 mA )



## B 2 Programming units, additional units and accessories

### Additional units used for programming (simulation, starting-up, documentation)

P05	Hand-held programming unit	PCA2.P05
P01	Programming interface	PCA0.P01
S10	Input simulation unit	PCA2.S10
K80	Cable	PCA1.K80
S05	Input simulation unit	PCA2.S05
P18	Programming unit	PCA2.P18
PCASS	SAIA°PCA ASSEMBLER	PCASS
P16	EPROM-Kopiergerät	PCA2.P16

### Memory modules

R95	Memory module 4K, non-volatile	PCA1.R95
R96	Memory module 4K, non-volatile	PCA1.R96
R20	Text memory extension module	PCA1.R20
R25	Data memory extension module	PCA1.R25

### Display modules

D11	Display module, 4-digit	PCA1.D11
D12	Display module (remote display), 4-digit	PCA2.D12
D13	Display interface for D12	PCA1.D13
D14	Display module (remote display), 2x6-digit	PCA2.D14

### External interface module, type KOM

KOM 111B	Dual-input interface, 220 VAC, type D4, output 24VDC/40mA pulsating per input
KOM 111B	Dual-input interface, 110 VAC, type C8, output 24VDC/40mA pulsating per input
KOM 121B	Dual-relay output interface, type M4
	Switching power AC1 : 6A, 250 VAC (per output)
	AC11: 1A, 250 VAC (per output)

## B 2.1 Programming units

### B 2.1.1 Hand-held programming unit PCA2.P05

This compact programming unit was developed in particular for the series PCA0, but it can also be used for the series PCA1 and PCA2.

All operating modes can be selected with keys. Programming is performed in the "PROG"-operating mode by means of a 10-part keyboard in simple numerical code. All elements (inputs, outputs, flags, timers, counters) can be queried or set in the "MAN"-operating mode.

All timer and counter values can be indicated in the RUN-mode. In the operating mode "STEP" a jump can be effected to any program line (= step address) of the user memory. Finally, "BREAK" permits the program processing up to a set break-point and continuation in step-by-step operation. For details refer to chapter C "Operating modes".

It must be noted that the keys for selecting the operating modes must be pressed at least 0.5s for safety reasons. The selected mode is displayed by the corresponding LED.

In the case of PCA14, the operating modes are selected with the sliding switch on the basic module.

Connecting cable for PGU-connector

Indication where input is effected

Display of a program line (7-segment-LED)

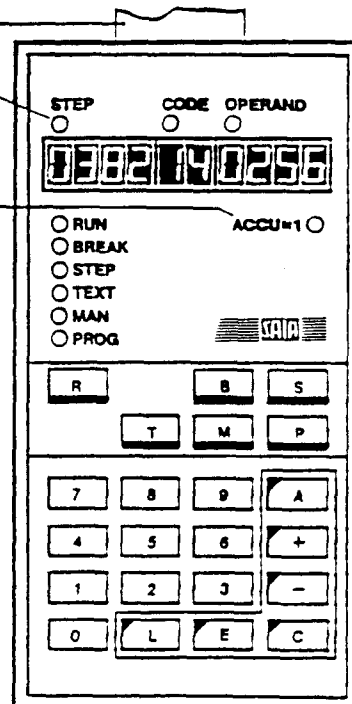
Display of the accumulator status (ACCU)

Display of the selected operating mode

Keys for the selection of the operating modes

(PCA 15)

16-part keyboard  
with 10-part block and 6 function keys

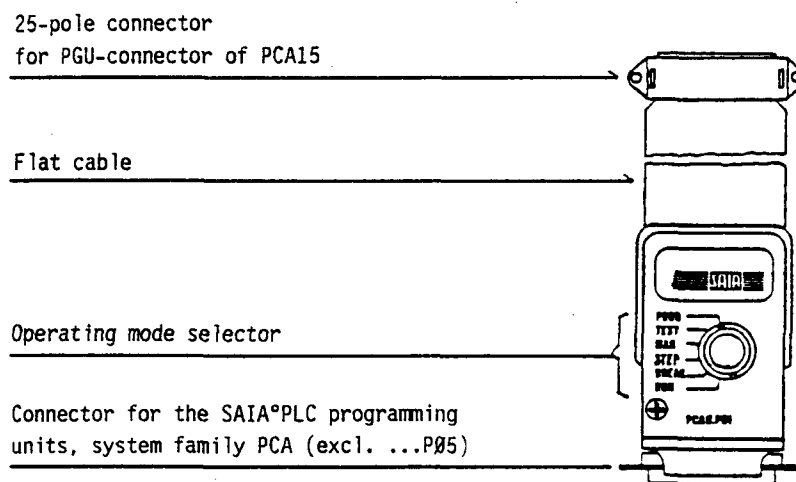


### B 2.1.2 Programming interface PCA0.P01 for PCA15

This interface allows connection of the following SAIA®PLC programming units to the series PCA15:

- PCA2.P18 - Hand-held computer with a wide range of possibilities  
(from software version V18-04 onwards)
- PCASS - IBM-PC with SAIA®PCA-ASSEMBLER

As a result, all upwards compatible tools of the SAIA®PLC, system family PCA, are available also for the PCA15.

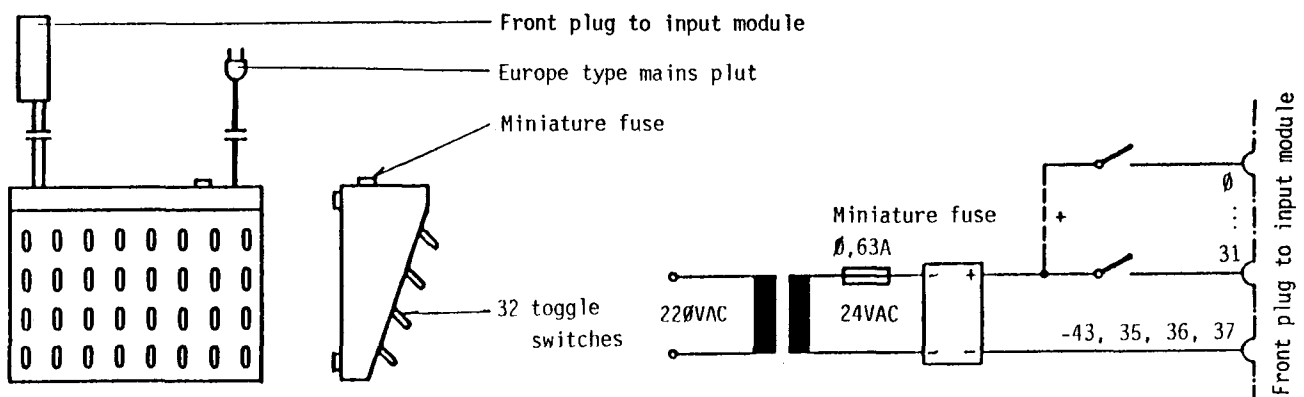


### B 2.1.3 PCA2.S10 Input simulation unit

Its purpose is to simulate input signals via toggle switches so that a program can be tested "at the desk". This considerably facilitates the commissioning of the actual control system.

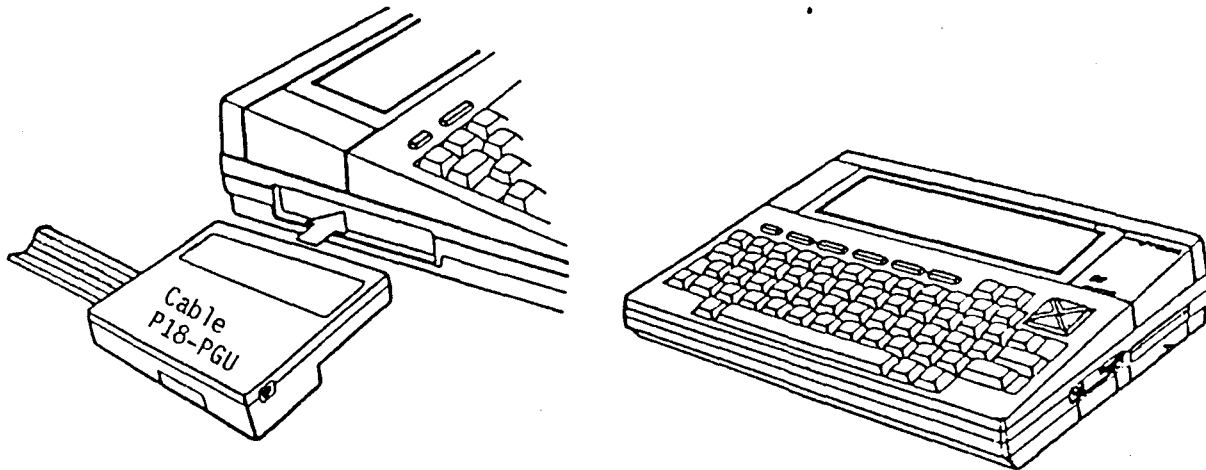
A transformer with rectifier is supplied from a mains cable. From the rectifier is a branch to 32 numbered toggle switches, the signals from which are fed to the PLC inputs via a system cable and plug.

Ordering designation for connection to 220VAC: PCA2.S10 D4





### B 2.1.5 Programming unit PCA2.P18



#### Brief description

The programming unit PCA2.P18 is a compact and versatile means which can be used for programming all SAIA°PLC as well as for servicing.

The P18 uses the commercial hand-held computer, type NEC 8201A, as hardware. Compactness combined with a high degree of intelligence, an efficient firm-ware and a variety of peripherals form an ideal portable programming unit, be it on your desk or out in the field.

With the SAIA°PLC connected (via PGU-connector), the P18 makes programming very easy. Moreover, SAIA°PLC texts can be edited or all PLC-registers can be accessed on-line for servicing purposes via the 20mA-data line of the PCA14 and PCA15.

In short, the following functions are possible:

- Programming in numerical or mnemonic code
- Display of program sections and texts
- Search functions
- Storage and loading of user programs and texts
- Printing of programs (on an external printer)
- Editing and output of SAIA°PLC texts
- Acces to data and registers of the SAIA°PLC while user program is running.

Thanks to the permanently stored BASIC-interpreter and the text processing program, the P18 can also be used as a portable personal computer. Numerous additional interfaces and the corresponding software support communication with peripheral units such as printer, modem, tape unit, disk drive unit and bar code reader.

A detailed description is supplied with each unit.

### B 2.1.6 SAIA°PCA ASSEMBLER

#### The software package SAIA°PCA ASSEMBLER for comfortable programming, documentation and starting-up

The PCA-ASSEMBLER makes programming of the PCA-family of controllers very easy. The user is efficiently supported in his work by practical menus and the appropriate auxiliary pages which means that he virtually does not require a manual or a knowledge of MS-DOS.

The user program is written in the so-called "Editor" using a conventional text processing program (e.g. Personal Editor or Wordstar). It is possible to use practice-oriented designations for the operands to mark jumps in the form of symbols and labels which are then converted to a PCA-program by the actual "Assembler" and "Linker". Macros with parameters can be implemented for frequently used routines and comments can be used for clearly documenting the new program.

Further possibilities of the new PCA assembler include the modular and global documentation, presentation as flow-charts, an efficient cross-reference list and it is also possible to load the program directly into the RAM-memory of the PCA.

Its advantages become obvious particularly when the controller is started up. In RUN-mode the "Online Debugger" allows the actual states of elements such as inputs, outputs, flags, timers, counters, registers and the date-time to be displayed and also modified. The programs "PIØ" and "CI" permit direct access to the RAM user memory of all PCAs. By selecting the submenu "Program eproms", tested user programs can be directly loaded into the EPROM programming units PCA2.P16 or ERTEC PGS49.

The software package SAIA°PCA ASSEMBLER can be run on all IBM-PC/XT/AT or PS/2 or compatible units which fulfil the following conditions:

- 512 Kbyte main memory
- 2 floppy disk drives of 360K or even better 1 floppy disk drive and a hard disk
- 1 or even better 2 bidirectional, parallel interfaces for controlling a printer and for connection to the PGU-connector of the PCA
- Monochrome or colour VDU (with MCGA, CGA, EGA, VGA or Hercules cards)
- Keyboard as desired
- Operating system MS-DOS 3.0 or a higher version
- Cable PCA2.K43 for connection to the PGU-connector of the PCA
- Text processing program as desired (Personal Editor and Wordstar are recommended)

A detailed description is available for every software package.



## Screen

### Main menu of PCA-ASSEMBLER

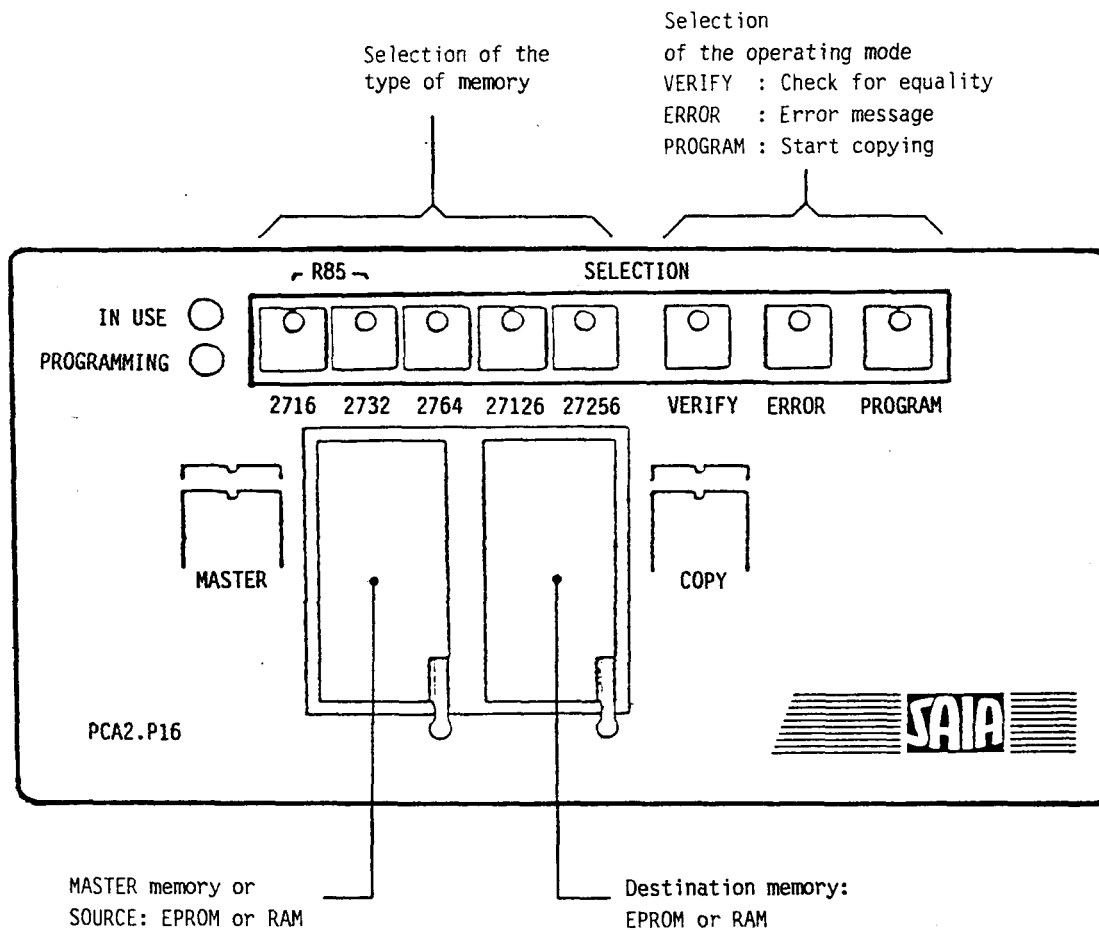
SAIA PCA ASSEMBLER V1.1		MAIN MENU
***** SAIA AG Marktbereich CH 3280 Murten *****		
Directory: C:\PCASS		16.12.88 13.30
Edit	Text assembler	Compare programs
Assemble	Disassembler	Xref listing
Link	flow chart	File handling
Up/download	Runtime analysis	Ms-dos command
<b>Online debug</b>	Hex converter	Setup
comms Interface	Program eeproms	Quit
<ARROW>, <SPACE> or <Tab> selects operation, <CR> or <Command letter> executes		

### ONLINE DEBUG menu of PCA-ASSEMBLER

SAIA PCA ONLINE DEBUG V3.4	
<b>Display</b> C260 2090 e12 0011 0010 B200 EE EF FF 3D 67  Σ0 1101 0000 0100 0011 T256 2163	<b>Clock</b> yy dd yy mo dm hh mm ss 48 03 88 12 15 17 05 58  <b>Program</b> A 1 03 2 A 2 03 7 A 3 10 12 A 4 10 21 A 5 10 13 A 6 10 24 A 7 14 256 A 8 00 500 A 9 01 256 A 10 10 25 A 11 20 0
<b>Write</b> <div style="border: 1px solid black; height: 20px; width: 100%;"></div>	
Display Write Program clock Save Load comms-Interface Reset Quit	

### B 2.1.7 Type PCA2.P16 EPROM-copying unit

Owing to two high- quality sockets (Texttool) the unit can be used for copying and comparing EPROMs and buffered RAMs independently of other units. The serial interface RS 232c permits connection of any commercial personal computer. A program supporting operation of the P16 from the IBM-PC is part of the PCA-assembler (package no. 3).



The P16 meets especially the requirements of the SAIA<sup>®</sup>PLC. In addition to the usual EPROM types 2716 to 27256, the buffered RAMs PCA1.R95 and PCA1.R96 can be written to and read.

### Technical data

Supply voltage	220 VAC 50 Hz $\pm$ 10%
Power requirement	20 VA
Microprocessor	MC 6809
Serial interface	RS 232c (9600, 2400, 1200 and 300 bauds)
Dimensions	222 x 47 x 172 mm (W x H x D)
Weight	1.7 kg

With the P16 the following memory modules can be programmed:

Type	Programming voltage:
2716	25V
2732	25V 1) 3)
2732A	21V 1)
2764	21V
27128	21V
27256	21V 2)
2816	3)
PCA1.R95 (buffered RAM)	
PCA1.R96 (buffered RAM)	

- 1) For the type 2732A the P16 has been set to a programming voltage of 21V (factory setting).  
For the type 2732 which has a programming voltage of 25V, a jumper needs to be re-soldered on the pc-board EP 80 067.
- 2) For the type 27256, which has a programming voltage of 12.5V, the resistor R3 (3k6) needs to be changed to 2k on the pc-board EP 80 066.
- 3) Do not use with SAIA<sup>®</sup>PLC.

### Copying

During copying, data is read from a master-IC and written to a copying-IC. When working without the Personal Computer, i.e. without using the serial interface, copying can usually be performed only using the same types of EPROM. However, mixed operation is possible using the EPROM 2764 and buffered RAMs PCA2.R95 or PCA2.R96. Only the entire memory contents can be copied from the MASTER socket to the COPY socket.

1. Select the copying EPROM with the appropriate key. The corresponding LED lights up. For the EPROM-emulators R95 and R96 the keys 2716 and 2732 must be pressed simultaneously.
2. Insert the master-IC and the copy-IC in the frames. Take care that the notch or pin 1 respectively is at the top on the left.  
The ICs are retained in the frames by pressing down the levers. In the case of the 24-pole ICs it must be noted that the upper contact openings must not be covered.

3. Press key "PROGRAM". The LED "IN USE" lights up for a short time. During this time a check is performed to determine whether the memory module to be programmed has been erased. Afterwards the LED "PROGRAMMING" also lights up until programming is finished. Any errors which occur during programming, are displayed by the flashing LED "ERROR". Moreover, an LED lights up in the keys indicating the type of error.

#### Error messages

Key 2716 : EPROM cannot be programmed  
 Key 2732 : EPROM has not been erased  
 Key 2764 : EPROMs are different  
 Key 27128: EPROMs are different and copy-IC empty  
 Key 27256: 2816 cannot be erased

The error display is cleared with the key "ERROR".

#### Comparing

The procedure is similar to copying. However, The LED "PROGRAMMING" does not light up. Proceed as follows:

1. Select copying-EPROM with the appropriate key.
2. Press key 'VERIFY'.

If no error message appears, the contents of the two memory modules are the same. The flashing LED "ERROR" indicates an error (see list of errors).

#### Erasing the 2816 (EEPROM)

In order to erase the 2816, press the key 'ERROR' and '2716' simultaneously.

Important: The memory module 2816 cannot be used together with the SAIA°PLC.

#### Serial interface RS 232c

The integrated serial interface offers the experienced user manifold possibilities of programming the P16 from a Personal Computer. See also chapter B.6 of the manual PCA2.P16.

When the PCA2.K46 cable is used, the transfer of data is supported under menu-guidance by the SAIA°PCA ASSEMBLER with the "Program eproms" program.

### B 2.1.8 Type PCA1.R95/R96 Buffered RAM chip

RAM-memories are read-/write-memories, which means that the information can be modified at any time with the aid of a programming unit (as data memory in the PCA14 also via the user program).

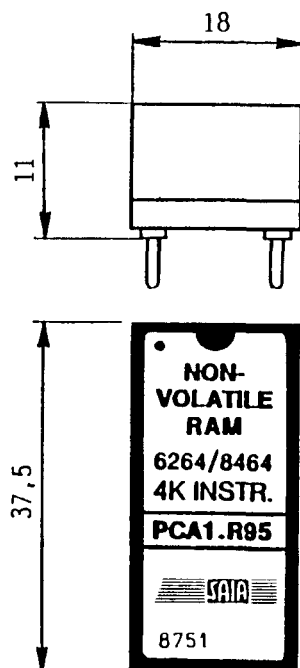
The buffered RAM chip is the ideal memory chip serving as a program and text memory from the programming stage to the start-up. Owing to the incorporated buffer battery and the protective electronic system this memory chip can be detached from the PLC and transported without modifying its contents.

The slightly conductive plastic socket protects the pins against static charges, thus avoiding memory content changes. The internal battery is thereby not discharged.

Memory type	PCA1.R95	PCA1.R96
Storage capacity		
- Program lines	4K	4K
- Texts, data	8K	8K
Number of pins	28	28
Buffer battery life	approx. 8 years	approx. 6 years

Application in PCA14/15, PCAØ and PCA2.

### Presentation



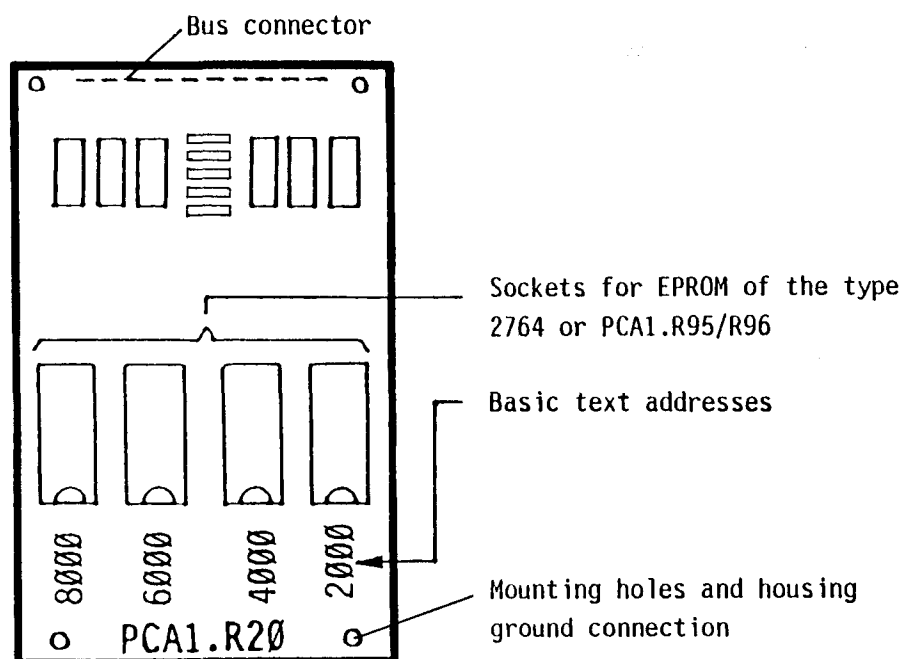
### B 2.1.9 Type PCA1.R2Ø Text memory extension module, 32 characters (for PCA14 as of version V6.Ø34)

The text memory card PCA1.R2Ø increases the storage capacity for texts five-fold. In addition, the text memory module offers the possibility of reserving the whole memory mounted in the CPU for user steps or as data memory and of storing all texts on the text module.

#### Technical data

Text capacity	4 x 8K characters = 32K text characters
Types of memory (sockets)	- for buffered RAM-memory PCA1.R95 or R96 - for EPROM type 2764 (order no. 4'5Ø2'4719'Ø)
Mounting of module	like I/O-module, however, only on socket Ø

#### Presentation



The module PCA1.R2Ø must always be mounted on socket Ø of the PCA14 (addresses Ø...7)!

### Memory structure

Memory socket	TEXT ADDRESSES not indexed	TEXT ADDRESSES indexed	
Right socket on the CPU	0 - 818	1000 - 1818 <sup>1)</sup>	as usual
Socket 2000 on R20	2000 - 2818	3000 - 3818	
Socket 4000 on R20	4000 - 4818	5000 - 5818	
Socket 6000 on R20	6000 - 6818	7000 - 7818	
Socket 8000 on R20	8000 - 8818 <sup>2)</sup>	9000 - 9818	

Compared to the normal text address assignment on the CPU (0...818), the addresses on the R20 module are increased by 2000 to 8000 (depending on the socket). The following footnotes should be read for indexed text output and limit addresses.

- 1) As is known, texts may be output in indexed form. For text subroutines (CPU socket) in the address range 0...818 only 3 figures are available for addressing.  
Details see manual "PCA Software level c", chapter "Text output".
- 2) Starting with text address 8192 the text number can no longer be entered directly in PAS 23, the multiple of 2 K must rather be entered in the code and the remainder in the operand.

<u>Example:</u> text no. 8400	Code	Operand
	PAS	23
	04	0208 ; (4 x 2048) + 208 = 8400

### Text input

A text input effected directly on the PCA1.R20 card is not provided for. There are two possibilities of entering texts:

1. Using PCA14. Texts are entered into a buffered RAM-memory module (R95 or R96), which is located on the right socket of the CPU. Therefore, the text addresses 0...818 are used. Upon termination of the input, the memory module is plugged into the corresponding address location on the R20 module.
2. Using the text assembler of the SAIA®PCA ASSEMBLER and the PCA2.P16 EPROM copying unit or the programming unit PCA2.P21.  
Proceed as described under 1.

### Text output (call text in the user program with PAS 23)

When calling the text, the basic addresses of the text (2000 to 8000) must be added in the 2nd line of the PAS 23 instruction in accordance with the selected socket. For indexed text calls those basic addresses exceed the basic addresses by 1000 (3000 to 9000), see description in chapter "Memory structure".

### Important notes:

- a) Text stored on the PCA1.R20 module are addressed using 4 digits. It must be noted for text subroutines that \$L must always be followed by 4 digits.
- b) A text subroutine which uses the addresses 2000...8818 cannot be called by a text using the addresses 0...818. However, a subroutine in the address range 0...818 can be called by a text in the address range 2000...8818, whereby the subroutine address must be entered using 4 digits (e.g. \$L 0412).



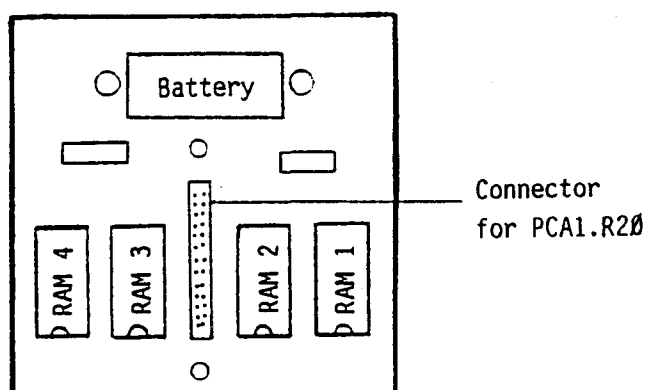
### B 2.1.10 Type PCA1.R25 Data memory extension module, 16K words

The PCA1.R25 module serves as an additional module for the text memory extension module PCA1.R20. It has a large buffered data memory of 16K words of 16 bits each.

#### Technical data

Data memory capacity	16K words of 16 bits each
Type of memory	RAM, battery-buffered with PAS 58 instructions, for writing and reading (16 bits)
Firmware version	PCA14 from version V6.036 onwards
Mounting of module	on module R20, on socket 0

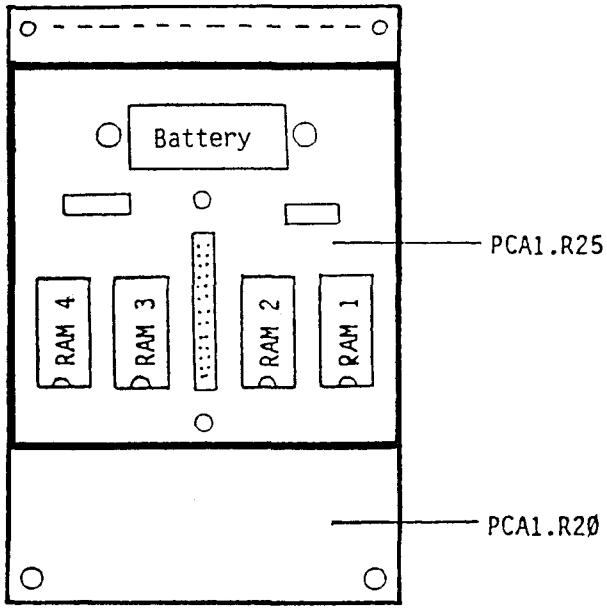
#### Presentation



#### Memory organization

	Word address (16 bits)
RAM 1	0 ... 4095
RAM 2	4096 ... 8191
RAM 3	8192 ... 12287
RAM 4	12288 ... 16383

Mounting on text memory extension module PCA1.R20



The data memory module PCA1.R25 is plugged onto the text memory extension module PCA1.R20 and fastened with 2 screws. Due to the module R20 + R25, the PCA14 is additionally provided with a text memory of 32K ASCII-characters and a data memory of 16K words or 32K bytes.

Buffer battery

When the PCA14 is switched off, the NiCd battery protects the RAM-memory against data loss for at least 2 months (battery completely charged).

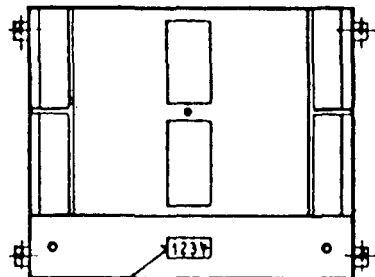
The pluggable battery lasts at least 5 years.  
Spare part no. 4'507'1360'0.

In order to prevent data loss on the R25 when replacing the battery, proceed as follows:

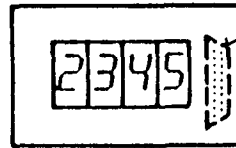
1. Switch off PCA14
2. Remove cover above the inputs/outputs
3. Switch on PCA14
4. Remove old battery
5. Install new battery
6. Check data on R25
7. Leave the PCA14 switched on for several hours (charging of battery!)

## B 2.2 Display modules

### B 2.2.1 PCA1.D11 Operand display module



Window in the  
cover of the  
operating panel



For PGU-connector  
on the operating panel

PCA1.D11 module,  
attachable to the  
operating panel

#### Description:

With the two instructions

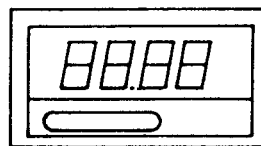
- DTC: Display Timer or Counter
- DOP: Display Operand

4-digit figures can be displayed in the RUN-mode. Thus, counter states (as well as step numbers), timers or, with the DOP-instruction, operands (e.g. as error numbers) can be displayed elegantly without using inputs or outputs.

Depending on the user program the following displays are possible:

- fixed display according to the user software
- various displays selectable by selector switch
- various displays periodically altering

## B 2.2.2 PCA2.D12 Display module



### General

The PCA2.D12 module is a remote display which can be controlled via SAIA°PLC outputs. It has a 4-digit display and is able to indicate a decimal point. The display can be built in anywhere at a greater distance to the PLC e.g. in the door of a control cabinet or an operating panel. Due to data transmission being effected via outputs, several displays can be controlled by one PLC.

In conjunction with the display interface PCA1/2.D13 the D12 can be connected even at a greater distance to the PGU-connector where the comfortable instructions DTC and DOP are available.

### Structure, function

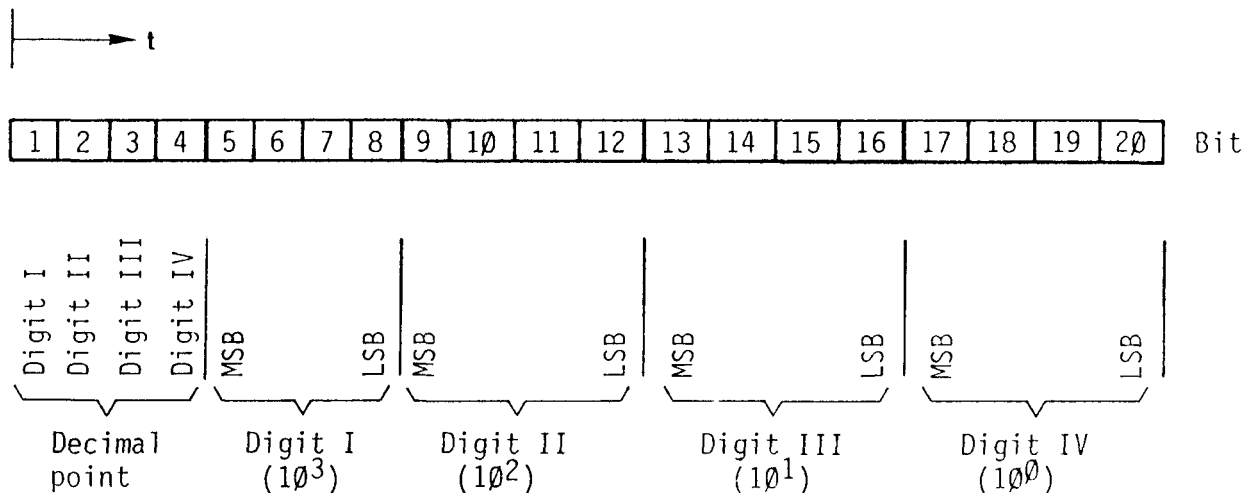
The module is in the same housing as the electronic totalizing counter of the CKG type. It consists of the following main components:

- power supply 24VDC
- 3 inputs for 24VDC
- decoder/driver
- 4-digit, 7-segment display with decimal point

The 3 outputs of the PLC resp. the 3 inputs of the display are designated "Enable", "Data" and "Clock". The Enable signal activates the display, i.e. Enable = "L" --> display is able to receive data, Enable = "H" --> display is inactive (it is not able to receive new data). Via the "DATA" line data in BCD-format is transmitted sequentially, i.e. bit by bit from the SAIA°PLC to the display. The display accepts each bit with the falling edge of the "Clock" signal.

For a complete indication (4 digits with or without decimal point) always 20 clock signals must be generated and 20 data bits must be transmitted (4 BCD-values + 4 bits for the decimal point).

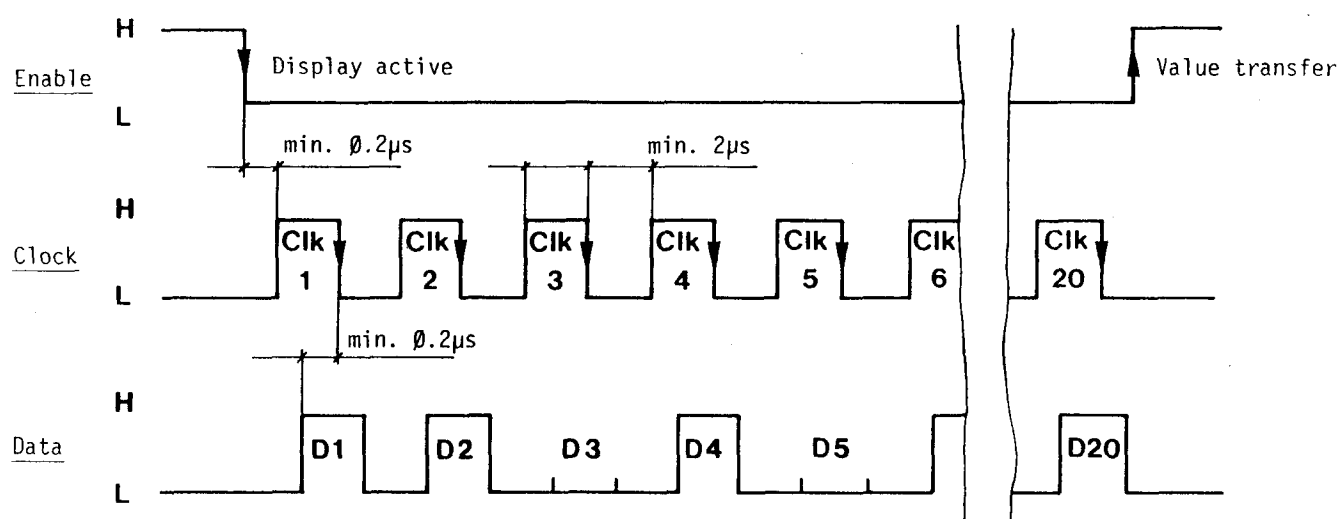
The following sequence of the 20 data bits must be adhered to:



The following 16 characters can be presented per segment:

Character	Code	Character	Code
Ø	0000	A	1010
1	0001		1011
2	0010		1100
3	0011		1101
4	0100	-	1110
5	0101	"blank"	1111
6	0110		
7	0111		
8	1000		
9	1001		

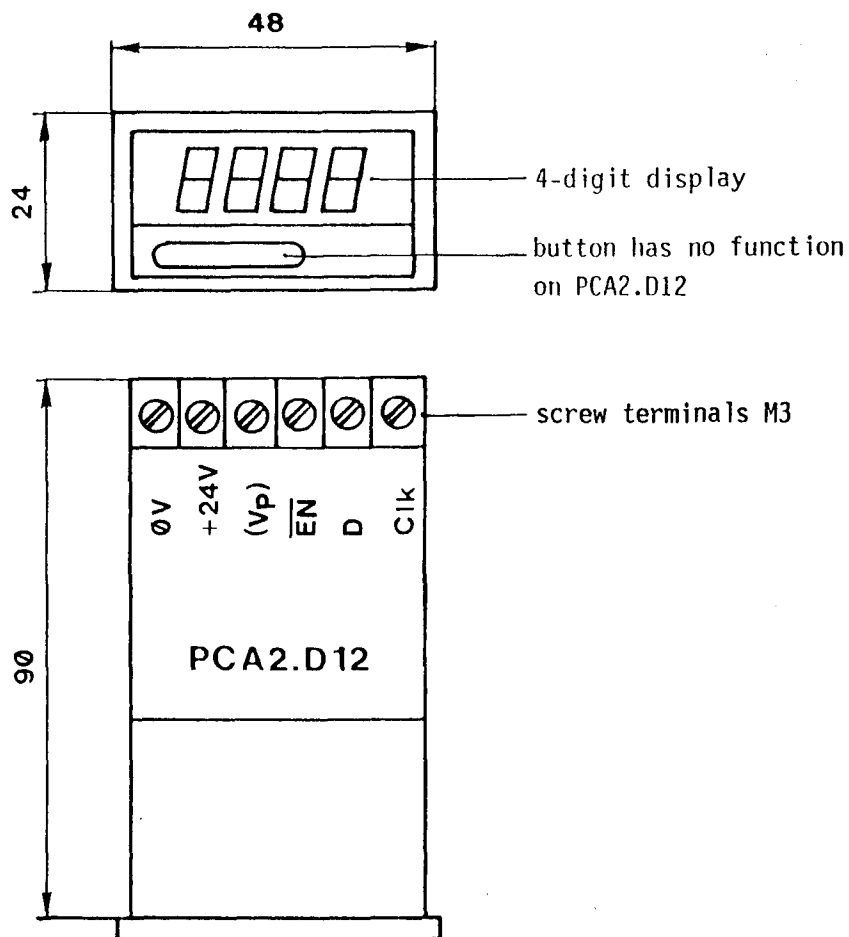
The connection between "Enable", "Clock" and "Data" is illustrated in the time-dependency diagram:



For the generation of the "Clock" as well as for the transmission of data the user must write a short program (examples will follow at the end). In this program, all functions shown in the above diagram, must be realized.

The minimum clock pulses and waiting times are short, so that the instruction set of the SAIA®PLC can easily be applied directly without waiting for certain periods to elapse.

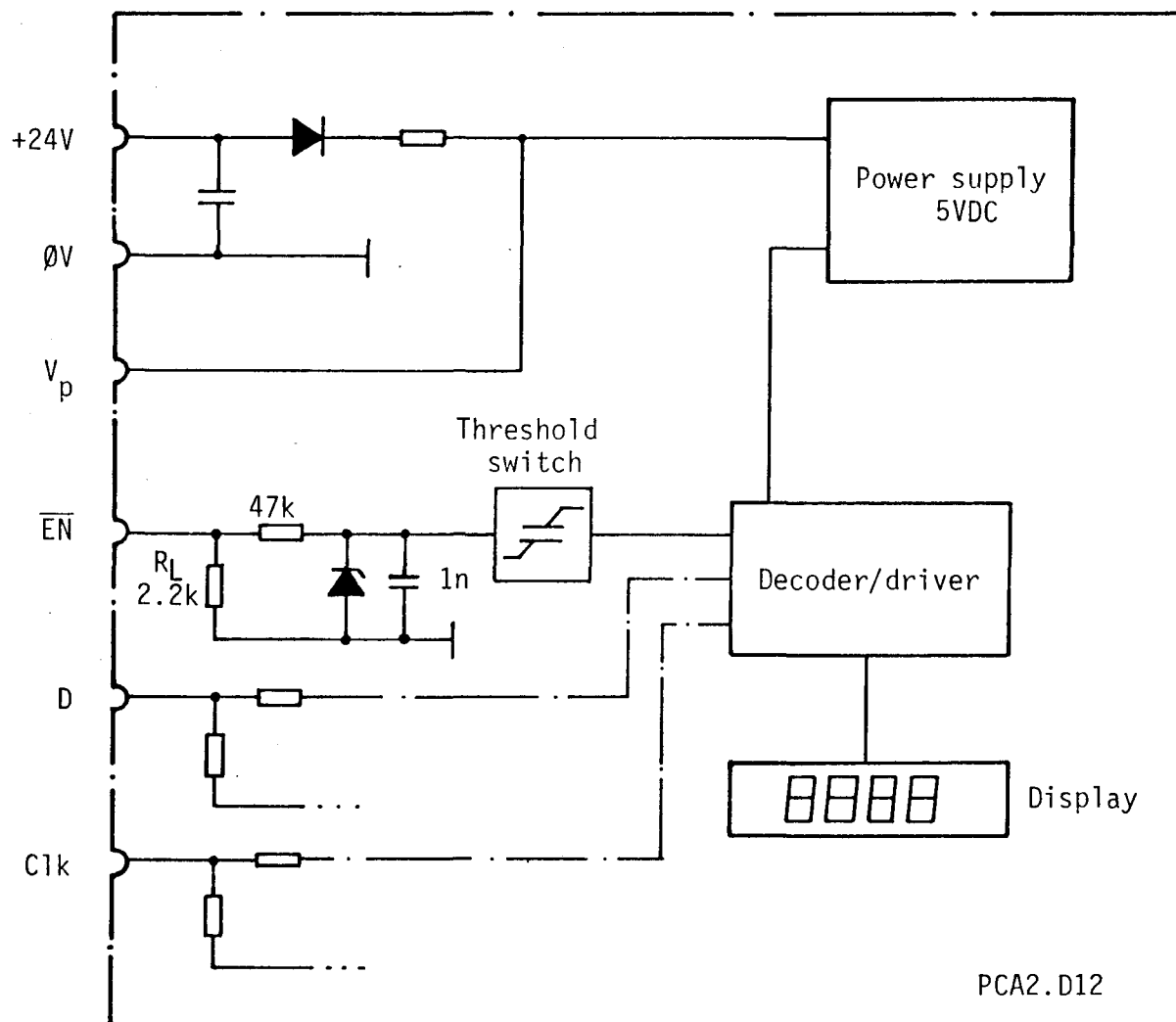
## Presentation and terminal arrangement



### Technical data:

- |  |  |
|--|--|
| - Supply voltage:                              | 24VDC $\pm$ 20%, two-way rectification is sufficient |
| - Input voltage for EN, D, CLK:                | 24VDC, smoothed                                      |
| - Input current for 24VDC:                     | 10mA   |
| - Definition of the input voltages:            | "H": 19V...32V<br>"L": 0V... 4V                      |
| - Input delay:                                 | < 1ms  |
| - Usable SAIA <sup>®</sup> PLC output modules: | PCA1.A10, B10, B80, B90<br>PCA2.A40                  |
| - Control                                      | serially via 3 PLC-outputs or via interface D13      |

# Input circuit and block circuit diagram



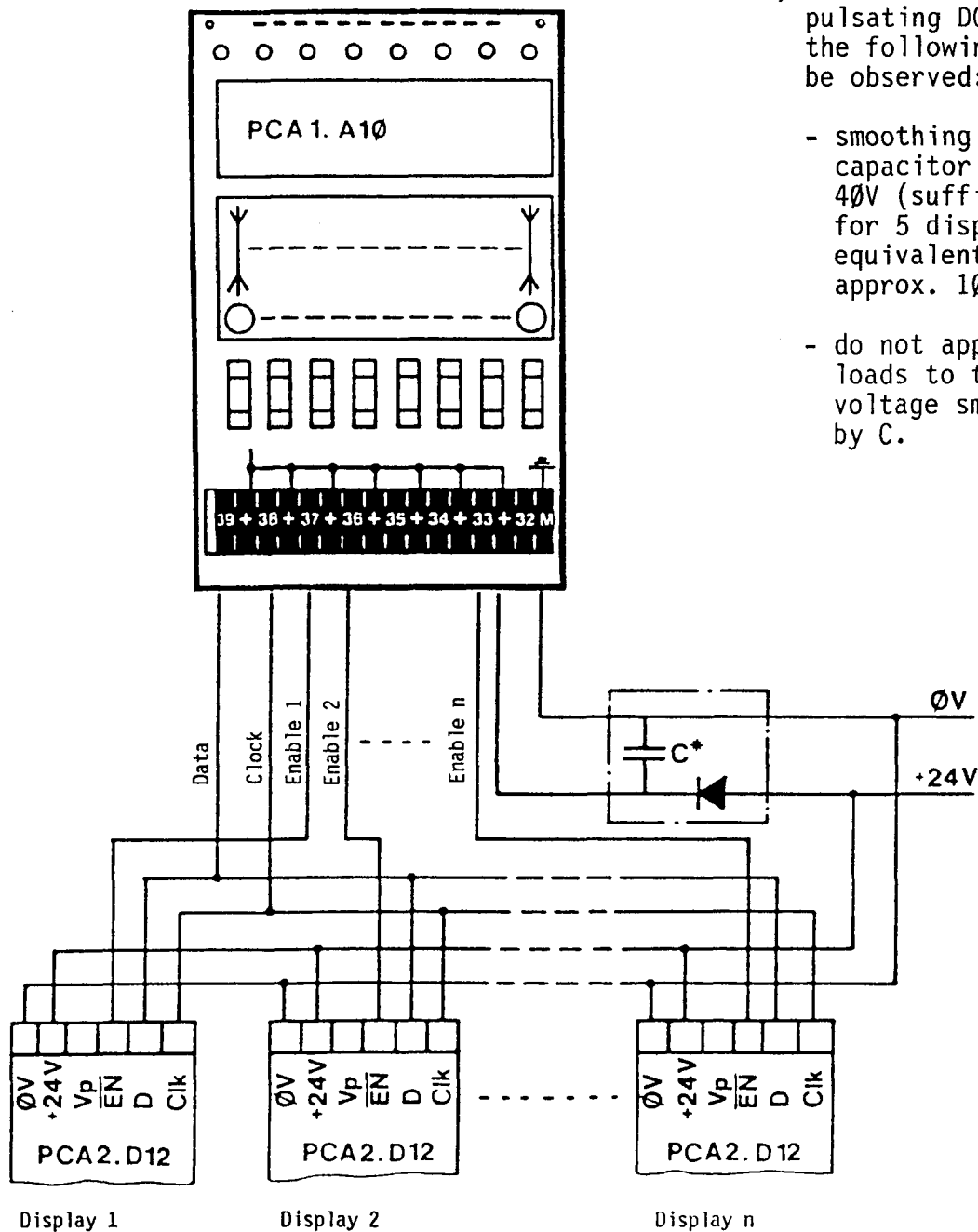
## Note:

$V_p$  supplies display interface D13.

### Connection of several displays to a PLC

Since the PCA2.D12 module is able to transmit an "Enable" signal, i.e. it can be switched to be active or inactive, the same "Clock" and "Data" signals can be used for several displays. These are transmitted to each display simultaneously. The "Enable" signal decides which display is controlled. This means that for each display one "Enable" signal is necessary (1 output per display). This also means, however, that for as many displays as desired only one data and one clock output must be provided.

Connection: (e.g. PCA1.A10 - PCA2.D12)

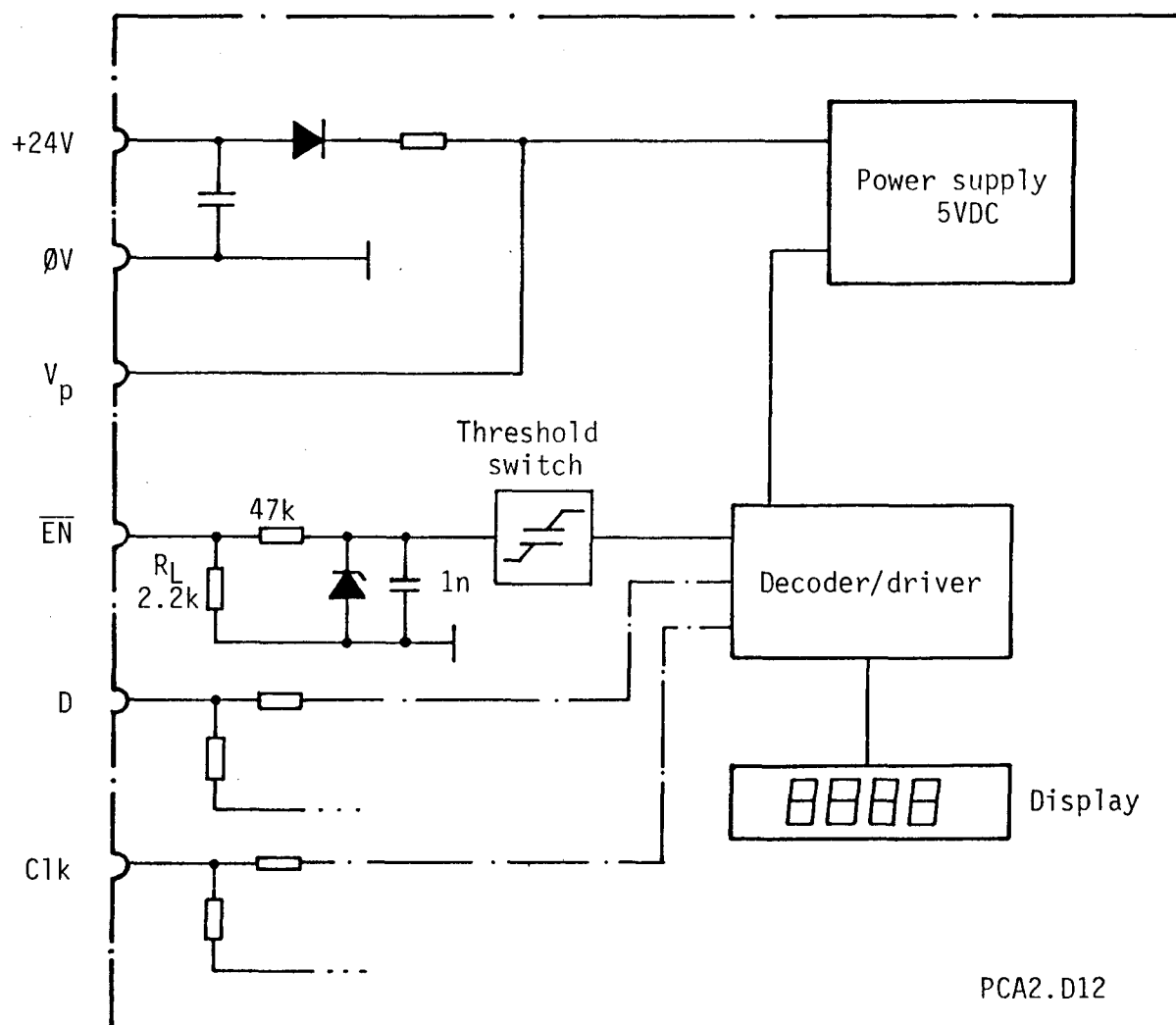


\*) In the case of a pulsating DC-voltage the following must be observed:

- smoothing by capacitor C100  $\mu$ F, 40V (sufficient for 5 displays is equivalent to I = approx. 100mA)
- do not apply other loads to the voltage smoothed by C.



# Input circuit and block circuit diagram



## Note:

V<sub>p</sub> supplies display interface D13.

## Examples

### Example 1

Six PCA2.D12 displays are to be connected to one SAIA<sup>®</sup>PLC. How many outputs are required?

### Solution 1

Per display one "Enable" signal	6 outputs
1 "Data" signal (simultaneously to all displays)	1 output
1 "Clock" signal (simultaneously to all displays)	1 output
<u>Total</u>	<u>8 outputs</u> =====

### Example 2

Every half second a counter is to be incremented up to the value 9999 and then reset to zero. Its content is to be indicated on the PCA2.D12 display module with a decimal point in the 2nd place.

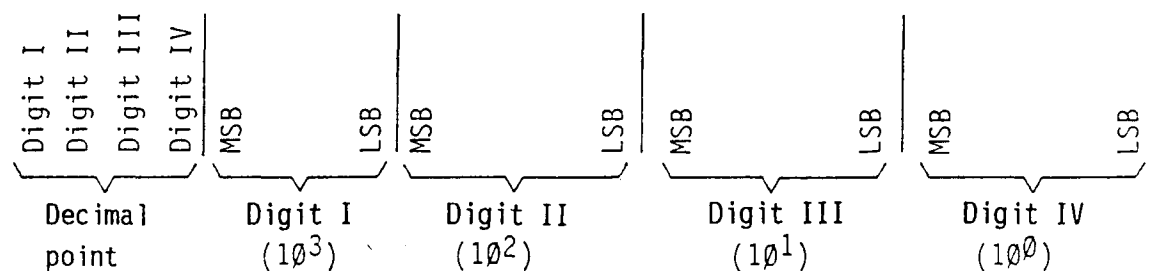
The following outputs must be assigned for "Enable", "Data" and "Clock":

EN : 02  
D : 03  
CLK: 04





Used counters: C280  
C281





→ t      Used flags 401-420

401	402	403	404	405	406	407	408	409	410	411	412	413	414	415	416	417	418	419	420	Bit
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----



## Solution 2

10	→	SCR	280	
11		SCR	0 0	; Initial value 0
12		SCR	281	
13		04 1807		; Maximum value 9999
14				
15	→	SCR	280	
16		20 420		; Counter contents on flags
17		SEO	402	; Decimal point on 2nd place 401...420
18				
19				
20		SEA	0	
21		REO	2	; Enable = "L" 
22		SEI	0	
23		SEO	4	; Clock 
24		STH	1401	IR: 401...420
25		OUT	3	; Data
26		SEA	0	
27		REO	4	; Clock 
28		INI	19	
29		JIO	23	
30		SEO	2	; Enable = "H" 
31				
32				
33		DTC	280	; Operand display
34		DEC	281	; -1
35		STL	281	; 0 ?
36		JIO	10	
37				
38				
39		INC	280	; (0,1,2,3...9999,0,1...)
40		STR	256	
41		00	5	
42		WIH	256	; Wait 0.5s
43		JMP	15	

SEA	0	
REO	2	; Enable = "L" 
SEI	0	
SEO	4	; Clock 
STH	1401	IR: 401...420
OUT	3	; Data
SEA	0	
REO	4	; Clock 
INI	19	
JIO	23	
SEO	2	; Enable = "H" 

Standard routine for controlling the display

→ t

401	402	403	404	405	406	407	408	409	410	411	412	413	414	415	416	417	418	419	420
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----

Bit

Digit I	Digit II	Digit III	Digit IV																
				MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB
Decimal point				Digit I (10 <sup>3</sup> )		Digit II (10 <sup>2</sup> )		Digit III (10 <sup>1</sup> )		Digit IV (10 <sup>0</sup> )									

### B 2.2.3 PCA1.D13 Display interface

#### Description

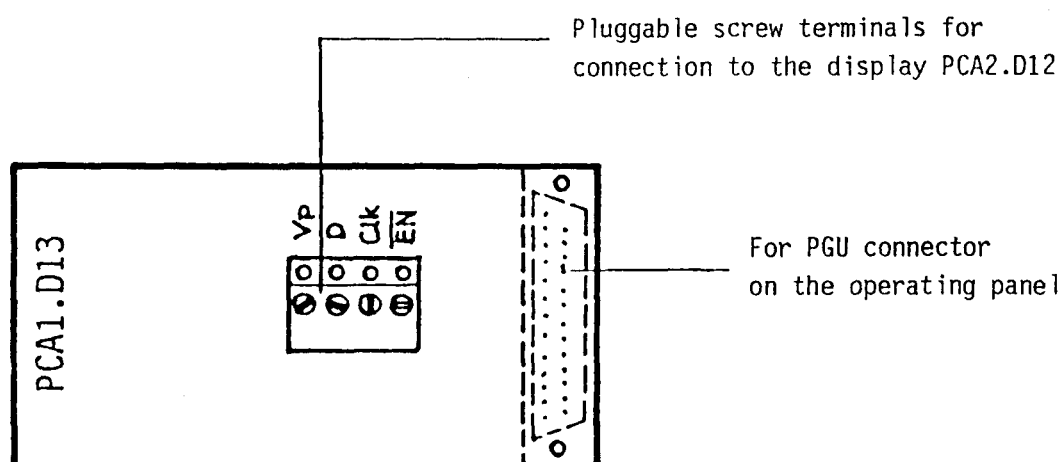
The display interface D13 combines the advantages of the display module PCA1.D11 (simple software handling via the instruction DTC and DOP for 4-digit decimal displays) and those of the display PCA2.D12, which need not be located anywhere near the SAIA®PLC.

The D13 is inserted in the PGU-plug of the SAIA®PLC and connected to the display PCA2.D12 by means of pluggable screw terminals.

#### Technical data

- Supply voltage  $V_p$ : 24VDC,  $\pm 20\%$ , full-wave rectified is sufficient (supplied by the display module PCA2.D12)
- 3 opto-isolated outputs for EN, D, CLK
- Connection of 2 displays PCA2.D12 is possible (same display)
- Control by means of the instructions DOP and DTC (see manual Software 1H)
- Concerning the cable layout and type of cable between D12 and D13 no special measures are required. The same general criteria as for the cabling of input and output modules apply (see chapter A 5).

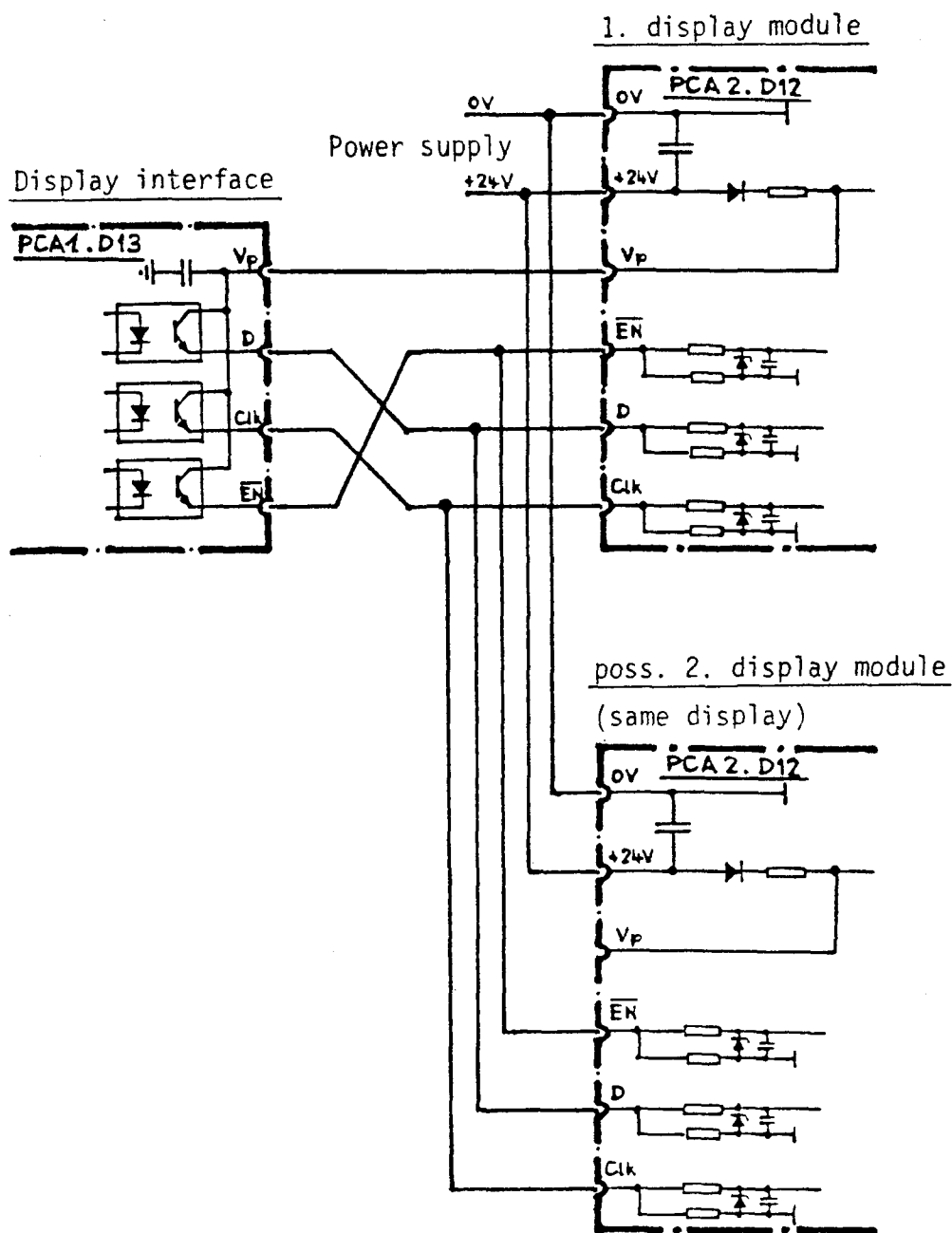
#### Presentation



The open module PCA1.D13 is plugged into the PGU-connector of the operating panel. The pluggable screw terminals for connecting the display module protrude through the window.

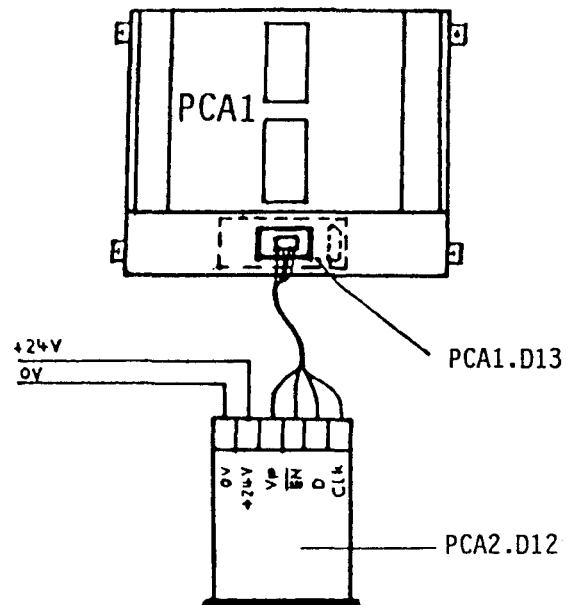
Various screws are supplied for the attachment and the mechanical protection of the module.

# Connection diagram

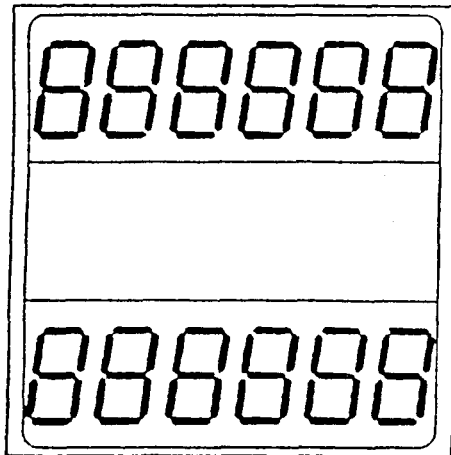


## Note:

- Both displays indicate the same data.
- Module D13 is supplied by module D12 at the back via the terminals Vp. This and the use of optocouplers ensure maximum interference protection of the PCA1.

Connection to display module PCA2.D12

### B 2.2.4 PCA2.D14 Display module



#### General

The PCA2.D14 module is a remote display module which is controlled via 3 outputs of the SAIA°PLC. The module has two 6-digit displays. Several PCA2.D14 can be connected in series in case of more than two displays.

#### Application, control

The module was developed in connection with the fast counter module PCA1.H10. In this application controlling is performed by the counter module alone. The user must only program the appropriate mode in the user program.

When the PCA2.D14 is used without the H10 module, the information to be displayed is most easily transmitted serially with a standard program routine from a flag field via 3 SAIA°PLC outputs.

#### Technical data

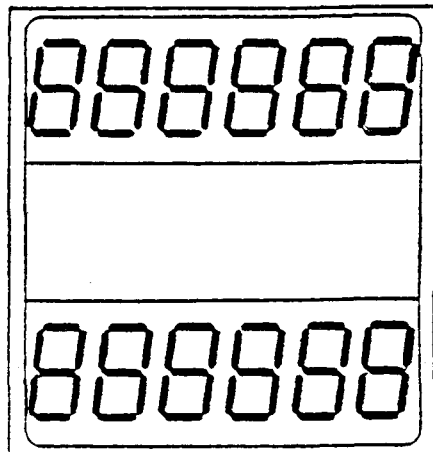
Display	2 times 6 digits, 7-segment LED
Digit height	10mm
Supply voltage	24VDC $\pm$ 20%, full-wave rectified is sufficient
Input voltage for EN, D, CLK	24VDC smoothed
Input current at 24VDC	10mA
Definition of the input level	"H" = +19...+32V "L" = 0...+ 4V
Input delay	< 1ms
Usable SAIA°PLC output modules	PCA1.A10, B10, B80, B90 PCA2.A40
Control	serially via 3 SAIA°PLC outputs irrespective of the number of D14

### Structure, function

The module is located in the same housing as the electronic totalizing counter CKG/AC.

Terminals: Screw terminals combined with connection strips (2.8 x Ø.8 mm) for flat pluggable bushes or soldering.

PLC-output	Clock	----->	CLK	PCA2.D14
PLC-output	Data-In	----->	D-IN	
PLC-output	Enable	----->	EN	
Carry	Data-Out	----->	D-OUT	
Voltage supply	+24V	----->	+24V	
Voltage supply	ØV	----->	ØV	



Upper display

Lower display

The data for a display of 2 x 6 digits are most easily presented in a complete flag field, e.g. M500...547 in BCD-notation. If these values are kept in counters, they must be transferred to the flag fields first.

	500						523	
M	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	upper	
	MSB	LSB				MSB	LSB	display
	100'000	10'000	1'000	100	10	1		

	524						547	
M	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	lower	
	MSB	LSB				MSB	LSB	display
	100'000	10'000	1'000	100	10	1		



### Software routine

Every time the following routine has been executed the current information in the flag field is indicated on the display until the display is updated by a new piece of information after a further run.

#### Softlevel 1 \*

```

(60 SEA 0)
61 REO 2  ENABLE
62 SEI 0
63 SEO 3  DATA
64 SCR 280 AUX. COUNTER
   00 4
66 SEO 4  CLOCK
67 REO 4  CLOCK
68 DEC 280 AUX. COUNTER
69 STH 280 AUX. COUNTER
70 JIO 66
71 SCR 280 AUX. COUNTER
   00 16
73 STH 1500 FLAGS
74 OUT 3  DATA
75 SEA 0
76 SEO 4  CLOCK
77 REO 4  CLOCK
78 INI 47
79 JIZ 84
80 DEC 280 AUX. COUNTER
81 STH 280 AUX. COUNTER
82 JIO 73
83 JMP 63
84 SEO 2  ENABLE
(85 RET 0)

```

When not used as a  
subroutine

#### Used address

Enable	A2
Data	A3
Clock	A4
Flag	M500...M547
Aux. counter	C280

for M500...547

for 1 D14 upper and lower display \*\*)

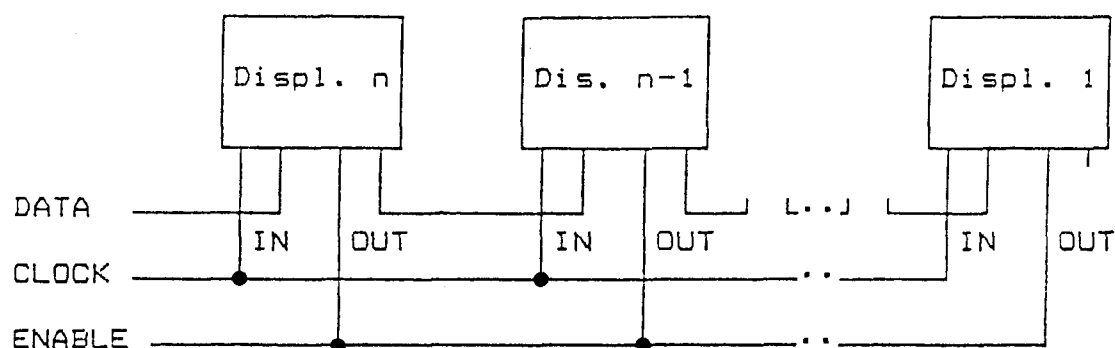
When used as a  
subroutine

500						523	
M	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	display
	MSB	LSB				MSB	LSB
	100'000	10'000	1'000	100	10	1	
524						547	
M	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	lower display
	MSB	LSB				MSB	LSB
	100'000	10'000	1'000	100	10	1	

\*) The display module D14 can thus be controlled from any SAIA°PLC (including PCA13 and PCA21).

\*\*) For connecting several D14 in series see following page.

The following diagram shows several PCA2.D14 connected in series.:  
Each D14 displays its own data.



The flag field containing the information to be displayed must be expanded correspondingly:

for 1 PCA2.D14 = 1 x 48 flags  
for 2 PCA2.D14 = 2 x 48 flags  
for 3 PCA2.D14 = 3 x 48 flags etc.

The routine in the user program remains the same, only the instruction "INI" must be changed accordingly:

for 1 PCA2.D14 = INI 47  
for 2 PCA2.D14 = INI 95  
for 3 PCA2.D14 = INI 143 etc.

In other words, INI  $(n \times 48) - 1$  with  $n$  = number of PCA2.D14.

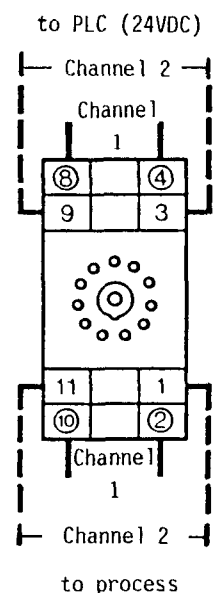
The following 16 characters per segment can be presented:

Character	Code	Character	Code
0	0000	A	1010
1	0001	I	1011
2	0010	l	1100
3	0011	U	1101
4	0100	-	1110
5	0101	"blank"	1111
6	0110		
7	0111		
8	1000		
9	1001		

For examples refer to the Software manual.

### B 2.3 KOM series external interface module

The purpose of the external interfaces is for adapting the I/O levels of the PLC from 24VDC to the process requirements. They are constructed in two-channel form and mounted in plug-in housings for an 11-way round socket. LEDs indicate the logic status ("H" = ON), facilitating the rapid checking of the signal lines as far as the terminals of the process. To render the wiring easy to view, the cables from the process or to the PLC are arranged on the opposite side of the plug holder.

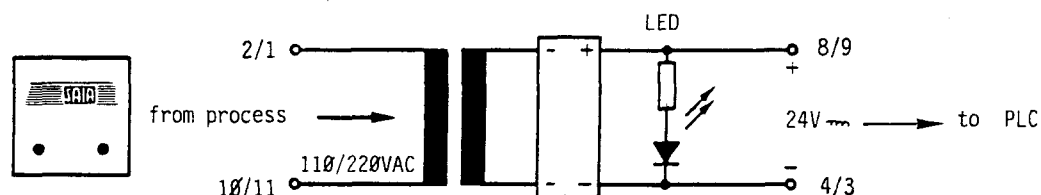


Plug-socket holder  
Order no. 4 408 4817 0

#### B 2.3.1 Type KOM 111B Dual input interface

The purpose of this input interface is for the isolation of the mains control lines from the 24V signal level of the PLC. The isolation is accomplished by means of inductive transmitters; this has the advantage of providing a safeguard against surge voltages.

Front Switching scheme (per channel)



#### Technical data

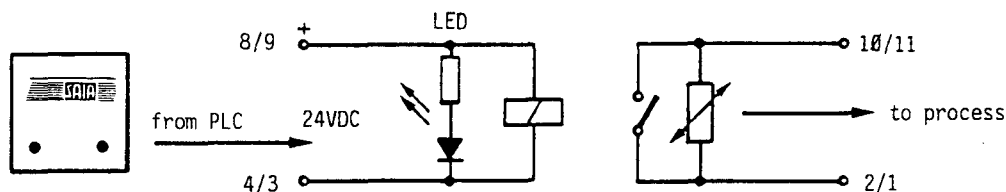
Input voltage	220V, 50...60 Hz $\pm$ 20% type KOM 111B D4 110V, 50...60 Hz $\pm$ 20% type KOM 111B C8
Input current	in each case 0.5A
Output voltage	24VDC pulsating
Output current	in each case max. 40mA
Reaction time	max. 10ms (acc. to phase length)
Surge voltage on process side	5kV, 1/50 $\mu$ s
Connection	11-way round socket
Order specification	KOM 111B D4 or C8 (see input voltage)

### B 2.3.2 Type KOM 121B Dual-relay-output interface

Electric isolation in this interface is achieved by relays, the contacts of which are able to directly switch mains voltages. The normally-open contact to the relay is used corresponding to the PLC output.

Front

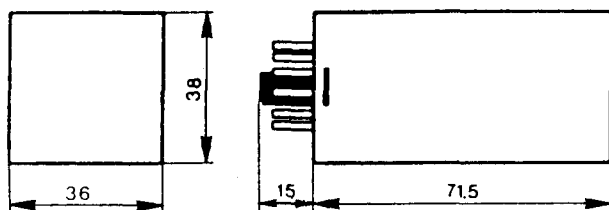
Switching scheme (per channel)



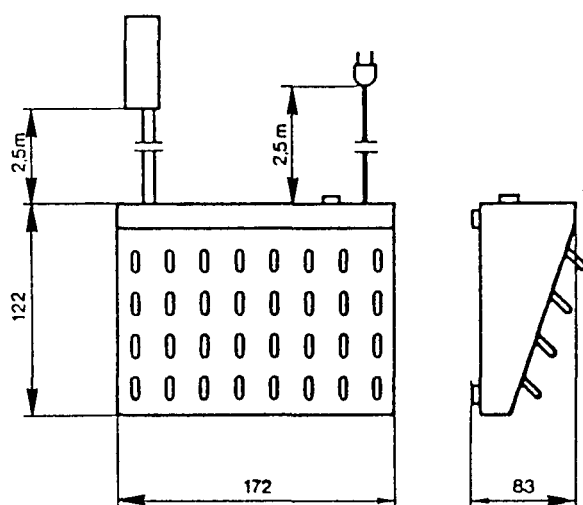
#### Technical data

Input voltage	24VDC $\pm$ 20%, smoothed or pulsating
Input current	in each case 20mA
Relay contact	in each case 1 normally-open contact with hard silver contacts
Switching power	in each case 6A, 250VAC AC1 1A, 250VAC AC11
Contact life (AC1)	3A, 220VAC 0.1 mio. switching cycles 1.5A, 220VAC 0.5 mio. switching cycles 0.3A, 220VAC 5 mio. switching cycles
Order specification	KOM 121B M4

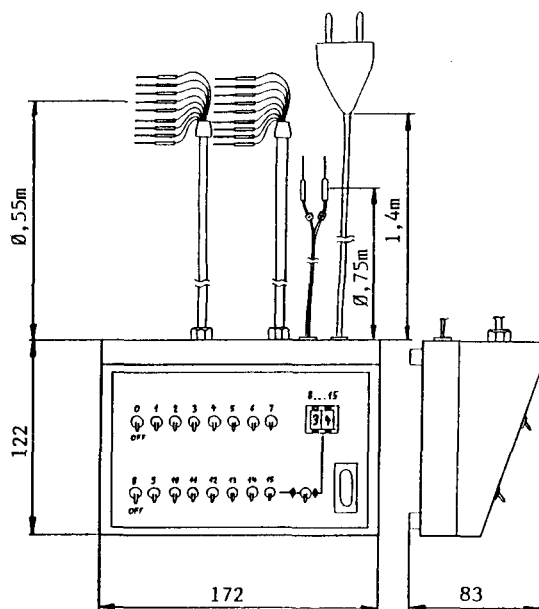
## B 2.4 Dimensions of additional units



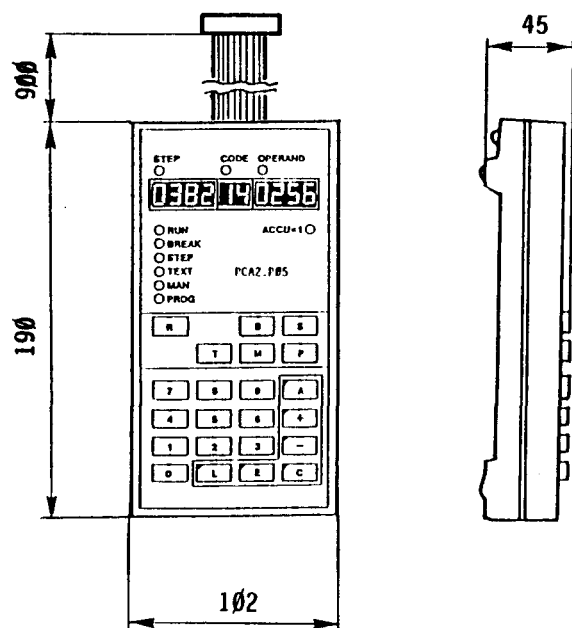
External interfaces  
KOM 111B and 121B



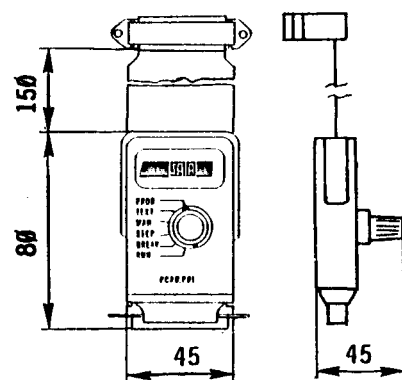
Input simulation unit  
PCA2.S10



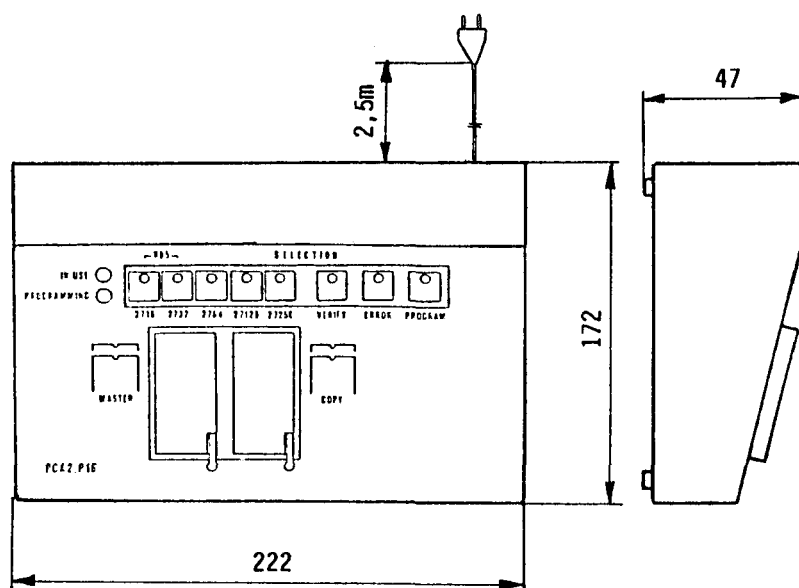
Input simulation unit  
PCA2.S05



Programming unit  
PCA2.P05



Programming interface  
PCA0.P01

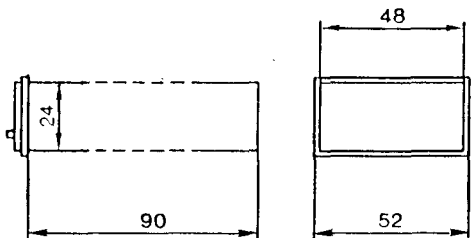
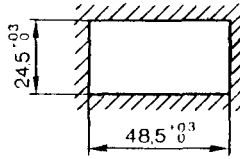
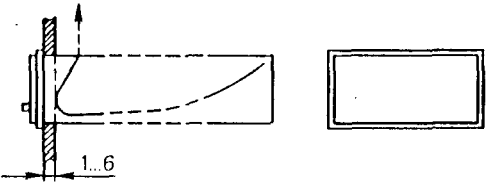
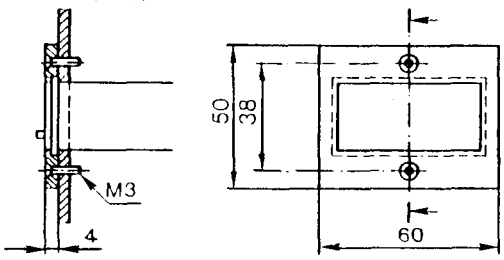
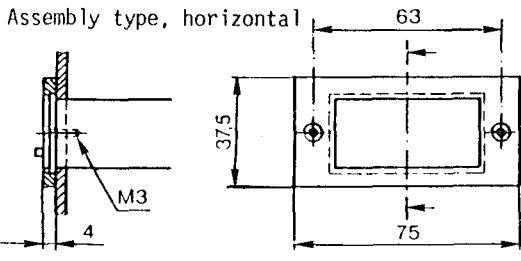


EPROM copying unit  
PCA2.P16

**B 2.5 Dimensions, assembly and installation of PCA2.D12**

The display can be installed in any position desired anywhere in a control cabinet door or an operating panel.

The display can be fastened in three ways:

Dimensions		
Opening for installation valid for both assembly types		
Fastening with clamping spring		Standard version
Fastening with frontal frame and 2 countersunk screws M3/90°. with vertical frontal frame	<p>Assembly type, vertical</p> 	Miscellaneous small parts  Order no. 4 1Ø8 3671 Ø
with horizontal frontal frame	<p>Assembly type, horizontal</p> 	Order no. 4 1Ø8 3672 Ø

## B 2.6 Dimensions, assembly and installation of PCA2.D14

The display module can be installed in any location desired.

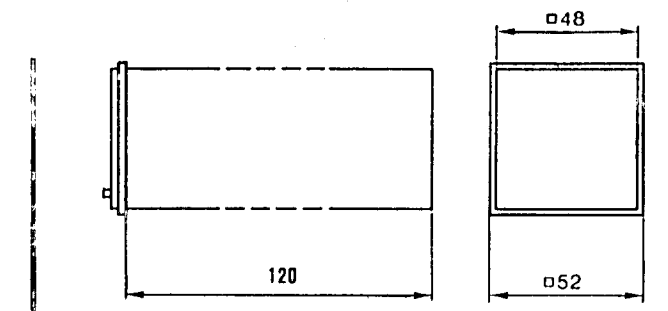
It can be fastened in two ways:

- with a clamping spring
- with a frontal frame and screws

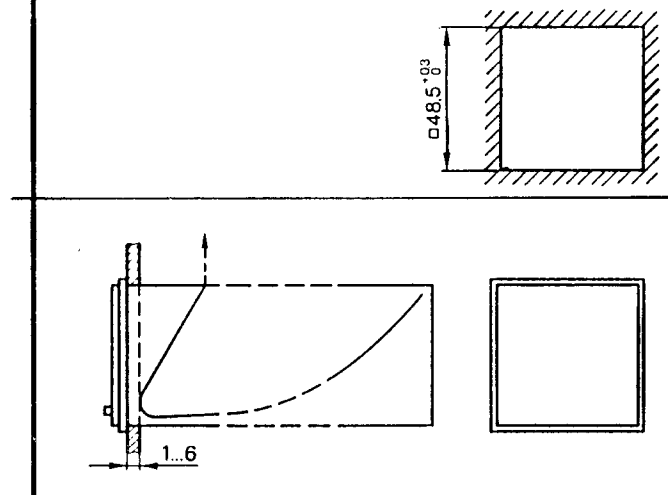
(The clamping spring and the frontal frame are supplied with every PCA2.D14).

### Dimensions

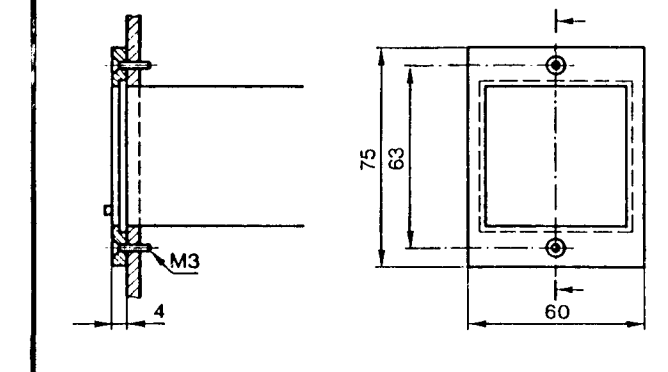
Opening for installation  
valid for both assembly  
types



Fastening with  
clamping spring

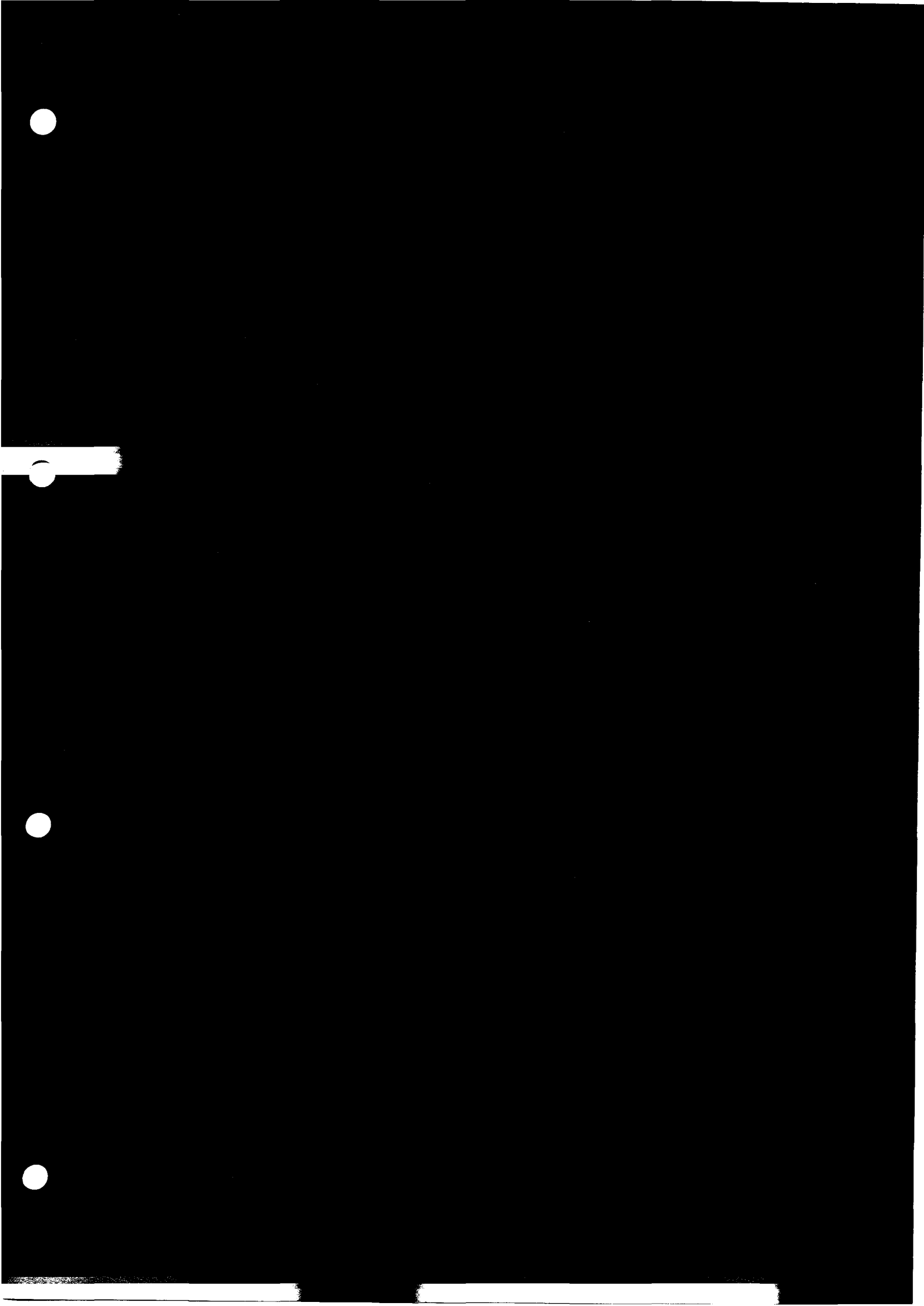


Fastening with  
frontal frame  
and 2 countersunk  
screws M3/90°





Notes:



## **OPERATING MODES**

### **C 1     Selection of operating modes for PCA14 and PCA15**

#### **C 1.1   Operating modes, level 1H for PCA15 and PCA14**

- RUN
- PROG
- MAN (Bit)
- BREAK
- STEP

#### **C 1.2   Summary of operating modes**

#### **C 1.3   Detailed description of operating modes**

### **C 2     Further operating modes (only PCA14)**

- MAN with date-time
- TEXT or text memory as data register

### Setting of operating modes

A PLC can operate in various operating modes for preparing, testing and editing a program.

PCA14: A sliding switch for selecting the operating modes is provided on the operating panel. This sliding switch is always active.

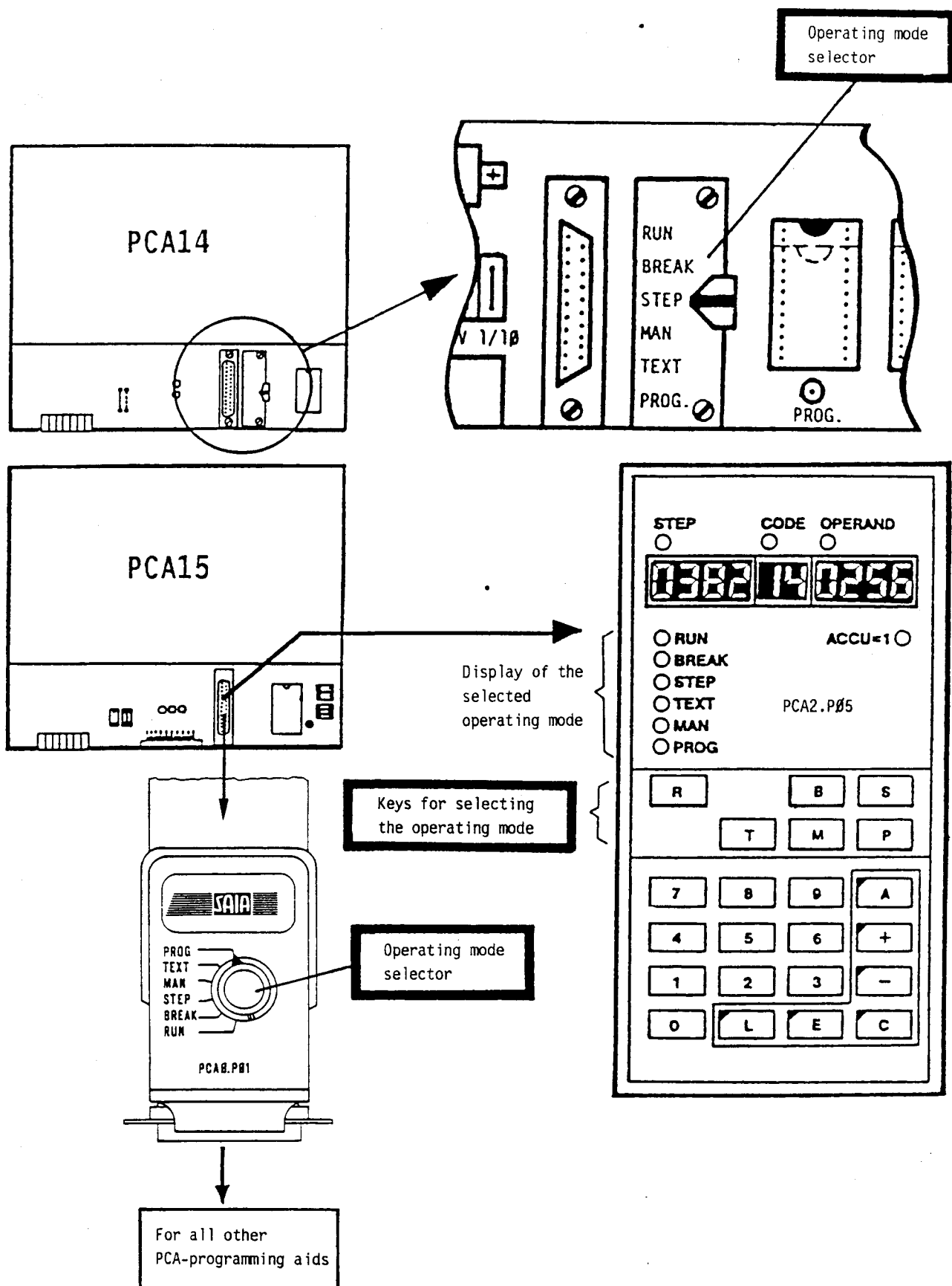
PCA15: The operating modes are preselected outside the PLC. The keys of the programming unit PCA2.P05 are used, or in case a different programming aid such as the handheld computer P18 or an IBM-PC is used, to select the operating modes with the programming interface PCA0.P01.

The selected operating mode remains active, when the connection between the programming units and the PCA15 is ended.

The following operating modes are automatically selected when the PCA15 is switched on.

- With programming unit P05 connected: STEP  
(LED "STEP" lights up, the green LED "RUN" does not light up!)
- Without programming unit: RUN  
(LED "RUN" lights up)
- With P01 connected: According to selector switch position

# C 1 Selection of operating modes



### C 1.1 Operating modes, level 1H for PCA15 and PCA14

- |                            |       |   |
|----------------------------|-------|---|
| <input type="checkbox"/> R | RUN   | Normal program processing (lamp RUN on PCA15 lights up)   |
| <input type="checkbox"/> P | PROG  | A user program can be loaded into a RAM memory (plugged onto the user plug-in socket of the PCA15). |
| <input type="checkbox"/> M | MAN   | Manual interrogation and setting of elements (inputs, outputs, flags, timers, counters)             |
| <input type="checkbox"/> S | STEP  | Jump to a preselected step address (program line) of the user program and step-by-step operation    |
| <input type="checkbox"/> B | BREAK | Program processing up to a set "breakpoint" and subsequent step-by-step operation                   |

## C 1.2 Summary of operating modes

### **R** RUN Normal program execution

The PCA1 is automatically in the RUN-mode when switching on if no programming unit is connected.

### **P** PROG Programming

A program can be stored in a RAM-memory (on the user socket of the PCA1) or overwritten (corrected).

<b>A</b> x x x x	<b>E</b> x x	Operand x x x x	
	<b>E</b> x x	x x x x	or <b>C</b> to delete a wrongly entered line
	<b>+</b>	Terminates the input	
Test program	<b>+</b> <b>+</b> or <b>-</b> <b>-</b>		

### **M** MAN \*\* Manual testing or setting of elements

(Elements = inputs, outputs, flags, counters, timers)

Testing: **A** x x x → display of the logic state in the operand (0/1)  
 Element address

Setting: **A** x x x **E** 1 ← or **0**  
 Element address

### **S** STEP **+** → Display showing where the program is.

Jump to the preselected step address of the user program

**A** 139 **+** → Program jumps to step 139, then

**+****+** ... step-by-step execution of the program with the result of the logic operation being checkable \* ACC = 1\*. Switching to RUN is always possible.

In case of parallel programs, only the activated parallel program is executed in the STEP-mode.

### **B** BREAK Interruption of the program run and subsequent step-by-step-operation

**+** → Display showing where the program is

**+****+** .... step-by-step execution of the program with the result of the logic operation being checkable \* ACC = 1\*. Switching to RUN is always possible.

In case of parallel programs, all programs are executed simultaneously (as in the RUN-mode).

Setting of a breakpoint

**A** 820 **+** → Program runs up to step 820, then

**+****+** .... step-by-step operation skipping the "critical" point.

\*) ACC = accumulator is used to indicate the result of the logic combination. If ACC = 1 (conditions of the logic combination fulfilled = 1), the following switching instructions are executed.

\*\*) If the address of a timer or counter is preceded by a 3 (e.g. 3260 for counter 260), the value of this register can be read or entered manually with **E** value **+**.

### C 1.3 Detailed description of the operating modes

**R** RUN      Normal program processing  
 The PCA15 is automatically in the RUN-mode when switching on if no programming unit is connected. For PCA14, the sliding switch must be in position RUN.

**P** PROG      Programming  
 A program can be stored in a RAM memory (on the user plug-in socket of the PCA1) or overwritten (corrected).

<b>A</b>	STEP xxxx	<b>E</b>	CODE xx	OPERAND xxxx
----------	--------------	----------	------------	-----------------

<b>E</b>	xx	xxxx
----------	----	------

**C** Deletes a wrongly entered line

**+** Terminates the input

**+** **+** or **-** **-** to display the program

**M** MAN      Manual testing or setting of elements  
 (Elements = inputs, outputs, flags, counters, timers)

		STEP <sup>1)</sup>	OPERAND
Testing:	<b>A</b>	xxx	0/1 → display of the logic state
Setting:	<b>A</b>	xxx	<b>E</b> → <b>1</b> or <b>0</b>

#### 1) STEP = Element address

If the address of a timer or counter is preceded by a 3 (e.g. 3260 for counter 260), the value of this register can be read or entered manually with:

**A** 3xxx    **E** value    **+**, **-**, **A**, **E**

For an example see following page.



Continued from footnote 1)

Example: Input of values 23419 or 127 into counters 290 or 291.

Input:	Display:	STEP	CODE	OPERAND
[A] 3290		3290	0Y	YYYY
				Units
				Ten-thousands
				Always 0

Input:	Display:	STEP	CODE	OPERAND
[A] 3290		3290	0Y	YYYY
[E] 23419		3290	02	3419
[E] 127		3291	01	0027

Correction before storing

[C]		3291	00	0000
[0] 127*		3291	00*	0127
[+]				

\* Values <10'000 have to be preceded by a leading 0.

**S** STEP     ☐+  $\longrightarrow$  Display showing where the program is.

Jump to the preselected step address of the user program

**A** 139   ☐+  $\longrightarrow$  Program jumps to step 139

☐+   ☐+   ... step-by-step processing of the program with the linkage result being checkable:  $\star \text{ ACCU} = 1$  <sup>2)</sup>

Switching to RUN is always possible.

In case of parallel program, only the activated parallel program is processed in the STEP mode.

**B** BREAK     Interruption of the program run and subsequent step-by-step operation

☐+  $\longrightarrow$  Display showing where the program is.

☐+   ☐+   ... step-by-step execution of the program with the linkage result being checkable:  $\star \text{ ACCU} = 1$  <sup>2)</sup>

Switching to RUN is always possible.

In case of parallel programs, all programs are processed simultaneously (as in the RUN-mode).

Setting of a "breakpoint"

**A** 820   ☐+  $\longrightarrow$  Program runs up to step 820 in slow RUN operation

☐+   ☐+   ... step-by-step operation over the "critical" point

---

2) ACCU (= accumulator) is used to indicate the status of the logic combination.

When LED lights up, the  $\text{ACCU} = 1$  (conditions of the logic combination fulfilled, linkage result = 1), and the following switching instructions are executed.

## C 2 Further operating modes (only PCA14)

### M "MAN"

#### Manual access to the software date-time

In case you use the date-time module E40 refer to chapter B 1, where reading and writing to the hardware date-time will be explained (black box routines, Software manual).

All programming units allow direct access to the software date-time (reading and writing).

Contrary to the buffered hardware date-time (PCA1.E40 module), the software date-time works only as long as voltage is applied to the PLC. Therefore, all values have to be introduced each time the PCA14 is started up. The date-time has a max. deviation factor of 3s/day.

The following table shows the signification and the numerical range for the addresses 4000...4007.

Address	Meaning	Numerical range
4000	Week of the year	1...53
4001	Day of the week	1...7
4002	Year (1989=89)	0...99
4003	Month	1...12
4004	Day of the month (Feb = 28)*	1...31
4005	Hours	1...23
4006	Minutes	1...59
4007	Seconds	0...59

\*) Contrary to the hardware date-time R27, the software date-time does not take the leap years into account (February = 28 days).

You may enter a maximum of 2 digits which appear in the operand (see examples on the following page).

- Examples: Input for Thursday, June 2nd, 89, 10h 12min 45s

Input:            Display:    STEP    CODE    OPERAND    .

A	4000	4000	00	00YY
E	22*	4000	00	0022
E	4*	4001	00	0004
E	89	4002	00	0089
E	6*	4003	00	0006
E	2*	4004	00	0002
E	10	4005	00	0010
E	12	4006	00	0012
E	45	4007	00	0045
+				

After entering the seconds (4007), key  is depressed, provided that the input corresponds to the actual time. Do not press key  again, since otherwise the input of the calendar week is erased.

- Display:

Input:            Display:

A	4000	4000	00	0022	22. week of the year
+		4001	00	0004	Thursday
+		4002	00	0089	1989
+		4003	00	0006	June
+		4004	00	0002	2
+		4005	00	0010	10h
+		4006	00	0012	12min
+		4007	00	0045	45s
					46s
					47s
					..
					..

\* Calendar week and day of the week must correspond to month and date!

## T "TEXT" or text memory as data register

### Input and reading of texts in the text memory

Input of texts is effected on RAM 6116, 6264 or 8464 or on the buffered RAM modules PCA1.R92/95/96 which are plugged onto the right-hand text socket of the basic module.

The following 2 possibilities are available:

- a) Using one of the PCA programming units, connected via the PGU connector.
- b) With a peripheral unit with current loop interface, connected to the serial data interface (7 terminals on the right).

For detailed description refer to manual Software level 2.

### Manual access to the text memory as data register (PAS 54) (as of system program version V6.004)

As mentioned in connection with the instruction PAS 54, the text memory can also be used as data register. In order to understand the monitor function of the system program, the formats which are used for organizing the various registers must be brought to mind:

Counter register : binary 16 bits  
Text memory : binary 8 bits or 16 bits  
(as data register) or BCD 8 bits

For manual access to the text memory as data register the operating mode selector switch must be set to "TEXT".

#### • Display of the text memory contents

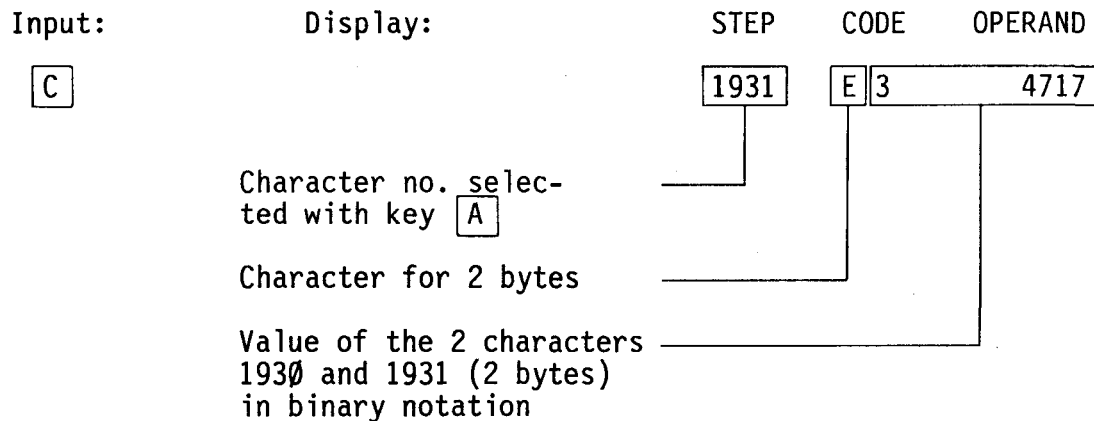
- a) Immediate display of a character value of 8 bits (1 byte) in binary notation

Upon actuation of key A, and subsequent input of the character number to be displayed (0...8191), the stored value (0...255) is displayed in the operand field in binary notation.

Input:	Display:	STEP	CODE	OPERAND
<span style="border: 1px solid black; padding: 0 2px;">A</span> 1931		<span style="border: 1px solid black; padding: 0 2px;">1931</span>	<span style="border: 1px solid black; padding: 0 2px;">00</span>	<span style="border: 1px solid black; padding: 0 2px;">0</span> <span style="border: 1px solid black; padding: 0 2px;">135</span>
	Character no.			
	Always 00 0			
	Value of 8 bits (1 byte) in binary notation			
<span style="border: 1px solid black; padding: 0 2px;">-</span>		1930	00	0157

b) Display of the contents of 2 character no. (2 bytes = 16 bits) in binary notation

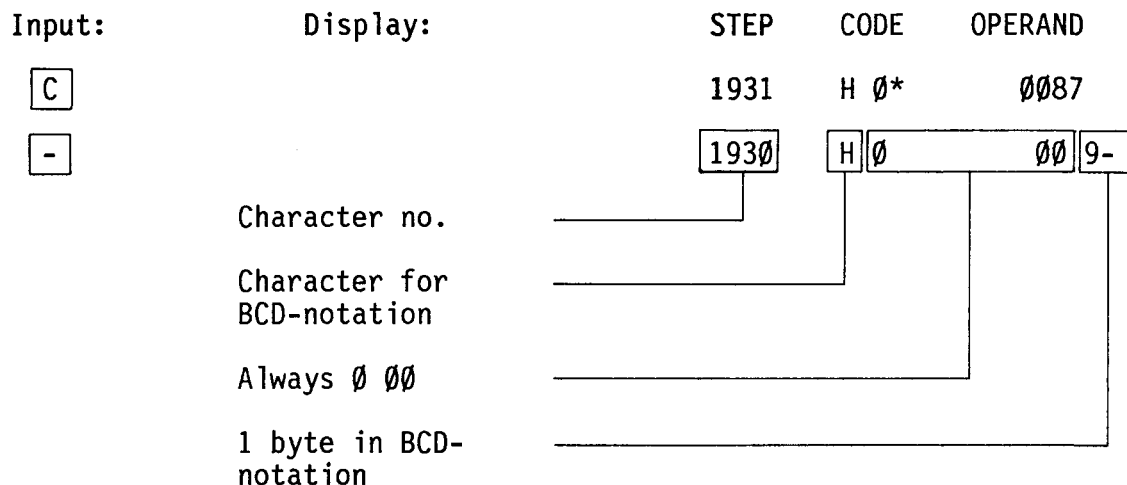
Actuating the key **C** once has the result that in addition to the selected character number the value of the preceding character can also be combined to form a 16-bit value (2 bytes) in binary notation. Consequently values in the range 0...65'535 can be displayed in the CODE and OPERAND field.



In this way, the contents of transferred counters can be displayed with their total capacity of 16 bits.

c) Display of 1 character no. (1 byte = 8 bits) in BCD-notation

By actuating key **C** (convert) a second time, the bit pattern is displayed in BCD-notation.



\*) Character in the code applies to P05. For P10 refer to the table on the following page.

Real BCD-bit patterns are displayed as decimals. If other characters are present as e.g. at character no. 1930, these are no BCD-bit patterns. In order to be able to interpret their values nevertheless, the following 7-segment characters are defined in the OPERAND:

Binary value	7-segment character	
	P10	P05
10		
11		
12		
13		
14		
15	blank	blank

• Manual data inputs into the text memory  
(limited RAM-memory in this area)

Key **A** : subsequent input of the character no., at which the value is to be stored

Key **E** : clears the old value and permits new input

Key **C** : before key **E** means "convert"  
after key **E** means "clear"

Key **+**, **-**, **A**, **E** : cause storage of the value introduced

Corresponding to the reading of data, 3 cases are distinguished for the manual input of data:

a) Input of a binary value of 1 byte (e.g. 48) at a character no.  
(e.g. 7436)

Input:	Display:	STEP	CODE	OPERAND
<b>A</b> 7436		7436	00	0XXX
<b>E</b> 48		7436	00	0048
<b>+</b>		7437	00	0YYY

b) Input of a binary value of 2 bytes (e.g. 1487) at character no. 7456 and 7457

Input:	Display:	STEP	CODE	OPERAND
[A] 7457 1)		7457	00	0XXX
[C]	2)	7457	EY*	YYYY
[E] 1487 3)		7457	E1*	0487
[C] 01487		7457	E0*	1487
[+]		7459 4)	EZ*	ZZZZ

1) Always the higher address of a pair of 2 bytes is entered.

2) [C] before [E] results in the conversion to 2 bytes.

3) If values < 10'000 are entered, a 0 must be typed first.  
Correction with [C].

4) The character no. is automatically increased by 2.

c) Input of a BCD-value (e.g. 30) at character no. 7660 (in BCD-notation, only values from 0..99 = 1 byte can be entered)

Input:	Display:	STEP	CODE	OPERAND
[A] 7660		7660	00	0XXX
[C]		7660	EY*	YYYY
[C]		7660	H0*	00ZZ
[E] 30		7660	H0*	0030
[+]		7661	H0*	00AB

\*) Characters apply to PCA2.P05.



List of modules

Type	Chapter	Page
KOM 111B	B 2.3.1	102B
KOM 121B	B 2.3.2	103B
PCA-ASSEMBLER	B 2.1.6	76B
PCAØ.PØ1	B 2.1.2	73B
PCA14	A 3	13A
PCA15	A 2	3A
PCA1.A1Ø	B 1.1.5	10B
PCA1.A21	B 1.1.6	12B
PCA1.A3Ø	B 1.1.7	14B
PCA1.A5Ø	B 1.1.8	16B
PCA1.B1Ø	B 1.1.9	18B
PCA1.B8Ø	B 1.1.10	21B
PCA1.B9Ø	B 1.1.11	25B
PCA1.C45	A 4	29A
PCA1.D11	B 2.2.1	87B
PCA1.D13	B 2.2.3	95B
PCA1.E1Ø	B 1.1.1	3B
PCA1.E11	B 1.1.2	5B
PCA1.E2Ø	B 1.1.3	6B
PCA1.E4Ø	B 1.1.12	29B
PCA1.E5Ø	B 1.1.4	8B
PCA1.F11	B 1.1.17	57B
PCA1.F12	B 1.1.17	57B
PCA1.F21	B 1.1.18	59B
PCA1.F22	B 1.1.18	59B
PCA1.H1..	B 1.1.19	67B
PCA1.K8Ø	B 2.1.4	74B
PCA1.K9Ø	A 4.1	29A
PCA1.R92	A 2.3.1/A 3.3.1	7A/17A
PCA1.R95/96	B 2.1.8	81B
PCA1.R2Ø	B 2.1.9	82B
PCA1.R25	B 2.1.10	85B
PCA1.W1..	B 1.1.13	40B
PCA1.W2..	B 1.1.14	42B
PCA1.W3..	B 1.1.15	46B
PCA1.W4Ø	B 1.1.16	54B
PCA2.D12	B 2.2.2	88B
PCA2.D14	B 2.2.4	98B
PCA2.PØ5	B 2.1.1	72B
PCA2.P16	B 2.1.7	78B
PCA2.P18	B 2.1.5	75B
PCA2.SØ5	B 2.1.4	74B
PCA2.S1Ø	B 2.1.3	73B